# Collision Aware Rate Adaptation (CARA)

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### Outline

- Introduction to Dynamic Rate Adaptation
- Related Work
  - Classification
  - ARF
  - RBAR
- CARA-1 and CARA-2
- Simulation Results
- Conclusions and Future Work



#### Basic CSMA/CA

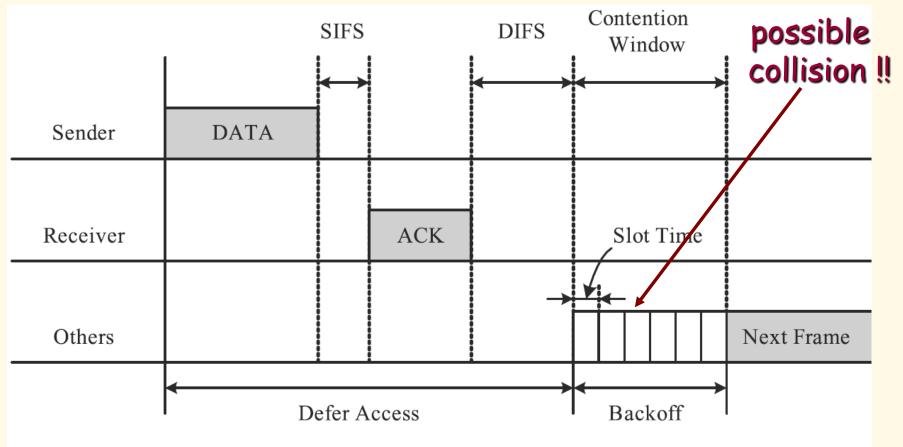
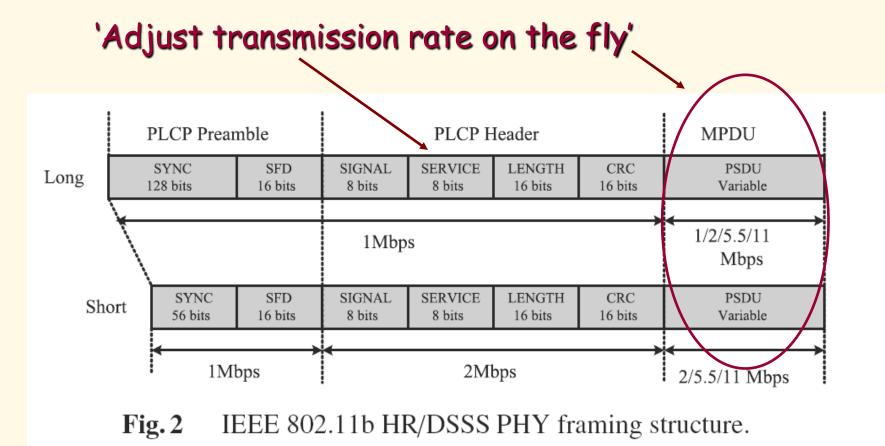


Fig. 1 CSMA/CA protocol of IEEE 802.11 MAC DCF. [N. Kim]



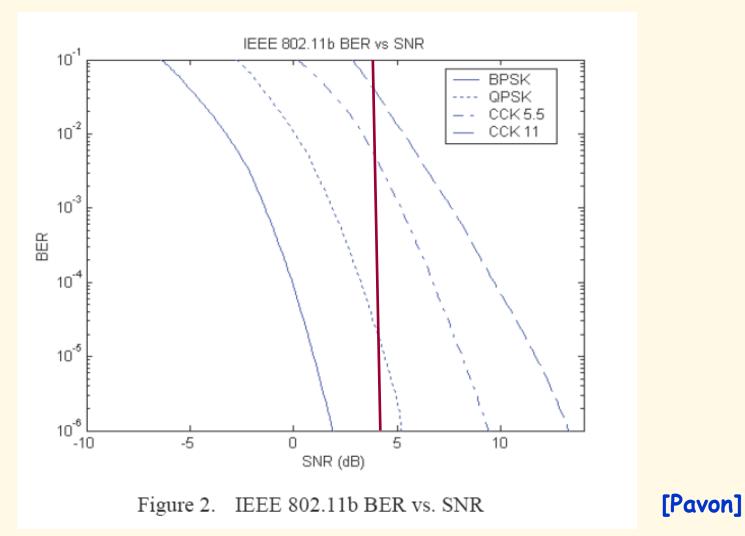
#### 802.11 Physical Layer



[N. Kim]



BER vs SNR



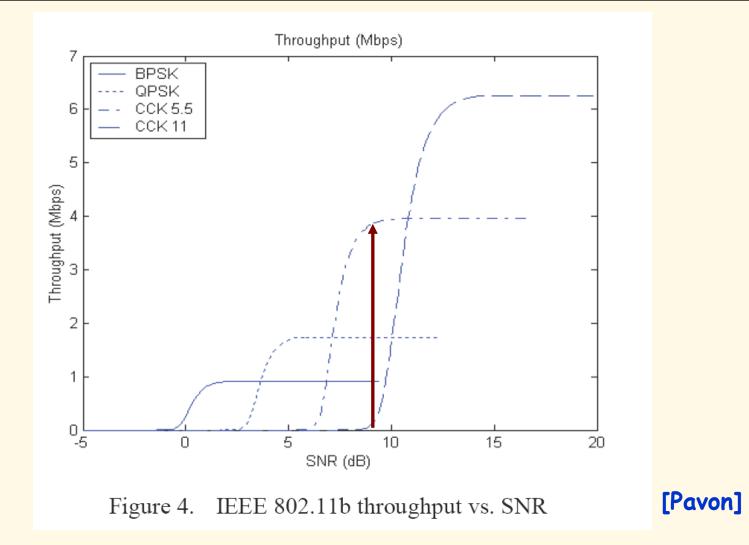


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#### Throughput vs SNR





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#### Unfairness

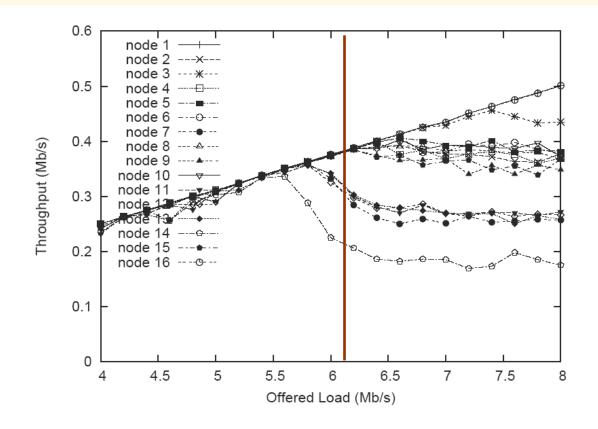


Figure 14: Empirical DCF fairness with respect to individual throughput share as a function of offered load for 16 iPAQs in indoor office environment.

[Choi]



Figure 2 RTS/CTS

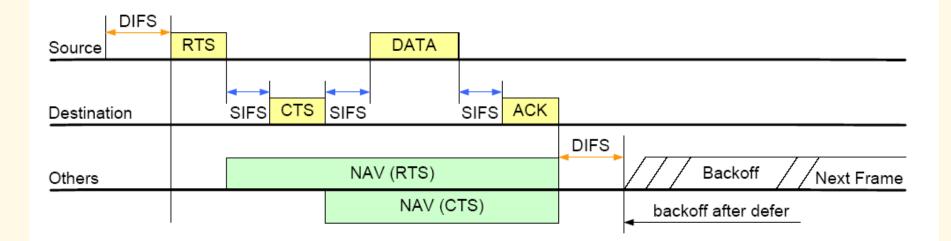


Fig. 2. RTS/CTS exchange mechanism of IEEE 802.11



#### RTS/CTS Summary

- . RTS/CTS can reduce collisions.
- RTS/CTS can guard against and reduce hidden terminals.
- RTS/CTS adds overhead that reduces throughput.
- Normally, RTS/CTS is turned off!



#### **Rate Adaptation Algorithms**

AARF	ARF	AMRR
CARA	CROAR	DOFRA
Fast-LA	HRC	LA
LD-ARF	MiSer	MultiRateRetry
MPDU	OAR	ONOE
PER	RBAR	RFT
RRAA	SampleRate	SwissRA



#### **Rate Adaptation Algorithms**

<b>1997</b>	ARF			
1998				
1999				
2000				
2001	RBAR			
2002	MPDU	OAR	PER	
2003	LA	MiSer	SwissRA	
2004	AARF	AMRR	HRC	MultiRateRetry
2005	Fast-LA	LD-ARF	RFT	SampleRate
2006	CARA	CROAR	DOFRA	RRAA
2007				



#### **Rate Adaptation Algorithms**

- Uses recent history and probes: ARF, AARF, SampleRate Long interval smoothing: ONOE, SampleRate Multiple rates: MultiRateRetry, AMRR, RRAA Uses RTS/CTS: RBAR, OAR, CROAR, CARA Uses RSSI to approximate SNR, each node maintains 12 dynamic RSS thresholds: LA Puts checksum on header and use NACK to signal link loss
- Puts checksum on header and use NACK to signal link loss error: LD-ARF
- Table lookup with thresholds: HRC, MPDU(len, rSNR, count) Fragmentation: DOFRA, RFT
- Miscellaneous: PER, MiSer, SwissRA, Fast-LA



#### Auto Rate Fallback (ARF)

- When **two** consecutive ACK frames are not received correctly, the second retry and subsequent transmissions are sent at the next lower rate and a timer is started.
- When the number of successfully received ACKs reaches 10 or the timer goes off, a **probe frame** is sent at the **next higher** rate. However, if an ACK is NOT received for this frame, the rate is lowered back and the timer is restarted.





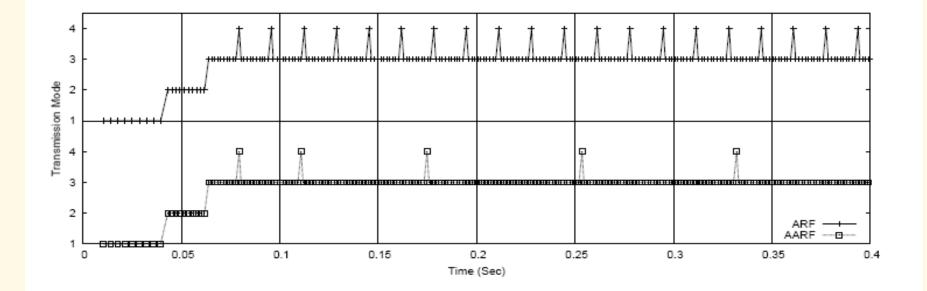


Figure 1: Mode selection comparison between ARF and AARF.



#### Receiver Based Auto Rate (RBAR)

- Receivers control sender's transmission rate.
- RTS and CTS are modified to contain info on size and rate {not 802.11 compatible}.
- Uses analysis of RTS reception (RSSI) to estimate SNR and choice sent back to sender in CTS.
- Receiver picks rate based on apriori SNR thresholds in a lookup table.



#### Collision Aware Rate Adaptation (CARA)

#### CARA uses two methods for identifying collisions:

## 1. RTS probing

#### 2. Clear Channel Assessment (CCA) detection



# **RTS** Probing

#### **RTS Probing Idea:**

Assume all RTS/CTS transmission failures after a successful RTS/CTS exchange must be due to channel errors.

# (Note - this assumes hidden terminals are not possible.)



#### CARA-1

- Data frame transmitted without RTS/CTS.
- If the transmission fails, RTS/CTS exchange is activated for the next retransmission. If this retransmission fails (assume channel quality problem), then the rate is lowered.
- If retransmission with RTS/CTS is successful {assume collision occurred}, stay at same rate and send next frame without RTS/CTS.



# Figure 4 ARF and RTS Example

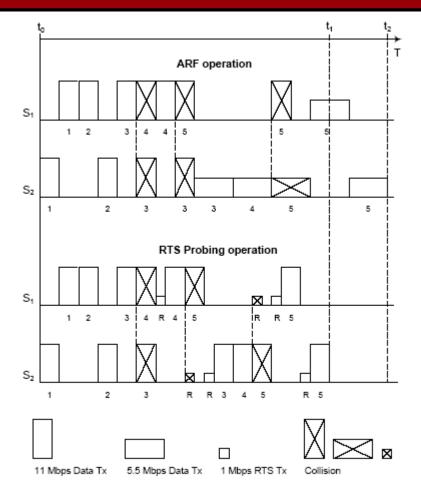


Fig. 4. Illustration of ARF and RTS-Probing timelines for a two-station network, when channel status is good enough to accommodate the highest transmission rate of the 802.11b PHY, i.e., 11 Mbps



#### Clear Channel Assessment (CCA)

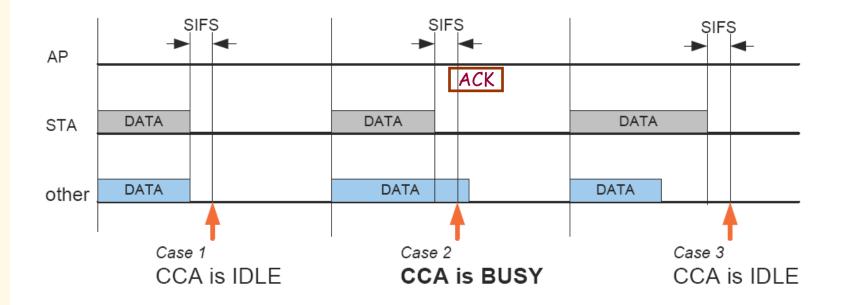


Fig. 5. Three possible cases of collision. In the second case, the collision can be detected via CCA detection.

[J. Kim]



#### **CCA** Collision Detection

- . Case 2: It is a collision.
  - Transmit without increasing failure count and lowering the transmission rate. No RTS/CTS probe is needed.
- Case 1 and Case 3: Cannot determine that a collision has occurred.
  - Initiate RTS/CTS probe scheme.



#### Rate Adaptation versus Distance

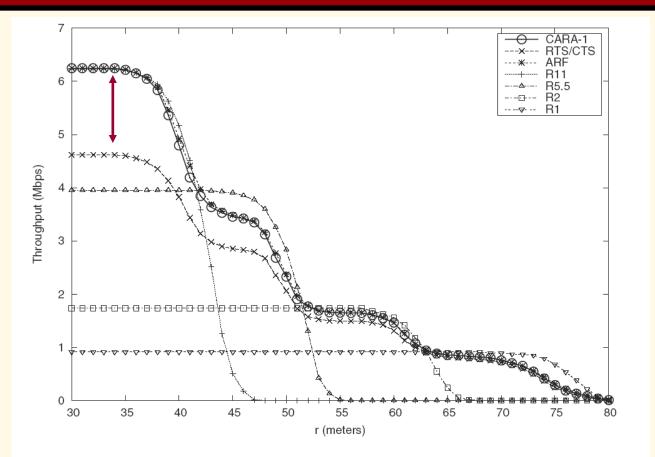


Fig. 6. Throughput comparison of our proposed rate adaptation scheme (CARA-1) against RTS/CTS, ARF, and single-rate schemes for one-to-one topology networks with various distance (r)



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# NS-2 Simulation Details

- . 20dBm transmit power
- Static stations; 1500 octet MAC payload
- BER vs SNR curves measured in AWGN (Additive White Gaussian Noise) environment without fading.
- Set background noise to -96dBm
- . Simulate indoor settings
- Use Ricean fading model for multi-path fading time-varying wireless conditions.



CARA-1 Throughput

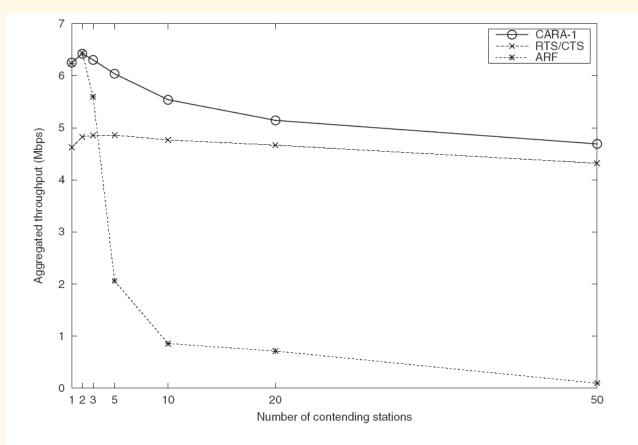


Fig. 7. Throughput comparison of our proposed rate adaptation scheme (CARA-1) against RTS/CTS and ARF for star-topology networks with various number of contending stations



## Figure 8 CARA-1 and CARA-2

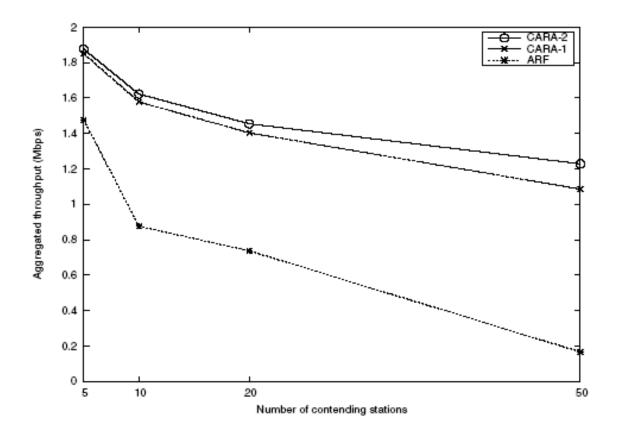
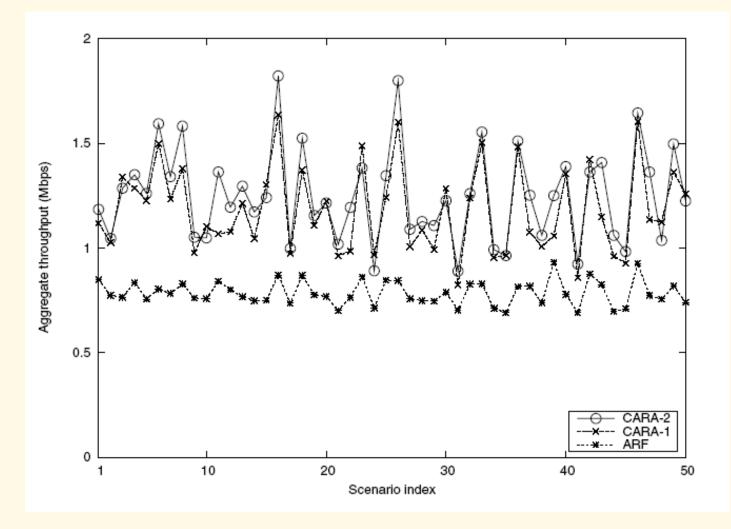


Fig. 8. Throughput comparison of our proposed rate adaptation schemes (CARA-1 and CARA-2) against ARF for line-topology networks with various number of contending stations with randomly chosen data frame sizes and stations' positions



### Figure 9a: 50 scenarios

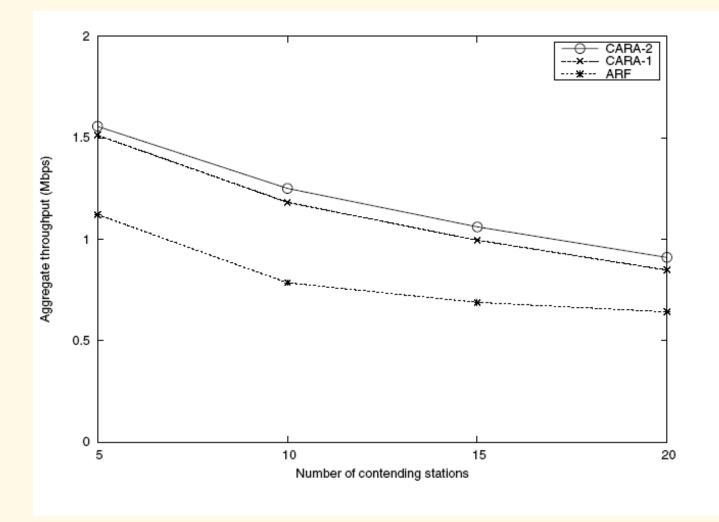




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#### Figure 9b Varying contending stations

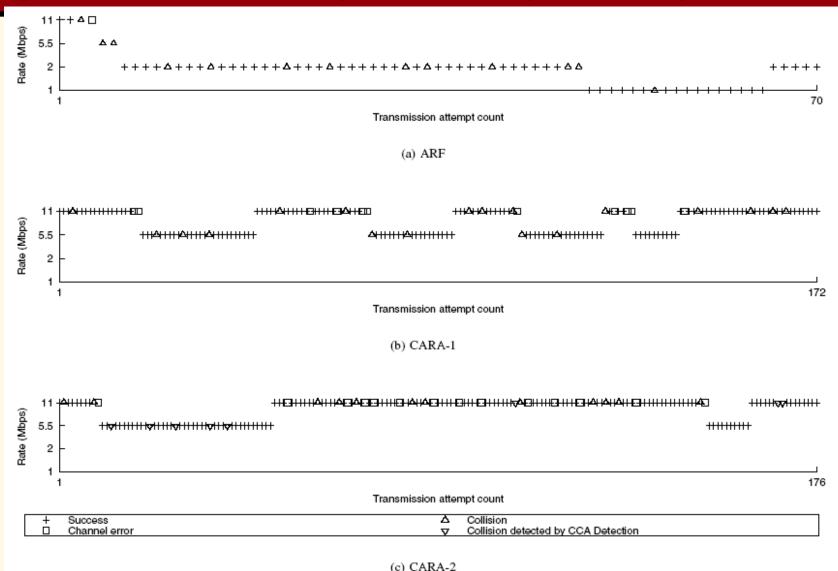




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### Figure 10 Adaptability Comparison





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#### TABLE II

#### COMPARISON OF THREE TESTING SCHEMES FOR THE 30-SECOND

#### SIMULATION RUN

	ARF	CARA-1	CARA-2
# of tx attempts	1344	3092	3246
# of tx successes	1094	2518	2643
Throughput (Mbps)	1.58	3.37	3.49



## Conclusions

- CARA is more likely to make correct rate adaptation decisions than ARF.
- CARA requires no change to the 802.11 standard (unlike RBAR).
- CARA significantly outperforms ARF in all simulated multiple contending environments.

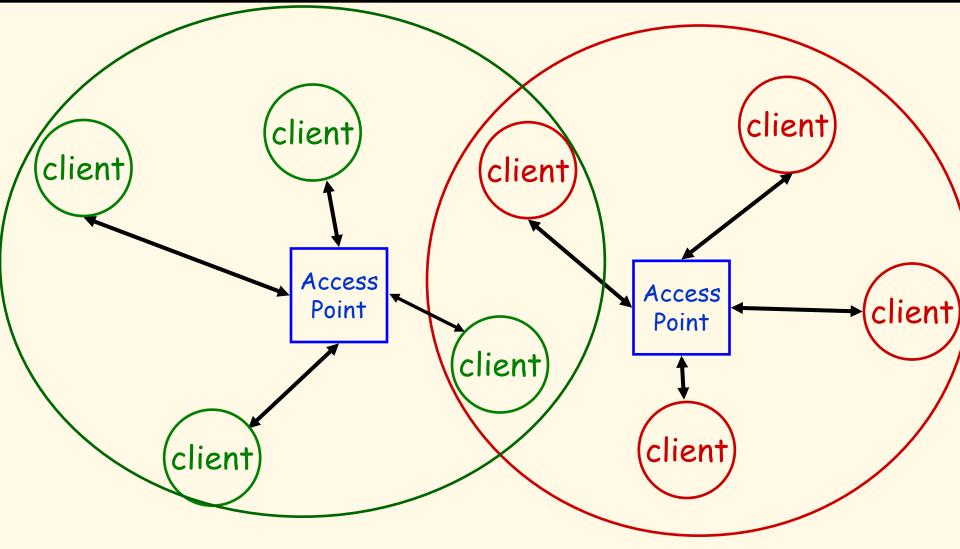


# Future Work

- Look at changes to the increase rate algorithm [CARA-RI].
- Study optimization of operational CARA parameters.
- Address possibility of hidden terminal detection [CARA-HD].
- Built a working CARA prototype using MadWIFI driver.



#### Multiple APs multiple clients (heterogeneous)





#### Hidden Terminals

Without a hidden terminal, loss ratio ~5.5%. One hidden AP with mild sending rate (0.379 Mbps) yields:

	$/ \land$			
	ARF	AARF	SampleRate	FixedRate
Goodput (Mbps)	0.65	0.56	0.58	1.46
Loss Ratio	61%	60%	59%	60%

Table 1: Performance of different rate adaptation algo-rithms in the presence of hidden stations.[Wong]



### **Future Work Results**

Seongkwan Kim, Sunghyun Choi, Daji Qiao, and Jongseok Kim

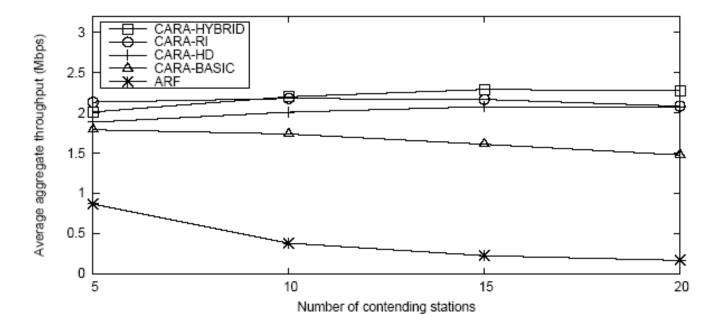


Fig. 1. Throughput comparison in random-topology networks.





# Collision Aware Rate Adaptation (CARA)



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