

# TinyOS Applications



**Advanced Computer Networks**

# TinyOS Applications Outline

- AntiTheft Example {done in gradual pieces}
  - LEDs, timer, booting
- Sensing Example
  - Light Sensor
  - Wiring to AntiTheft
- Single Hop Networks
  - Active Messages interface
  - Sending packets
  - Receiving packets

# AntiTheft Example [List 6.1]

```
module AntiTheftC {  
  uses {  
    interface Boot;  
    interface Timer <Tmilli> as WarningTimer;  
    interface Leds;  
  }  
}  
  
implementation {  
  enum { WARN_INTERVAL = 4096, WARN_DURATION = 64 };  
}
```

← can only declare integer constants


# AntiTheft Example [List 6.1]

```
event void WarningTimer.fired ( ) {  
    if (call Leds.get ( ) & LEDS_LED0)  
    { /* Red LED is on. Turn it off, will switch on  
        again in 4096 - 64 ms. */  
        call Leds.led0Off ( );  
        call WarningTimer.startOneShot (WARN_INTERVAL -  
                                          WARN_DURATION);  
    }  
    else  
    { // Red LED is off. Turn it on for 64 ms.  
        call Leds.led0On ( );  
        call WarningTimer.startOneShot (WARN_DURATION);  
    }  
}
```



# AntiTheft Example [List 6.1]

```
event void Boot.booted ( ) {  
    /* We just booted. Perform first  
                                   LED transition */  
    signal WarningTimer.fired ( );  
}  
}
```



software signal

```
interface Leds {
```

[List 6.2]

...

```
    async command void led0On ( );  
    async command void led0Off ( );  
    async command uint8_t get ( );
```

```
}
```

# AntiTheft configuration [List 6.6]

```
configuration AntiTheftAppC { }  
implementation {  
    components AntiTheftC, MainC, LedsC;  
    components new TimerMilliC ( ) as WTimer;  
  
    AntiTheftC.Boot -> MainC;  
    AntiTheftC.Leds -> LedsC;  
    AntiTheftC.WarningTimer -> WTimer;  
}
```

# Sensing Example

- TinyOS provides **two standard interfaces** for reading sensor samples:
  - **Read** :: acquire a single sample.
  - **ReadStream** :: sample at a fixed rate.

```
interface Read <val_t> {  
  command error_t read ( );  
  event void readDone (error_t, val_t val );  
}
```

# Sensing Example [List 6.8]

Anti-theft Example: detecting dark conditions

```
module DarkC {  
    uses {  
        interface Boot;  
        interface Leds;  
        interface Timer<TMilli> as TheftTimer;  
        interface Read<uint16_t> as Light;  
    }  
}
```

# Sensing Example [List 6.8]

implementation {

enum { DARK\_INTERVAL = 256, DARK\_THRESHOLD = 200};

samples four times per second



event void Boot.booted ( ) {

call TheftTimer.startPeriodic (DARK\_INTERVAL);

}

event void TheftTimer.fired ( ) {

call Light.read ( ); //Initiate split-phase light sampling

}

# Sensing Example [List 6.8]

```
/* Light sample completed. Check if it is a theft. */  
  
event void Light.readDone (error_t ok, uint16_t val)  
{  
  
    if (ok == SUCCESS && val < DARK_THRESHOLD)  
        call Leds.led2On ( ); /* Theft Alert! Alert! */  
    else  
        call Leds.led2Off( ); /* Don't leave LED on */  
}  
}
```

# Sensor Components

- Sensors are represented in TinyOS by generic components, e.g., **PhotoC** for the light sensor on the mts310 board.
- A single component usually represents a single sensor:

```
generic configuration PhotoC ( ) {  
    provides interface Read<uint16_t>;  
}
```

# AntiTheft Light Sensor Wiring [List 6.9]

```
configuration AntiTheftAppC { }  
implementation {  
... /* the wiring for the blinking Red LED */  
  components DarkC, MainC, LedsC;  
  components new TimerMilliC ( ) as TTimer;  
  components new PhotoC ( );  
  
  DarkC.Boot -> MainC;  
  DarkC.Leds -> LedsC;  
  DarkC.TheftTimer -> TTimer;  
  DarkC.Light -> PhotoC;  
}
```



# Single Hop Networks

- TinyOS uses a layered network structure where each layer defines a header and footer layout.
- The lowest **exposed** network layer in TinyOS is called *active messages (AM)*.
- **AM** is typically implemented directly over a mote's radio providing **unreliable**, single-hop packet transmission and reception.

# Single Hop Networks

- Packets are identified by an **AM type**, an 8-bit integer that identifies the packet type.
- '**Active Messages**' indicates the type is used automatically to dispatch received packets to an appropriate handler.
- Each packet holds a user-specified **payload** of up to **TOSH\_DATA\_LENGTH** bytes (normally **28 bytes**)\*\*.
- A variable of type **message\_t** holds a single AM packet.

**\*\* changeable at compile time.**

# Platform-Independent Types

- TinyOS has traditionally used **structs** to define message formats and directly access messages.
- Platform-independent structs are declared with **nx\_struct** and every field of a platform-independent struct must be a platform-independent type.

```
nx_uint16_t val ;           // A big-endian 16-bit value  
nxle_uint32_t otherval;    // A little-endian 32-bit value
```

# TinyOS 2.0 CC2420 Header [List 3.32]

```
typedef nx_struct cc2420_header_t ** {  
    nxle_uint8_t length;  
    nxle_uint16_t fcf;  
    nxle_uint8_t dsn;  
    nxle_uint16_t destpan;  
    nxle_uint16_t dest;  
    nxle_uint16_t src;  
    nxle_uint8_t type;  
} cc2420_header_t;
```

The CC2420 expects all fields to be little-endian.

# Theft Report Payload

Modifying anti-theft to report theft by sending a broadcast message

Platform-independent struct in the `antitheft.h` header file:

```
#ifndef ANTITHEFT_H
#define ANTITHEFT_H
typedef nx_struct theft {
    nx_uint16_t who;
} theft_t;
```

...

```
#endif
```

← struct to define payload

# AMSend Interface [List 6.12]

- Contains all the commands needed to **fill in** and **send** packets:

```
interface AMSend {  
    command error_t send (am_addr_t addr, message_t*  
                           msg, uint8_t len);  
    event void sendDone (message_t* msg, error_t error);  
    command error_t cancel (message_t* msg);  
    command uint8_t maxPayloadLength ( );  
    command void* getPayload (message_t* msg, uint8_t len);  
}
```

Node's AM address (usually) = TOS\_NODE\_ID

# Sending Report-Theft Packets [List 6.13]

uses interface **AMSend** as **Theft**;

...

```
message_t reportMsg; //theft report message buffer
bool sending;        //Do not send while a send is in progress
void reportTheft ( ) {
    theft_t* payload = call Theft.getPayload (&reportMsg,
                                              sizeof (theft_t) );

    if (payload && !sending)
    { //If Payload fits and we are idle - Send packet
        payload->who = TOS_NODE_ID; //Report being stolen!
        //Broadcast the report packet to everyone
        if (call Theft.send (TOS_BCAST_ADDR, &reportMsg,
                             sizeof (theft_t) ) == SUCCESS)
        }
    }
}
```

# Sending Report-Theft Packets [List 6.13]

```
event void Theft.sendDone (message_t *msg,  
                           error_t error) {  
    sending = FALSE; //Our send completed  
}
```

Called from MovingC

```
if (variance > ACCEL_VARIANCE * ACCEL_NSAMPLES)  
{  
    call Leds.led2On ( ) ; /* Theft Alert */  
    reportTheft ( );  
}
```



# Generic AMSenderC configuration

```
generic configuration AMSenderC (am_id_t AMId) {  
  provides {  
    interface AMSend;  
    interface Packet;  
    interface AMPacket;  
    interface PacketAcknowledgements as Acks;  
  }  
}
```

# Communication Stack

Cannot switch itself on and off on-demand, and needs the **SplitControl** interface to start and stop the radio:

```
interface SplitControl {                                     [List 6.14]
    command error_t start ( );
    event void startDone (error_t error);

    command error_t stop ( );
    event void stopDone (error_t error);
}
```

# MovingC using SplitControl

uses interface **SplitControl** as **CommControl**;

...

```
event void Boot.booted ( ) {  
    call CommControl.start ( ) ;  
}
```

```
event void CommControl.startDone (error_t ok) {  
    //Start checks once communication stack is ready  
    call TheftTimer.startPeriodic (ACCEL_INTERVAL);  
}
```

```
event void CommControl.stopDone (error_t ok) { }
```

# Moving C Receiving Packet

- **MovingC** receives a packet payload (defined as a **struct** contained in a header file **antitheft.h**) that contains acceleration settings for detecting movement of the mote:

```
typedef nx_struct settings {  
    nx_uint16_t accerVariance;  
    nx_uint16_t accelInterval;  
} settings_t;
```

← struct to define payload

# AM Packet Reception

- Provided by the TinyOS Receive interface:

```
interface Receive {  
    event message_t* receive(message_t* msg,  
                             void* payload, uint8_t len);  
}
```

`Receive.receive`, as a receive “handler”, receives a packet buffer which it can simply return or return as a different buffer if the handler wants to hold onto buffer.

# MovingC Receiving Packet [List 6.16]

uses interface `Receive` as `Setting`;

...

```
uint16_t accelVariance = ACCEL_VARIANCE;
```

```
event message_t* Settings.receive (message_t *msg,  
                                   void *payload, uint8_t len) {  
    if (len >= sizeof (settings_t)) //Check for valid packet  
    { /* Read settings by casting payload to settings_t,  
        reset check interval */  
        settings_t *settings = payload;  
        accelVariance = setting->accelVariance;  
        call TheftTimer.startPeriodic (setting->accelInterval);  
    }  
    return msg;  
}
```

# Selecting a Communication Stack

- Need to wire to the components representing the desired communications stack.

```
configuration ActiveMessageC {  
    provides interface SplitControl;  
    ...  
}  
generic configuration AMSenderC (am_id_t id) {  
    provides interface AMSend;  
    ...}  
generic configuration AMReceiverC (am_id_t id) {  
    provides interface Receive;  
    ...}
```

# TinyOS Applications Summary

- AntiTheft Example
  - LEDs, Timer, Boot
  - **get, enum**
- Sensing Example
  - Light Sensor
  - **Read (split-phase)**
  - Wiring to AntiTheft
  - **Two Timer instances**



# TinyOS Applications Summary

- Single Hop Networks
  - Active Messages, typed messages
  - Platform-independent types
- Sending packets
  - AMSenderC generic configuration
  - SplitControl of Radio Stack
  - Structs for packet payloads
- Receiving packets
  - Implemented as a receive event handler.