

Spanning Trees in Dense Graphs

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In this paper we prove the following almost optimal theorem. For any $\delta > 0$, there exist constants c and n_0 such that, if $n \geq n_0$, T is a tree of order n and maximum degree at most $cn/\log n$, and G is a graph of order n and minimum degree at least $(1/2 + \delta)n$, then T is a subgraph of G .

1. Introduction

1.1. Notation and definitions

We will sometimes use $+$ and Σ to denote disjoint unions of sets. $V(G)$ and $E(G)$ denote the vertex set and the edge set of the graph G , and we write $v(G) = |V(G)|$ (order of G) and $e(G) = |E(G)|$ (size of G). (A, B) or (A, B, E) denote a bipartite graph $G = (V, E)$, where $V = A + B$, and $E \subset A \times B$. In general, given any graph G and two disjoint subsets A, B of $V(G)$, the pair (A, B) is the graph restricted to $A \times B$. $N(v)$ is the set of neighbours of $v \in V$. Hence the size of $N(v)$ is $|N(v)| = \deg(v) = \deg_G(v)$, the degree of v . $\delta(G)$ stands for the minimum, and $\Delta(G)$ for the maximum degree in G . More generally, for $A \subset V(G)$ we write $N(A) = \cup_{v \in A} N(v)$. $N(u, v) = N(u) \cap N(v)$ is the set of common neighbours. For a vertex $v \in V$ and set $U \subset V - \{v\}$, we write $\deg(v, U)$ for the number of edges from v to U . The length of a path is the number of its edges, and the distance between two vertices x and y , denoted by $\text{dist}(x, y)$, is the minimum length of an $x - y$ path. We let $e(A, B)$ denote the number of edges of G with one end-point in A and the other in B . For non-empty A and B ,

$$d(A, B) = \frac{e(A, B)}{|A||B|}$$

is the *density* of the graph between A and B .

Definition 1. The pair (A, B) is ε -regular if

$$X \subset A, Y \subset B, |X| > \varepsilon|A|, |Y| > \varepsilon|B|$$

imply

$$|d(X, Y) - d(A, B)| < \varepsilon;$$

otherwise it is ε -irregular.

Definition 2. $G = (A, B, E)$ is said to be (ε, δ) -super-regular if it is ε -regular, and

$$\deg(a) > \delta|B| \quad \text{for all } a \in A, \quad \text{and} \quad \deg(b) > \delta|A| \quad \text{for all } b \in B.$$

Given a rooted tree and a vertex v , we write $A(v)$ for the set of ancestors of v , $C(v)$ for the set of children of v , $G(v)$ for the set of grandchildren of v , and $T(v)$ for the set of descendants of v (including v itself). In a tree T we denote the set of leaves by $L(T)$. In a star S we denote the middle vertex (or the root) by $M(S)$. A rooted forest is a forest of rooted trees. We will use $a \ll b$ to denote that a is sufficiently small compared to b . For simplicity, we do not always compute these dependences, although it could be done.

1.2. Packings and subtrees in dense graphs

Definition 3. An *embedding* of a graph $G = (V, E)$ into a graph $G' = (V', E')$ is an edge-preserving one-to-one map from V to V' , that is, an injection $\varphi : V \rightarrow V'$ such that $\{u, v\} \in E$ implies $\{\varphi(u), \varphi(v)\} \in E'$.

Such a map φ induces an injection from E into E' ; we will use the notation φ for that map, too. In particular, we will write $\varphi(E)$ for the image set of the edges of G .

Definition 4. Given a set of graphs G_1, G_2, \dots, G_l , we say that G_1, G_2, \dots, G_l can be *packed* into G if we can find embeddings φ_i of G_i into G such that the edge sets $\varphi_i(E(G_i))$ are pairwise disjoint. If $G = K^n$, the complete graph on n vertices, then we say simply that there is a packing of G_1, G_2, \dots, G_l .

The notion of packing plays an important role in the investigation of computational complexity of graph properties. Thus it is not surprising that in recent research literature there is considerable interest in packing-type results and problems (see, e.g., [2, 3, 4, 13]).

Along these lines, solving an old conjecture of Bollobás [2] we proved the following [6].

Theorem 1.1. *Let Δ and $c < 1/2$ be given. Then there exists a constant n_0 with the following properties. If $n \geq n_0$, T is a tree of order n with $\Delta(T) \leq \Delta$, and G is a graph of order n with $\Delta(G) \leq cn$, then there is a packing of T and G .*

We proved this theorem in the following equivalent embedding form.

Theorem 1.1'. *Let Δ and $\delta > 0$ be given. Then there exists a constant n_0 with the following properties. If $n \geq n_0$, T is a tree of order n with $\Delta(T) \leq \Delta$, and G is a graph of order n with $\delta(G) \geq ((1/2) + \delta)n$, then T is a subgraph of G .*

In this form, the theorem can be considered as a generalization of Dirac's theorem on Hamiltonian paths. The proof in [6] laid the foundations for a series of papers in which we developed a new method based on the Regularity Lemma and the Blow-up Lemma (see [6, 8, 9, 10, 7, 11]). The method is usually applied to finding certain constant maximum degree spanning subgraphs in dense graphs. Typical examples are spanning trees (above), Hamiltonian cycles or powers of Hamiltonian cycles [10, 7] or H -factors for a fixed graph H [11].

Returning to Theorem 1.1' and the original paper [6], it is a natural question (first asked by P. Erdős) whether in this theorem the constant degree requirement on T can be relaxed. The purpose of this paper is to prove the following almost optimal result in this direction.

Theorem 1.2. *Let $\delta > 0$ be given. Then there exist constants c and n_0 with the following properties. If $n \geq n_0$, T is a tree of order n with $\Delta(T) \leq cn/\log n$, and G is a graph of order n with $\delta(G) \geq ((1/2) + \delta)n$, then T is a subgraph of G .*

This result is optimal apart from a constant factor. In fact, let c_1 be a sufficiently large constant, and let T and G be as follows: T is a rooted tree with root r and depth 2, $\deg(r) = (\log n)/c_1$ and the degrees of the children of r are as equal as possible; G is a random n -graph with edge-probability 0.9. An easy calculation shows that, with high probability for large n , G satisfies $\delta(G) > 0.8n$ but T is not a subgraph of G .

In addition to being an almost optimal result, Theorem 1.2 is the first case when we were able to apply the Regularity Lemma/Blow-up Lemma method for finding spanning subgraphs with higher than constant maximum degree.

2. Main tools

2.1. Regularity Lemma

In the proof the following lemma of the third author plays a central role.

Lemma 2.1 (Regularity Lemma). *For every $\varepsilon > 0$ and positive integer m there are positive integers $M = M(\varepsilon, m)$ and $N = N_0(\varepsilon, m)$ with the following property: for every graph G with $n \geq N$ vertices there is a partition of the vertex set into $k + 1$ classes (clusters)*

$$V = C_0 + C_1 + C_2 + \cdots + C_k$$

such that

- $m \leq k \leq M$,
- $|C_0| < \varepsilon n$,
- $|C_1| = |C_2| = \cdots = |C_k|$,
- at most εk^2 of the pairs (C_i, C_j) are ε -irregular.

The proof can be found in [15], although an earlier version appeared in [16].

We will also use the following easy consequence of the Regularity Lemma (see [6]).

Lemma 2.2 (Degree form of the Regularity Lemma). *For every $\varepsilon > 0$ and positive integer m there are positive integers $M = M(\varepsilon, m)$ and $N = N_0(\varepsilon, m)$ with the following property: if $G = (V, E)$ is any graph with $n \geq N$ vertices and $d \in [0, 1]$ is any real number, then there is a partition of the vertex set into $k+1$ clusters C_0, C_1, \dots, C_k , and there is a subgraph $H \subset G$ with the following properties:*

- $V(H) = V(G)$,
- $m \leq k \leq M$,
- $|C_0| \leq \varepsilon n$,
- $|C_1| = |C_2| = \dots = |C_k|$,
- $\deg_H(v) > \deg_G(v) - (d + \varepsilon)n$ for all $v \in V$,
- all $H|_{C_i}$ are empty (the C_i s are independent in H),
- all pairs $H|_{C_i \times C_j}$, $1 \leq i < j \leq k$, are ε -regular, each with a density either 0 or exceeding d .

Furthermore, if G satisfies $\delta(G) \geq (\frac{1}{2} + 2d + 2\varepsilon)v(G)$, then the following additional conditions can also be met:

- k is even,
- the clusters can be matched $\sum C_i = (\sum A_i) + (\sum B_i)$ in such a way that H restricted to any pair (A_i, B_i) is (ε, d) -super-regular.

We will refer to the pairs (A_i, B_i) as the ‘edges of the 1-factor’.

In [6] the proof of Theorem 1.1’ reduced the general embedding problem to two special cases, namely, embedding forests of stars and forests of paths into bipartite graphs. Here we again use these two special cases in Section 4.1.

2.2. Embedding a forest of stars

Given a bipartite graph $G = (A, B, E)$ and a vector $\underline{d} = (d_a : a \in A)$, $\sum d_a \leq |B|$ of positive integers, we say that G has a \underline{d} -matching from A to B if there is a partition $B = B_0 + \sum_{a \in A} B_a$ such that, for all $a \in A$,

$$|B_a| = d_a \quad \text{and} \quad \{a\} \times B_a \subset E.$$

Lemma 2.3 (Embedding a forest of stars). *Let $G = (A, B, E)$ be a bipartite graph, and write*

$$\delta_A = \min_{a \in A} \deg(a), \quad \delta_B = \min_{b \in B} \deg(b).$$

We are also given a vector $\underline{d} = (d_a : a \in A)$, $\sum d_a \leq |B|$ of positive integers, and we write $\Delta = \max d_a$.

If G has the weak expanding property

$$(X \subset A, Y \subset B, |X| > \delta_A/\Delta, |Y| > \delta_B) \quad \text{imply} \quad e(X, Y) > 0,$$

then there is a \underline{d} -matching from A to B .

This lemma is a relatively straightforward consequence of Hall’s theorem (for details see [6]).

2.3. Embedding a forest of paths

Definition 5. A *four-layer graph* is a graph $G = (V, E)$ where $V = V_1 + V_2 + V_3 + V_4$, $|V_i| = m$, $1 \leq i \leq 4$, and $E \subset \sum_{i=1}^3 A_i \times A_{i+1}$.

A *four-layer super-regular graph* is a four-layer graph in which the graphs $G_{|V_i+V_{i+1}}$ are all super-regular.

Lemma 2.4. For every $\delta > 0$, there are $\varepsilon, m_0 > 0$ such that the following holds for all $m \geq m_0$. If G is a four-layer (ε, δ) -super-regular graph on $4m$ vertices, then for any one-to-one map between V_1 and V_4 there exists a set of m vertex-disjoint paths of order 4, each one connecting mapped pairs.

We note that three layers would not be sufficient, since a vertex on layer 1, while certainly connected (by paths of order 3) to at least $(1 - \varepsilon)n$ vertices of layer 3, is not necessarily connected to *all* vertices of layer 3. Furthermore, it would be much easier to prove a 5-layer version of the lemma: namely, one can choose a random one-to-one map between V_1 and V_3 , and this has to be modified at only a few vertices. We just used the 4-layer version because it is optimal.

2.4. Random ε -regular subgraphs

Our final tool is the following lemma.

Lemma 2.5. Let $0 < \varepsilon \ll d$. There exist constants $C, n_0 > 0$ and $\varepsilon \ll \varepsilon' \ll d$ with the following properties. Let $n \geq n_0$, $m \geq m' \geq n_0$, and let (A, B) be an ε -regular pair of density d with $|A| = m$ and $|B| = n$. Let us select at random a subset $A' \subset A$ with $|A'| = m'$. Then with probability close to 1 we have the following:

- (1) the pair (A', B) is ε' -regular,
- (2) if $m' \geq C \log n$, then (with probability $1 - O(ne^{-m'})$) every vertex $v \in B$ has degree $\deg(v, A') \geq \deg(v, A) \frac{m'}{m} - \varepsilon m'$.

Indeed, (2) is just the consequence of the law of large numbers.

For (1), observe that, with high probability (about $1 - O(m'e^{-\varepsilon m'})$), apart from at most $4\varepsilon|A'|^2$ exceptional pairs in A' , for a pair $\{x, x'\} \subset A'$ we have

$$|N(x, x')| \geq (d - \varepsilon)^2 |B|.$$

This so-called quasi-random property is known to imply (1) (see [14, 1, 5]).

3. Sketch of the proof of Theorem 1.1'

In [6] the proof of Theorem 1.1' followed the following rough outline. We started by splitting the graph G into a 1-factor of super-regular pairs as guaranteed by Lemma 2.2, and splitting the tree T into a constant number of small trees. These small trees were assigned to the edges of the 1-factor first in an approximate manner, and then, moving some vertices around, we made this assignment exact. Then we embedded the bulk of T

with the application of a simple greedy technique, and finally an application of Lemma 2.3 or Lemma 2.4 concluded the proof.

4. Proof of Theorem 1.2

4.1. Special cases when the proof of Theorem 1.1' works

Here we will use the following main parameters:

$$\beta \ll \varepsilon' \ll \alpha \ll \delta. \quad (4.1)$$

Let us make T rooted by picking an arbitrary vertex r as the root. The proof method in [6] works with minor modifications for $\Delta(T) \leq cn/\log n$ as well in the following special cases:

- T contains at least αn vertex-disjoint paths of length 3 (induced, with counting edges),
- T contains at least αn non-leaf vertices with at least one leaf child.

We sketch briefly that this is in fact the case. For further details see [6].

We decompose T into small trees. Find a vertex v such that

- $|T(v)| \geq \beta n$, and
- $|T(u)| < \beta n$ for every $u \in C(v)$.

Each subtree $T(u)$ is a piece of the decomposition and the (u, v) edges are called bridges. We cut these pieces out and continue with the remaining part of T . The obtained pieces in this decomposition are all of size less than βn , and their number is at most

$$\left(\frac{1}{\beta} + 1\right) \frac{cn}{\log n}.$$

We decompose G into a matching of clusters using Lemma 2.2, with ε' playing the role of ε . We define two types of buffer vertices B_1, B_2 in T . In both cases these vertices are disjoint from the bridges. In the first case they are $\lfloor \alpha n/2 \rfloor$ vertex-disjoint paths of length 3, where the first type of buffer vertices (B_1) are the end-points of the paths, and the other type (B_2) is the set of the middle vertices on the paths. In the second case, B_1 is a set of $\lfloor \alpha n/2 \rfloor$ non-leaf vertices with at least one leaf child, and B_2 is the set of their leaf children.

The crucial observation is that the number of bridges is much less than the number of both types of buffer vertices. We first assign the pieces to clusters as follows. We assign the next piece to the next pair where we have so far assigned fewer vertices to both clusters than the actual number of vertices in the two clusters. We fill up the two clusters in a balanced way and we ensure that we assign sufficiently many B_1 (and thus also B_2) buffer vertices to each cluster. This can easily be achieved by a simple greedy strategy. Then in each pair we consider the assigned buffer vertices and we set aside random buffer zones for them (separately for B_1 and B_2). We start the actual embedding.

- We embed the pieces in a top-down breadth-first manner, first finishing the embedding of a whole piece (apart from the B_2 buffer vertices) before moving over to the next piece. Thus, we first embed the piece P_1 containing r and we put the pieces that are connected to P_1 through bridges in a left-to-right ordering into a first-in first-out queue. We remove the first piece P from the queue, we embed it, and again we put the pieces

that are connected to P through bridges in a left-to-right ordering into the end of the queue. We continue in this fashion until the queue is empty, by always embedding the first piece from the queue, and putting the pieces that are connected to this piece through bridges in a left-to-right ordering into the end of the queue.

- We embed the non-bridge vertices of a piece into the pair where the piece is assigned with a greedy strategy. That is, we always embed into a vertex that has many neighbours in the remaining non-buffer zone vertices, so we can continue the embedding.
- We handle the bridges as follows. Suppose (u, v) is a bridge between pieces P and P' where $u \in P', v \in P$ and $u \in C(v)$. Assume that v is embedded into cluster C , and P' is assigned to (G, G') such that the children of u are assigned to G . Find a D such that v has many neighbours in D , and (D, G) is an ε -regular pair with high density. Embed u into a vertex (buffer vertex if the rest of $N_D(v)$ is occupied already) in D with large degree in G . We embed the children of u into non-buffer vertices among these neighbours and continue the greedy strategy for the embedding of P' .
- We embed the non-buffer vertices into non-buffer zone vertices, and we embed the B_1 buffer vertices into their buffer zones. The B_2 buffer vertices (so the middle vertices of the paths in the first case, and the leaves in the second) remain unembedded at this point.
- When we run out of empty non-buffer vertices or empty B_1 buffer zone vertices in a cluster, we combine these two sets and continue the embedding. Finally when this set becomes small as well, we combine it with the B_2 buffer zone and finish the embedding apart from the B_2 buffer vertices.
- After an adjusting step, since the number of bridges is small, for the embedding of the B_2 buffer vertices in each pair we can use Lemma 2.3 or Lemma 2.4, respectively, in the two cases.

The missing details can be found in [6]. Therefore we can assume that neither of these two cases holds. This implies that T contains mostly leaves; more precisely it contains at least $(1 - \sqrt{\alpha})n$ leaves.

We distinguish two cases, according to the distribution of the leaves among the levels

$$V_i = \{v : v \in T, \text{dist}(r, v) = i\}.$$

In the remainder of the proof we will use the following main parameters:

$$\alpha \ll \gamma \ll \varepsilon \ll d \ll \delta. \quad (4.2)$$

4.2. The well-distributed case

In this case we assume

$$|V_i| < \gamma n \quad \text{for all } i, \quad (4.3)$$

that is, the leaves are distributed relatively evenly among the levels. The other case, when at least one level contains a large portion of the leaves, is discussed in the next section.

We break up the proof into a few steps.

Step 1: Decomposition of T .

We define

$$U_j = \bigcup_{i \equiv j \pmod{1/d}} V_i \quad \text{for } 0 \leq j < 1/d$$

(for simplicity we assume that $1/d$ is an integer). Let us consider U_j with the maximum number of leaves in it ($\geq d(1 - \sqrt{\alpha})n$). The levels in U_j divide T into regions R_0, R_1, R_2, \dots , where

$$R_0 = \{V_t : 0 \leq t \leq j\}, \quad \text{and}$$

$$R_i = \left\{ V_t : \frac{i-1}{d} + j + 1 \leq t \leq \frac{i}{d} + j \right\} \quad \text{for } i = 1, 2, \dots$$

Since R_0 may be a short region, for simplicity we remove V_j from U_j . U_j still contains at least $dn/2$ leaves. We consider the grandparents in T of the leaves in U_j , and we denote these vertices by r_1, r_2, \dots, r_l (roots) in a top-down, breadth-first order. Let T_i denote the depth-2 subtree of T with root r_i and leaves in U_j . This subforest (denoted by F) will play a major role in the rest of the proof in the well-distributed case. The leaves in most of this subforest will be embedded only at the very end to the buffer zones by using a König–Hall argument. Note that r_i may have children in T not in T_i , and also a child of r_i in T_i may have children not in T_i .

Step 2: Decomposition of G .

We partition G into clusters using Lemma 2.2 with ε and d as in (4.2). Note that we will not use the matching part of Lemma 2.2 but use a covering by stars instead.

Step 3: Construction of the star covering.

We define the following so-called *reduced graph* G_r : The vertices of G_r are the clusters C_i , $1 \leq i \leq k$, in the partition and there is an edge between two clusters if they form an ε -regular pair in H with density exceeding d . Since, in H ,

$$\delta(H) > \delta(G) - (d + \varepsilon)n \geq \left(\frac{1}{2} + \delta\right) - (d + \varepsilon)n,$$

an easy calculation shows that in G_r we have

$$\delta(G_r) \geq \left(\frac{1}{2} + \frac{\delta}{2}\right)k. \tag{4.4}$$

This implies that, for all $C_1, C_2 \in G_r$, we have

$$|N_{G_r}(C_1) \cap N_{G_r}(C_2)| \geq \delta k. \tag{4.5}$$

This time, for the finishing König–Hall-type argument we need a covering (of most of the clusters) by a constant number of stars in G_r instead of a covering by independent edges (matching). We are going to construct a constant number of stars S_1, S_2, \dots, S_s in G_r with the following properties.

- (1) $L(S_i) \cap L(S_j) = \emptyset$ for every $1 \leq i < j \leq s$ (but note that $M(S_i) \in S_j$ or $M(S_j) \in S_i$, or even $M(S_i) = M(S_j)$, is allowed).

(2) For every $S_i, 1 \leq i \leq s$ we have the following:

$$|N_{G_r}(M(S_j)) \cap L(S_i)| \geq d^2|L(S_i)| \quad \text{for every } 1 \leq j \leq s, j \neq i.$$

These clusters in $L(S_i)$ are called bridge clusters from S_i to S_j .

(3) $n - \sum_{i=1}^s |L_G(S_i)| \leq \varepsilon n$, where $L_G(S_i)$ denotes the set of vertices in G in the leaf clusters of S_i .

We construct these stars in the following way. For the first star S_1 , take an arbitrary cluster as $M(S_1)$, and $L(S_1)$ is the neighbour of $M(S_1)$ in G_r , so from (4.4) we have

$$|L(S_1)| \geq \left(\frac{1}{2} + \frac{\delta}{2}\right)k.$$

In addition, select randomly a subset $L'(S_1) \subset L(S_1)$ of size $d|L(S_1)|$ (assuming that this is an integer). By the law of large numbers and (4.5), with high probability, we have

$$|N_{G_r}(C) \cap L'(S_1)| \geq \frac{\delta}{2}|L'(S_1)| = \frac{\delta}{2}d|L(S_1)| \gg d^2|L(S_1)| \tag{4.6}$$

for every cluster C , since, from (4.5),

$$|N_{G_r}(C) \cap L(S_1)| \geq \delta k.$$

Fix a subset $L'(S_1)$ for which (4.6) is true for every cluster C in G_r .

For S_2 , if there is a cluster in $G_r \setminus S_1$ which covers at least half of the clusters in $G_r \setminus S_1$, then this cluster is $M(S_2)$ and its neighbours in $G_r \setminus S_1$ are $L(S_2)$. Otherwise, from (4.4), we have $d_{G_r}(S_1, G_r \setminus S_1) > 1/2$, so there must exist a cluster in S_1 which covers at least half of the clusters in $G_r \setminus S_1$. In this case, this cluster is $M(S_2)$ and its neighbours in $G_r \setminus S_1$ are $L(S_2)$. In addition, in both cases we add some more clusters to $L(S_2)$. We select randomly a subset $L'(S_2)$ of size $d|L(S_2)|$ from $N_{G_r}(M(S_2)) \setminus L'(S_1)$. Note that $L'(S_2)$ may contain clusters from $L(S_1)$. Again, by the law of large numbers and (4.5), with high probability, we have

$$|N_{G_r}(C) \cap L'(S_2)| \geq \frac{\delta}{2}|L'(S_2)| = \frac{\delta}{2}d|L(S_2)| \gg d^2|L(S_2)| \tag{4.7}$$

for every cluster C , since, from (4.5),

$$|N_{G_r}(C) \cap (N_{G_r}(M(S_2)) \setminus L'(S_1))| \geq \delta k - |L'(S_1)| \geq \frac{3}{4}\delta k.$$

Fix a subset $L'(S_2)$ for which (4.7) is true for every cluster C in G_r . Remove the clusters in $L'(S_2) \cap L(S_1)$ from $L(S_1)$ and add them to $L(S_2)$ as well, so now $L'(S_2) \subset L(S_2)$.

We continue in this fashion. Assume that S_1, \dots, S_{i-1} are already defined. To get S_i , $M(S_i)$ is a cluster that covers at least half of the clusters in $G_r \setminus \cup_{j=1}^{i-1} S_j$, and $L(S_i)$ is the set of its neighbours in $G_r \setminus \cup_{j=1}^{i-1} S_j$. In addition, we select randomly a subset $L'(S_i)$ of size $d|L(S_i)|$ from $N_{G_r}(M(S_i)) \setminus \cup_{j=1}^{i-1} L'(S_j)$. By the law of large numbers and (4.5), with high probability, we have

$$|N_{G_r}(C) \cap L'(S_i)| \geq \frac{\delta}{2}|L'(S_i)| = \frac{\delta}{2}d|L(S_i)| \gg d^2|L(S_i)| \tag{4.8}$$

for every cluster C , since, from (4.5),

$$|N_{G_r}(C) \cap (N_{G_r}(M(S_i)) \setminus \cup_{j=1}^{i-1} L'(S_j))| \geq \delta k - |\cup_{j=1}^{i-1} L'(S_j)| \geq \frac{3}{4}\delta k.$$

Fix a subset $L'(S_i)$ for which (4.8) is true for every cluster C in G_r . Remove the clusters in $L'(S_i) \cap (\cup_{j=1}^{i-1} L(S_j))$ from $\cup_{j=1}^{i-1} L(S_j)$, and add them to $L(S_i)$, so now $L'(S_i) \subset L(S_i)$.

We continue in this fashion until $n - \sum_{j=1}^i |L_G(S_j)| \leq \varepsilon n$. Since every star covers at least half of the remaining clusters, we have $s \leq \lceil \log \frac{1}{\varepsilon} \rceil$. Properties (1) and (3) are satisfied by the construction. For property (2), observe that during the whole process we removed at most $d|L(S_i)|$ clusters from $L(S_i) \setminus L'(S_i)$ when we constructed the stars $S_j, i < j \leq s$. This fact, $L'(S_i) \subset L(S_i)$ and (4.8) applied to $C = M(S_j)$ show that property (2) of the star covering is satisfied as well.

Step 4: Setting buffer vertices aside.

The buffer vertices in T are the leaves in the T_i s. The buffer zones ($\text{buf}(C)$) are simply subsets of every leaf cluster in the stars (so in $\cup_{i=1}^s L(S_i)$) such that their sizes are as equal as possible and the total number of vertices in them is the same as the number of buffer vertices in T . Thus all the buffer zones have size at least $\frac{d}{2} \frac{n}{k}$. We select the sets $\text{buf}(C)$ at random, uniformly from among all subsets of C of the given size. Denote $\text{buf}(G) = \cup_C \text{buf}(C)$, and, in general, for a collection of clusters K let $\text{buf}(K)$ denote $= \cup_{C \in K} \text{buf}(C)$. This selection guarantees, by the law of large numbers (as in Lemma 2.5), that these buffers have the following property:

- $\text{deg}(v, \text{buf}(C)) \geq (d - 2\varepsilon)|\text{buf}(C)|$ for all clusters C , and for all $v \in V$ such that $\text{deg}(v, C) \geq (d - \varepsilon)|C|$.

Step 5: Decomposing F into two subforests F_1 and F_2 , assigning the T_i s in F_1 to stars. In this step, for technical reasons we decompose F into two subforests $F = F_1 \cup F_2$, where F_2 will consist of the last few levels of the T_i s. We assign only the T_i s in F_1 to stars; F_2 will be used later (Step 9) for the handling of the various exceptional vertices.

Define s'_1 by

$$\sum_{i=1}^{s'_1} |L(T_i)| \leq (1 - \varepsilon^{1/4})|\text{buf}(L(S_1))|, \quad \text{but} \quad \sum_{i=1}^{s'_1+1} |L(T_i)| > (1 - \varepsilon^{1/4})|\text{buf}(L(S_1))|.$$

Let s_1 be the largest integer for which $s_1 \leq s'_1$, and r_{s_1} is the last root on a level. Relations (4.2) and (4.3) imply that

$$(1 - \varepsilon^{1/4})|\text{buf}(L(S_1))| \geq \sum_{i=1}^{s_1} |L(T_i)| \geq (1 - 2\varepsilon^{1/4})|\text{buf}(L(S_1))|.$$

Then T_1, \dots, T_{s_1} are assigned to S_1 , so the children of r_1, \dots, r_{s_1} in T_1, \dots, T_{s_1} (and actually all other non-leaf vertices at this level) are assigned and will be embedded into $M(S_1)$, and the leaves in T_1, \dots, T_{s_1} are assigned and will be embedded into the leaf clusters of S_1 . Define s'_2 by

$$\sum_{s_1+1}^{s'_2} |L(T_i)| \leq (1 - \varepsilon^{1/4})|\text{buf}(L(S_2))|, \quad \text{but} \quad \sum_{s_1+1}^{s'_2+1} |L(T_i)| > (1 - \varepsilon^{1/4})|\text{buf}(L(S_2))|,$$

and similarly s_2 is the largest integer for which $s_2 \leq s'_2$, and r_{s_2} is the last root on a level. The trees $T_{s_1+1}, \dots, T_{s_2}$ are assigned to S_2 , so the children of $r_{s_1+1}, \dots, r_{s_2}$ in these trees

are assigned and will be embedded into $M(S_2)$, and the leaves are assigned and will be embedded into the leaf clusters of S_2 .

We continue in this fashion until we have assigned T_i s to every star. F_1 denotes the subforest of the T_i s that are assigned to stars and $F_2 = F \setminus F_1$. Note that there are still at least $\varepsilon^{1/3}n$ leaves in F_2 , and these leaves will be used to handle the various exceptional vertices in Step 9.

Before proceeding further, let us point out two important facts here. First, from (4.2), for any cluster C ,

$$|T \setminus L(T)| \leq \sqrt{\alpha n} \ll \varepsilon|C|. \quad (4.9)$$

Second, from (4.2) and (4.3), for any cluster C ,

$$|V_i| < \gamma n \ll \varepsilon|C| \quad \text{for all } i. \quad (4.10)$$

Thus the total number of non-leaf vertices in T and the size of one level of T are both very small compared to the size of a cluster.

Step 6: Assigning most of the non-buffer vertices in T to specific clusters.

In this step, before we start the actual embedding, we assign most of the non-buffer vertices in T to specific clusters. The only non-buffer vertices in T which will not be assigned in this step are the children of the roots in F_2 . The assignment means that later these vertices will be embedded into the clusters where they were assigned. We emphasize here that, at this point, we only assign these vertices to clusters: they will be actually embedded into these clusters only later. We only assign vertices to the leaf clusters in the stars.

Denote the last region by R_m , where the T_i s at the bottom of the region are in F_1 . Write $R'_i = R_i \setminus V_{\frac{i}{d}+j}$; thus we get R'_i by removing the last level in R_i . In each region R'_i , $1 \leq i \leq m$, we consider the level (denoted by $V(R_i)$) with the smallest number of leaves. Clearly, for the number of leaves in $\cup_{i=1}^m V(R_i)$ we have

$$\sum_{i=1}^m |L(V(R_i))| \leq dn. \quad (4.11)$$

This level $V(R_i)$ breaks up R'_i into two parts (one possibly empty): a leaf-light part ($LL(R_i)$), which contains fewer leaves, and a leaf-heavy part ($LH(R_i)$), which contains more leaves. Thus, if $V(R_i) = V_t$ for some $\frac{i-1}{d} + j + 1 \leq t \leq \frac{i}{d} + j - 1$, and the upper half is the lighter part, then

$$\begin{aligned} LL(R_i) &= \cup_{t'} \left\{ V_{t'} : \frac{i-1}{d} + j + 1 \leq t' \leq t-1 \right\}, \\ LH(R_i) &= \cup_{t'} \left\{ V_{t'} : t+1 \leq t' \leq \frac{i}{d} + j - 1 \right\} \quad \text{and} \\ R'_i &= LL(R_i) \cup LH(R_i) \cup V(R_i). \end{aligned}$$

For R_0 we just put $LL(R_0) = R_0$, and for $i > m$, $LH(R_i) = R'_i$.

First we assign only the leaves in $\cup_{i=0}^m LL(R_i)$ to clusters. This is done with a simple greedy strategy. As we go top-down in T , we assign the leaves at the next level in $\cup_{i=0}^m LL(R_i)$ to the cluster with the smallest number of leaves assigned to it so far. Note

that when we assigned all the leaves in $\cup_{i=0}^m LL(R_i)$ with this procedure, the difference between the number of assigned leaves in two arbitrary clusters $C_1, C_2 \in \cup_{i=1}^s L(S_i)$ is at most the size of the level V_i in T with the most leaves, which is $\ll \varepsilon|C_1| = \varepsilon|C_2|$ by (4.10). We have to make sure that this assignment is realizable; thus we have to assign the non-leaf vertices in $\cup_{i=0}^m LL(R_i)$ carefully. Furthermore, we are also going to assign the leaves on level $V(R_i)$.

Suppose first that $LL(R_i)$ is the upper half of region $R_i, i \geq 1$. Assume further that the non-leaf vertices on the last level of R_{i-1} (i.e., $V_{\frac{i-1}{d}+j-1}$) are assigned to cluster G (if $i \geq 2$, and the T_i s at the bottom of R_{i-1} are assigned to star S , then $G = M(S)$) and that the leaves on the first level of R_i (i.e., $V_{\frac{i}{d}+j+1}$) are assigned to cluster C . The non-leaf vertices on the last level of R_{i-1} are assigned to a cluster D , such that $(G, D), (D, C) \in E(G_r)$ ((4.5) implies that D exists). Similarly, if the non-leaf vertices on a certain level are already assigned to cluster G , and the leaves two levels below are assigned to cluster C , then the non-leaf vertices on the next level are assigned to cluster D , such that $(G, D), (D, C) \in E(G_r)$. For R_0 , if the leaves on V_1 are assigned to cluster C , then the root of T is assigned to a cluster D with $(D, C) \in E(G_r)$, and for the remaining non-leaf vertices we follow the same strategy as above for $i \geq 1$.

We continue in this fashion for $i \geq 1$ until the assignment of the non-leaf vertices two levels before $V(R_i)$, so on the level V_{t-2} , if $V(R_i) = V_t$. The assignment of these non-leaf vertices requires some special care. We follow the same procedure as for the non-leaf vertices on the other levels. However, here we do not just take one arbitrary cluster among the possible $\geq \delta k$ clusters (guaranteed by (4.5)), but we take the cluster with the fewest leaves from $\cup_{i=1}^m V(R_i)$ assigned to it so far. Furthermore, we assign the leaves on level $V(R_i)$ to this cluster. But we do not assign at this point the non-leaf vertices one level before or on $V(R_i)$. These will be used to connect the embedding of $LL(R_i)$ and $LH(R_i)$.

The case when $LL(R_i), i \geq 1$ is the lower half of R_i is similar, except that we move level by level upward until $V(R_i)$. In fact, assume that the T_i s at the bottom of R_i are assigned to star S , and the leaves on the last level of $LL(R_i)$ (i.e., $V_{\frac{i}{d}+j-1}$) are assigned to cluster C . The non-leaf vertices on $V_{\frac{i}{d}+j-2}$ (thus including the roots r_i) are assigned to a cluster D such that $(M(S), D), (D, C) \in E(G_r)$. We continue to move upward in this fashion until the level after $V(R_i)$, so the level V_{t+1} . Say the leaves on this level are assigned to cluster C , and the non-leaf vertices on this level are assigned to cluster G . Again, for the assignment of the non-leaf vertices on level $V(R_i)$, we take the cluster from the at least δk clusters in $N_{G_r}(C) \cap N_{G_r}(G)$ (using (4.5)) with the fewest leaves assigned to it so far from $\cup_{i=1}^m V(R_i)$. Furthermore, we assign the leaves on level $V(R_i)$ to this cluster. Thus, in this case we assign all the vertices in $LL(R_i) \cup V(R_i)$.

We follow the same procedure for all the regions $R_i, 1 \leq i \leq m$. From the above construction, (4.9) and (4.11), it follows that, when we have finished this part of the assignment, the difference between the number of assigned vertices in two arbitrary clusters $C_1, C_2 \in \cup_{i=1}^s L(S_i)$ is at most

$$(d/\delta + \varepsilon)|C_1| = (d/\delta + \varepsilon)|C_2|. \quad (4.12)$$

This in turn implies that the number of assigned vertices for every cluster C is at most

$(1/2 + 2d/\delta)|C \setminus \text{buf}(C)|$, using (4.9), (4.11) and the fact that $LL(R_i)$ contained fewer leaves than $LH(R_i)$.

Next we assign the leaves in $\cup_i LH(R_i)$ with the usual greedy procedure. That is, as we go from top to bottom in T , we assign the leaves at the next level in $\cup_i LH(R_i)$ to the cluster with the smallest number of vertices assigned to it so far. Note that with this procedure we eliminate the somewhat larger discrepancy of (4.12), and when we assigned all the leaves in $\cup_i LH(R_i)$, the difference between the number of assigned vertices in two arbitrary clusters $C_1, C_2 \in \cup_{i=1}^s L(S_i)$ is $\ll \varepsilon|C_1| = \varepsilon|C_2|$ again.

We finish Step 6 by assigning the remaining non-leaf vertices (except for the children of the roots in F_2) to clusters. This is done the same way as in the assignment of the non-leaf vertices in $\cup_{i=1}^m LL(R_i)$ above. Furthermore, we assign the non-leaf vertices on the level before $V(R_i)$ in such a way that the embedding of the upper and lower halves of R_i can be connected. More precisely, let us assume that the non-leaf vertices two levels above $V(R_i)$ (so on level V_{t-2} , if $V(R_i) = V_t$) are assigned to a cluster C , and the non-leaf vertices on $V(R_i)$ are assigned to cluster G . Then the non-leaf vertices on the level before $V(R_i)$ (on level V_{t-1}) are assigned to a cluster D , such that $(C, D), (D, G) \in E(G_r)$ (using (4.5)).

This finishes the assignment procedure: we have assigned every non-buffer vertex of T except for the children of the roots in F_2 . The difference between the number of assigned vertices in two arbitrary clusters $C_1, C_2 \in \cup_{i=1}^s L(S_i)$ is $\ll \varepsilon|C_1| = \varepsilon|C_2|$. This fact implies that, for every cluster $C \in \cup_{i=1}^s L(S_i)$, the difference between the number of assigned non-buffer vertices and the available non-buffer zone vertices in C is $\ll \varepsilon|C|$.

Now we are in a position to start the actual embedding process. As we move down in T region by region we execute the following two tasks in a given region.

- We embed the vertices in $T \setminus F$ level by level in the region into non-buffer zone vertices of the cluster where the vertex is assigned (see Step 7).
- If the T_i s at the bottom of the region belong to F_1 , and they are assigned to star S_i , then with a special procedure (described in Step 8) we first embed the roots r_i into their assigned cluster, then their children into $M(S_i)$, and finally we assign the leaves in the T_i s to $L(S_i)$. These buffer vertices will be embedded only at the end by a König–Hall procedure in Step 11. Otherwise, if the T_i s belong to F_2 , then we embed them by another special procedure (described in Step 9) to handle the various exceptional vertices.

Even though these two tasks are executed together for each region, we separate their discussion for better understanding.

Step 7: Embedding $T \setminus F$.

We embed the vertices in $T \setminus F$ level by level from top to bottom with a simple greedy procedure into the non-buffer zone vertices of the clusters where they are assigned. Namely, we always embed a non-leaf vertex of T into a non-buffer zone vertex v of the given cluster, such that v has high degree (at least $(d - \varepsilon)$ -portion) to the remaining non-buffer zone vertices of the one or two clusters where the vertices at the next level of T are assigned. ε -regularity makes this possible, and this guarantees that we can always continue the embedding. The roots r_i and their children in the T_i s in F_1 are embedded with a special strategy, described in the next step, but the buffer vertices in F_1 are not embedded

at this point. F_2 is embedded by another special strategy, described in Step 9. When there are only a few non-buffer zone vertices left ($< \sqrt{\varepsilon}|C|$) in a cluster $C \in \cup_{i=1}^s L(S_i)$, we unite the buffer zone with the non-buffer zone and continue embedding in this set.

Step 8: Embedding the roots and their children in F_1 .

Consider the first S_1 and the trees T_1, T_2, \dots, T_{s_1} assigned to it. Because of the above construction, when we are embedding an $r_j, 1 \leq j \leq s_1$, it can still be embedded into a large subset ($\geq (d - \varepsilon)\sqrt{\varepsilon}$ -portion) of the cluster where it was assigned. Denote this cluster by $Cl(r_j)$. We have $(Cl(r_j), M(S_1)) \in E(G_r)$. We are going to partition the children of these roots in F into groups G_1, G_2, \dots depending on the number of their children. We place those children of the roots in G_i when the number of children is in the interval

$$\left(\frac{cn}{\log n} 2^{-i}, \frac{cn}{\log n} 2^{1-i} \right].$$

The number of groups (denoted by g) is at most $\log n$. To each root we assign two kinds of weights corresponding to the groups. For $r_j, w_i(r_j)$ is the number of G_i children of r_j , and $lw_i(r_j)$ (leaf weight) is the number of leaves under these G_i children of r_j . Similarly, for $v \in G_i, lw(v)$ is the number of leaves under v , and $lw(G_i) = \sum_{v \in G_i} lw(v)$.

For each $i, 1 \leq i \leq g$ we partition the roots into two classes: we say that a root $r_j, 1 \leq j \leq s_1$ is *i-heavy* if

$$w_i(r_j) \geq c_2 \log n, \quad (4.13)$$

where c_2 is a sufficiently large constant, and we say it is *i-light* if (4.13) does not hold. We denote the set of *i-heavy* roots by iH , and similarly iL for the *i-light* roots.

We are going to embed the vertices in G_i in quite large blocks, and the *i-light* roots can cause some problems. However, it is enough to restrict our attention to groups G_i with

$$\sum_{r_j \in iL} w_i(r_j) \geq c_3 \log n, \quad (4.14)$$

where c_3 is a sufficiently large constant compared to c_2 . In fact, let us assume that (4.14) does not hold for a group G_i . First let us embed arbitrarily the G_i children of the *i-light* roots into unoccupied vertices in $M(S_1)$. Then we embed the leaves under one such G_i child of an *i-light* root into the cluster $C \in N_{G_i}(M(S_1))$ with the smallest number of vertices assigned to it so far. The number of exceptional leaves we have to embed in this way is very small: it is

$$\leq \sum_{i=1}^g c_3 \log n \frac{cn}{2^{i-1} \log n} \ll \varepsilon |C|,$$

for every cluster C , if c is sufficiently small. Thus, for simplicity, we assume that (4.14) holds in every group $G_i, 1 \leq i \leq g$.

For the embedding of the G_i children of the *i-light* roots we will set aside a random buffer zone $\text{buf}(G_i)$ in $M(S_1)$. (Note that this buffer zone has nothing to do with the buffer zones for the leaves in F .) We construct this random set in the following way. First we remove a small number of exceptional vertices from $M(S_1)$ denoted by $\text{Exc}(M(S_1))$. These are vertices with the property that they have few ($< (d - \varepsilon)$ -portion) neighbours in many

($\geq \sqrt{\varepsilon}$ -portion) leaf clusters of S_1 . The number of these vertices is $\leq \sqrt{\varepsilon}|M(S_1)|$. In the remaining set every vertex has large degree to most of the leaf clusters. This fact will be important later for the completing König–Hall argument.

We select this set $\text{buf}(G_i)$ randomly (and disjointly for different $1 \leq i \leq g$) from the remaining non-exceptional vertices with size

$$(1 + \sqrt{\varepsilon}) \sum_{r_j \in iL} w_i(r_j) \geq c_3 \log n. \quad (4.15)$$

Note that Lemma 2.5 and (4.2) imply that with high probability $(\text{buf}(G_i), C)$ is a $\sqrt{\varepsilon}$ -regular pair for every $1 \leq i \leq g$ and cluster $C \in N_{G_i}(M(S_1))$, and furthermore, if for a $v \in C$ we have $\deg(v, M(S_1)) \geq (d - \varepsilon)|M(S_1)|$ (most vertices are such in C), then $\deg(v, \text{buf}(G_i)) \geq (d - 2\varepsilon)|\text{buf}(G_i)|$.

We are going to embed the G_i children of the i -light roots into $\text{buf}(G_i)$. These G_i vertices embedded into $\text{buf}(G_i)$ will form the first (and the only light) block $B_{i,1}$ for G_i . The remaining blocks $B_{i,2}, B_{i,3}, \dots$ will be heavy blocks defined below.

We start the embedding with r_1 . Consider those i s for which r_1 is i -light, denoted by $\text{Light}(r_1)$. Similarly $\text{Heavy}(r_1)$ can be defined. r_1 can still be embedded into a large subset of $Cl(r_1)$. From this subset we remove the few exceptional vertices v for which $\deg(v, M(S_1)) < (d - \varepsilon)|M(S_1)|$. We embed r_1 into a random vertex of the remaining set. For an $i \in \text{Heavy}(r_1)$ we embed the G_i children of r_1 into a random subset (with the given size $w_i(r_1)$) of the remaining unoccupied vertices in $N_{M(S_1)}(r_1) \setminus \text{Exc}(M(S_1))$. At the same time we assign the leaf children of these vertices to $L(S_1)$. For these i s this is a heavy block, so it is $B_{i,j}$ for some $j \geq 2$. The heavy blocks behave the same way as the light blocks, so, for every block $B_{i,j}$, the pair $(B_{i,j}, C)$ is a $\sqrt{\varepsilon}$ -regular pair for every cluster $C \in N_{G_i}(M(S_1))$.

For $i \in \text{Light}(r_1)$, by the above remark with high probability the (embedded) r_1 has many neighbours in $\text{buf}(G_i)$ for every $1 \leq i \leq g$. The G_i children of r_1 are embedded into these neighbours and we assign the leaf children of these vertices to $L(S_1)$.

Next we move to r_2 and we follow the same procedure. We update $\text{buf}(G_i)$ by removing the vertices occupied in the previous step. We embed r_2 into a random vertex in $Cl(r_2)$ that has many neighbours in $M(S_1)$. For $i \in \text{Heavy}(r_2)$ we embed the G_i children of r_2 into a random subset of the remaining unoccupied vertices in $N_{M(S_1)}(r_2) \setminus \text{Exc}(M(S_1))$ of the appropriate size and we assign the leaf children to $L(S_1)$. For $i \in \text{Light}(r_2)$ we embed the G_i children of r_2 into $\text{buf}(G_i)$.

We continue with this procedure for all the roots assigned to S_1 . Lemma 2.5 and (4.15) imply that we never get stuck, we are able to embed all the G_i children of i -light roots into $\text{buf}(G_i)$. Lemma 2.5 also implies that with high probability we have the following: for every $B_{i,j}$, $C \in L(S_1)$ and $v \in C$, if

$$\deg(v, M(S_1)) \geq (d - \varepsilon)|M(S_1)|, \quad (4.16)$$

then we have

$$\deg(v, B_{i,j}) \geq (d - 2\varepsilon)|B_{i,j}|. \quad (4.17)$$

Note that, apart from $\leq \varepsilon|C|$ exceptional vertices, (4.16) holds for every vertex $v \in C$.

We follow the same procedure for all the stars, and the T_i s assigned to them. At this

point the only T_i s remaining are in F_2 . They will be used to handle the various exceptional vertices in the next step.

Step 9: Embedding F_2 and handling the various exceptional vertices.

It is time to take care of the various exceptional vertices, a common task in applications of the Regularity Lemma. First of all we have the remaining unoccupied vertices in C_0 and in the exceptional clusters not covered by the leaves of the stars. Denote their set by E . We add some more vertices to E from each star S . These are unoccupied vertices v in the leaf clusters of S such that, for the exceptional blocks $B_{i,j}$ for which (4.17) does not hold for v , we have

$$\sum lw(B_{i,j}) \geq \sqrt{\varepsilon}|L_G(S)|. \quad (4.18)$$

The number of these exceptional vertices is at most $\sqrt{\varepsilon}|C|$ in every $C \in L(S)$. We add these vertices to E as well. The size of E is still at most $2\sqrt{\varepsilon}n \ll \varepsilon^{1/3}n$.

Next we take care of the vertices in E : we embed leaves from the remaining T_i s (F_2) into them by a simple greedy strategy. From the construction we know that there are still at least $\varepsilon^{1/3}n$ (much more than $|E|$) unassigned leaves in F_2 . Denote the roots in F_2 by r'_1, r'_2, \dots . These roots are embedded into G by the greedy strategy described in Step 7. Denote the embedded image vertex in G by $G(r'_i)$. From $\delta(G) \geq (1/2 + \delta)n$ and the random choice of the buffer zones, for every $e \in E$, the two vertices $G(r'_1)$ and e have at least δn common unoccupied neighbours in $\text{buf}(G)$. Thus there is an unoccupied neighbour u_1 of $G(r'_1)$ which has at least $\delta|E|$ neighbours in E . Embed one of the children of r'_1 in F_2 into u_1 and embed the leaves under this child of r'_1 in F_2 into neighbours of u_1 in E . We repeat this procedure for the remaining vertices in E . When $|E|$ becomes small ($\leq \frac{cn}{\delta \log n}$), it might not be possible to embed all the leaves under a child of a root to these neighbours in E . In this case, let us assume that this child of a root in F_2 is embedded into vertex u_i in G . We embed the remaining leaves that cannot be embedded in E into the remaining buffer vertices of the cluster with the smallest number of embedded vertices, chosen from those clusters where u_i has many neighbours ($\geq d$ -portion in at least half the clusters). We handle similarly the remaining leaves in F_2 , when there are no more unoccupied vertices left in E .

When we are finished with the procedure, and all the vertices are embedded except for the F_1 -buffer leaves, for every cluster $C \in \cup_{i=1}^s L(S_i)$ the difference between the number of vertices that are embedded into C and the non-buffer zone vertices in C is $\ll \varepsilon^{1/4}|C|$.

Step 10: Adjusting the assignment.

Thus at this point there can be a small difference ($\ll \varepsilon^{1/4}|S_i|$) in a star S_i between the number of remaining unoccupied vertices in the leaf clusters of the star and the number of F_1 leaves assigned to it. Therefore we need some adjusting. Consider a star S' where we assigned more F_1 leaves than vertices remaining, and a star S'' where we assigned fewer F_1 leaves than vertices remaining (there has to be one such star since we are looking for a spanning subgraph). By property (2) of the star covering, in S'' among the leaf clusters we have many ($\geq d^2|L(S'')|$) clusters which are bridge clusters from S'' to S' , that is, they are neighbours of $M(S')$ in G_r as well. We add one typical vertex from these common clusters from S'' to S' . Now we are one step closer to the perfect assignment, and by iterating

this process we can achieve it. Furthermore, using $\varepsilon \ll d$ we can guarantee that, during the whole adjustment procedure, we have removed or added at most $\varepsilon^{\frac{1}{3}}|C|$ vertices from every cluster C .

Step 11: Finishing the embedding of the F_1 -buffer leaves by a König–Hall argument.

We can treat the stars separately. Consider the bipartite graph $G(A, B)$, where A is the set of the children of the roots in F_1 embedded into the middle cluster of the given star (say S) and B is the set of the remaining unoccupied vertices in the leaf clusters. Let \underline{d} denote $(d_a : a \in A)$, where d_a is the number of leaf children of a (so $d_a = lw(a)$). We are looking for a \underline{d} -matching from A to B . We need to check the König–Hall criterion:

$$|N(X)| \geq d_X \quad \text{for all } X \subset A$$

holds with probability close to 1 (the choice of A was random). From the construction

$$A = \cup_{i=1}^g G_i, \quad G_i = \cup_{j=1}^{n_i} B_{i,j},$$

where n_i is the number of blocks in G_i , $v \in G_i$ implies

$$\frac{cn}{2^i \log n} < d_v \leq \frac{cn}{2^{i-1} \log n}, \quad (4.19)$$

and

$$\sum_{i=1}^g d_{G_i} = \sum_{i=1}^g \sum_{j=1}^{n_i} d_{B_{i,j}} = |B|. \quad (4.20)$$

Furthermore, from the construction we get that, with high probability, for every $B_{i,j}$, the pair $(B_{i,j}, B)$ is $\varepsilon^{\frac{1}{6}}$ -regular.

We distinguish three cases (the proof is similar to the König–Hall argument in [6]).

Case 1: $X_{i,j} = X \cap B_{i,j} < \varepsilon^{\frac{1}{6}}|B_{i,j}|$ for all blocks $B_{i,j}$.

Then, if $v \in X$ is arbitrary we get

$$|N(X)| \geq \deg(v) \geq \frac{d}{2}|B| = \sum_{i=1}^g \sum_{j=1}^{n_i} \frac{d}{2} d_{B_{i,j}} > \sum_{i=1}^g \sum_{j=1}^{n_i} d_{X_{i,j}} = d_X.$$

Here we used the fact that the minimum degree in $G(A, B)$ from A to B is at least $\frac{d}{2}|B|$, (4.19), (4.20), and that ε is much smaller than d .

Case 2: There exists a block $B_{i,j}$ with $X_{i,j} \geq \varepsilon^{\frac{1}{6}}|B_{i,j}|$ but $d_X \leq (1 - \varepsilon^{\frac{1}{6}})|B|$.

In this case we have

$$|N(X)| \geq (1 - \varepsilon^{\frac{1}{6}})|B| \geq d_X. \quad (4.21)$$

Indeed, this follows from the fact that $(B_{i,j}, B)$ is a $\varepsilon^{\frac{1}{6}}$ -regular pair. Thus, if (4.21) were not true, then with $Y = B \setminus N(X)$ we would have $|X| \geq \varepsilon^{\frac{1}{6}}|B_{i,j}|$, $|Y| \geq \varepsilon^{\frac{1}{6}}|B|$, but $d(X, Y) = 0$, contradicting $\varepsilon^{\frac{1}{6}}$ -regularity.

Case 3: $d_X > (1 - \varepsilon^{\frac{1}{6}})|B|$.

In this case, with high probability,

$$|N(X)| = |B| \geq d_X.$$

In fact, for an arbitrary $v \in B$, with high probability, (4.17) holds for almost all the blocks

$B_{i,j}$; the exceptional blocks (the blocks not satisfying (4.17)) have total d -weight $\leq 2\sqrt{\varepsilon}|B|$ (the exceptional vertices were removed from B). Therefore, in this case, there must be a non-exceptional block $B_{i,j}$ with $|X_{i,j}| \geq (1 - \varepsilon^{\frac{1}{3}})|B_{i,j}|$, implying $v \in N(X_{i,j}) \subset N(X)$. Since v was arbitrary,

$$N(X) = B,$$

thus finishing Case 3 and the proof of the well-distributed case.

4.3. The concentrated case

In this case we can assume that there is a level V_r with

$$|V_r| \geq \gamma n.$$

We are going to use ideas similar to the well-distributed case; therefore we will sometimes omit the details.

We are going to divide the proof into three (perhaps overlapping) special cases.

Case 1: There is an r with

$$|V_r| \geq \gamma n \quad \text{but} \quad |V_{r-1}| < \gamma |V_r|. \quad (4.22)$$

The proof of this case is similar to (but simpler than) the well-distributed case. Consider the leaves in V_r , their parents and grandparents. In this case these are the T_i s, with roots r_i on level V_{r-2} . The choice of buffer zones is the same. We start the embedding into non-buffer zone vertices from the top by arbitrarily embedding the root of T . Suppose that a non-leaf vertex v on a certain level is already embedded. Then, we embed its non-leaf children in T one by one into vertices with large degree to the cluster with the fewest vertices embedded into it so far, and then we embed the leaf grandchildren of v into these neighbours. We move down T in a top-down breadth-first manner until V_{r-3} , that is, one level before the roots of the T_i s. The handling of the T_i s and the construction of the stars is very similar to the well-distributed case. The only difference is that, since now we are not in the well-distributed case, a T_i can be large (for example there could be only one T_1). We divide T_i into smaller pieces $T_{i,j}$ which are disjoint apart from the common root r_i . The only problem could be that a T_i could be assigned to several stars, and then r_i would have to be connected to several stars. Thus we do the following. Take the first T_1 from the left. Assume that the father of r_1 on level V_{r-3} is embedded into cluster C . Take an arbitrary cluster $G \in N_{G_r}(C)$ and r_1 will be embedded into cluster G . But first we start the construction of the star covering. It is similar to the well-distributed case, but for S_1 we take $M(S_1) \in N_{G_r}(G)$. We assign pieces $T_{1,j}$ from T_1 to S_1 as in the well-distributed case. If we have leftover pieces in T_1 , then we move on to constructing S_2 with $M(S_2) \in N_{G_r}(G)$. For this purpose we pick $M(S_2)$ as the cluster in $N_{G_r}(G)$ which covers the most clusters ($\geq \delta$ -portion) in $G_r \setminus L(S_1)$. Otherwise, if we assigned all the pieces of T_1 to S_1 , then we move to T_2 . If the father of r_2 is embedded into a cluster C' , then r_2 will be embedded into a cluster $G' \in N_{G_r}(C') \cap N_{G_r}(M(S_1))$. Then we start assigning pieces from T_2 to S_1 . If we have leftover pieces in T_2 , then we construct S_2 with $M(S_2) \in N_{G_r}(G')$. We continue in this fashion. This procedure guarantees that, if r_i is embedded into a cluster G'' and a piece of T_i is assigned to star S_j , then we have $(G'', M(S_j)) \in E(G_r)$. The leaf children of a

root r_i on level V_{r-1} are embedded into the neighbour cluster of G'' in G_r with the fewest vertices embedded into it so far. By (4.22) the total number of these leaves is very small ($\leq \gamma$ -portion) compared to the number of buffer vertices; therefore they are not causing any significant discrepancies among the number of embedded vertices in the clusters. For the embedding of the part of T below V_r , we follow the same simple greedy strategy as in the upper half. There are no further difficulties; we can follow the same steps as in the well-distributed case.

Case 2: r is small, $r \leq \frac{1}{\gamma^2}$ (for simplicity we assume that $\frac{1}{\gamma^2}$ is an integer).

We may assume that $|V_{r-1}| \geq \gamma|V_r|$; otherwise Case 1 holds. Similarly we may assume that $|V_{r-2}| \geq \gamma|V_{r-1}|$, since otherwise we have

$$|V_{r-1}| \geq \gamma^2 n \quad \text{but} \quad |V_{r-2}| < \gamma|V_{r-1}|;$$

the situation is similar to Case 1. Iterating this we get

$$c \frac{n}{\log n} \geq |V_1| \geq \gamma^r n \geq \gamma^{\frac{1}{\gamma^2}} n,$$

a contradiction if n is sufficiently large.

Case 3: $r > \frac{1}{\gamma^2}$.

Consider the levels between V_r and $V_{r-\frac{1}{\gamma^2}}$, and let V_s denote the level with the smallest number of leaves ($\leq \gamma^2 n$) in it. Take the non-leaf vertices on V_{s-1} , and the subtrees of T below them between levels V_{s-1} and V_r (including V_r). These subtrees (denoted by T'_1, T'_2, \dots) provide a partition of the region between V_{s-1} and V_r . If for one of these subtrees T'_i we have

$$|T'_i| \geq \gamma^2 n,$$

then the proof is similar to Case 2. Therefore we may assume that

$$|T'_i| < \gamma^2 n \tag{4.23}$$

for every subtree.

For the embedding of the part of T above V_{s-1} , we follow the same greedy strategy as in Case 1. For the region between V_{s-1} and V_r we do the following. First of all, the T_i s again consist of the leaves on level V_r , their parents and their grandparents. We take the first subtree T'_1 in this region. We embed the leaves in T'_1 at one level (except for the leaves on level V_s) into the cluster with the smallest number of vertices embedded into it so far. This is done by going upward (with the assignment procedure, and then downward with the actual embedding) in T'_1 starting with the leaves on level V_{r-1} and following the same procedure as in the well-distributed case. We keep going until V_s ; we embed the root of T'_1 so we can connect the embedding of T'_1 and the part of T above V_s . Then the leaves on level V_s are evenly distributed among the clusters where the embedded root has many neighbours.

We continue the procedure for the other T'_i s in this fashion. Relation (4.23), and the fact that on V_s there are $\leq \gamma^2 n$ leaves, implies that we again fill up the non-buffer zones in a balanced way, and there are no further complications in this case, thus completing the proof of Theorem 1.2.

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