



IMGD 5100:  
Immersive HCI

# Classifying 3D Input Devices

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# But First...

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- Who are you?
  - Name
  - Interests
  - Strengths
  - Would like to do a project on...
    - “I don’t know” is okay.

# Let's talk about the paper...

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# Motivation

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- The mouse and keyboard are good for general desktop UI tasks
  - Text entry, selection, drag and drop, scrolling, rubber banding, ...
  - Fixed computing environment
  - 2D mouse for 2D windows
  
- How can we design effective techniques for 3D?
  - Use a 2D device?
  - Use multiple  $n$ -D devices?
  - Use new devices?
  - Use 2D interface widgets?
  - Need new interaction techniques!

# Motivation (cont.)

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- Gaming and Virtual Reality
  - Tight coupling between *action* and *reaction*
  - Need for precision
- VR can give *real* first-person experiences, not just views
  - Head-mounted Display
    - In order to look behind you, turn your head!
  - Selecting/manipulating an object
    - Reach your hand out and grab it!
  - Travel
    - Just walk (well, not quite)!
- Doing things that have no physical analog is more problematic

# Common Input Devices

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Mouse



Keyboard



Joystick



TrackBall



TrackPoint



TrackPad



Tablet



MightyMouse



Multi-Touch  
TrackPad

# Game Controllers



Atari 2600  
(1977)



Intellivision  
(1980)



PlayStation2  
(2000)



Xbox 360  
(2005)



PlayStation3  
(2008)

# "Natural" Motion Controllers



WiiMote  
(2007)



Microsoft  
Kinect (2010?)



WiiMotionPlus  
(2009)

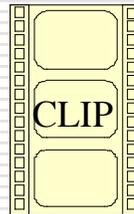


PlayStation  
Move (2010)

# Multi-Touch Surfaces

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- High resolution
- Co-located interaction



[http://www.ted.com/talks/jeff\\_han\\_demos\\_his\\_breakthrough\\_touchscreen.html](http://www.ted.com/talks/jeff_han_demos_his_breakthrough_touchscreen.html)

# Prototypes of Controllers



Nintendo "Revolution"  
Controller (prototype)



Nintendo Wii + Nunchuck  
(released)

# Prototypes of Controllers (cont.)

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PlayStation3 Controller  
(prototype)



PlayStation3 SIXAXIS  
(released)

# Hand-Held Devices

□ Becoming interesting!



Apple iPhone 4  
(2010)



Apple iPad  
(2010)



Motorola DROID  
(2009)



Nintendo DS Lite  
(2006)



Sony PlayStation  
Portable (2004)

# Classification Schemes

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- ❑ Relative vs. Absolute movement
- ❑ Integrated vs. Separable degrees of freedom
- ❑ Digital vs. Analog devices
- ❑ Isometric vs. Isotonic devices
- ❑ Rate control vs. Position control
- ❑ Special-purpose vs. General-purpose devices
- ❑ Direct vs. Indirect manipulation

# More on Classifications

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- Relative vs. Absolute movement
  - Mouse vs. Tablet
  
- Integrated vs. Separable degrees of freedom
  - Mouse has integrated X, Y control
  - Etch-a-sketch has separate X, Y control
    - Motions that are easy with one are hard with the other
  
- Analog devices allow more sensitivity
  - For example, analog game controllers

# Isometric vs. Isotonic Input Devices (Zhai)

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- No motion vs. No resistance
- Actually a continuum of elasticity
  - TrackPoint (mostly isometric) vs. mouse (mostly isotonic)
  - Many devices are re-centering (*e.g.*, joysticks)

# Rate Control vs. Position Control (Zhai)

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- Mouse is normally used for position control
- Mouse scroll-wheel
  - Position control
  - Click-drag for rate controlled scrolling
- Trackballs typically use position control
- Joysticks: Control position (cross-hair), or Control velocity (aircraft)
- Rate control eliminates need for clutching/ratcheting
- **Isotonic-rate control and isometric-position control tend to produce poor performance (Zhai)**

# Special-Purpose vs. General-Purpose Input Devices (Buxton)

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- Game controllers are designed to support many types of games
  - Game developer decides on mapping
  - No "standard" mappings -> each game different
  
- Some special-purpose devices exist
  - Light guns
  - Steering wheels
  - RPG keyboard/joystick
  - Drum kits, dance pads, bongos, *etc.*

# Direct vs. Indirect Manipulation

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## □ Direct

- Clutch and drag an icon with mouse or stylus
- Touch screens, PDAs use direct manipulation
- Works well for things that have a physical analog

## □ Indirect

- Use some widget to indirectly change something

## □ Problems with direct manipulation

- Some things do not have a physical analog
- Precision may be lacking
- Selection/de-selection may be messy

# 3D Input Devices



SpaceBall



SpaceMouse



CyberGlove II



HMD with  
3-DOF tracker



Tracked Paddle for 2D Interaction



PHANTOM Omni  
Haptic Device

# Motion-Capture/Tracking Systems

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- Used heavily in movies and TV
  - Capture actual motion, and re-use
  - Example, Fox Sports NFL guy
- Can be done interactively, or offline
- Can capture three or more (six) Degrees of Freedom (DoF)
  - Position, Orientation, or Both
- Many technical approaches
- No really good, general approaches

# Tracking Technologies

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- ❑ Mechanical
- ❑ Magnetic
- ❑ Ultrasonic
- ❑ Inertial
- ❑ Optical
- ❑ Time of flight
- ❑ Hybrid

# Mechanical Tracking

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- Rigid linkage, potentiometers at joints
- Pros:
  - High accuracy
  - High resolution
- Cons:
  - Limited range of motion
  - Cumbersome

# Magnetic Tracking

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- Transmitter creates a magnetic field
  - Transmitter is the origin
- Receivers are tracked using changes in magnetic field
- Pros:
  - Fairly lightweight
  - Six DoF
- Cons:
  - Very noisy near ferrous metal
  - Limited working range

# Ultrasonic Tracking

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- Transmitter sends pulses
- Receivers hear tones
- Distance is computed
- Can use "constellations" for orientation
- Pros:
  - High accuracy
  - High resolution
- Cons:
  - Requires line-of-sight (hearing)

# Inertial Tracking

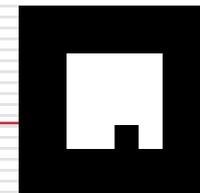
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- Accelerometers
  - Tilt
  - Acceleration
- Gyroscopes
  - Measure movement
- Pros:
  - Not anchored to a place in space
- Cons:
  - Accumulated error can cause drift
  - Only moderate accuracy

# Optical Tracking

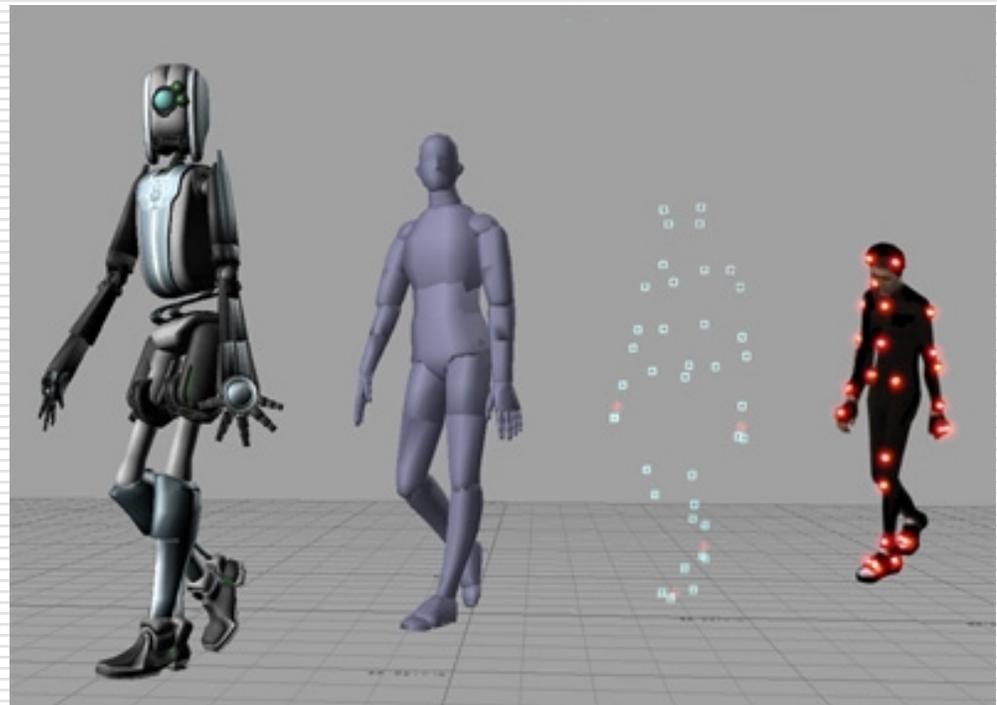
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- ❑ Multiple fixed cameras capture markers
- ❑ Known camera parameters (FOV, focal length, position, orientation)
- ❑ Use equations to compute position in 3-D space
- ❑ Markers can be simple points, or glyphs
- ❑ ARToolKit
  - <http://sourceforge.net/projects/artoolkit/>



# Optical Tracking (cont.)

## □ Active vs. Passive Markers



# Kinect

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- Structured light + sensor
- <http://www.youtube.com/watch?v=dTKINGSH9Po>

# Hybrid Tracking Techniques

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- Compensate negative characteristics of one approach with another
  - Inertial and Magnetic
  - Inertial and Optical
  - WiiMote+MotionPlus
  - PlayStation Move

# Other Options

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## □ Some alternatives

- Speech
- Gestures: pointing to fly
- Device actions (*e.g.*, buttons, joysticks)
- Head/gaze directed

## □ Hybrid

- Speech and gesture (*e.g.*, "Put that, there.")

# Special-Purpose Input Devices

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- Some applications are more "real" with a device that matches the real action
  - Steering wheel
  - Light gun
  - Flight-simulator motion platform
  - Snowboard/surfboard
  - Pod racer
  - Motor cycle
  
- Today, since sensors are cheap, we can turn almost *anything* into an input device

# Mapping Devices to Actions

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- For each (user, task, environment)
  - For the four basic VR tasks
    - For each device DOF
      - Choose a mapping to an action
  
- We also need to easily switch between actions!

# Placing Devices in Context

## □ Table?

Device	Rel/Abs	Int/Sep	Dig/Ana	Isom/Isot	Rate/Pos	Spec/Gen	Dir/Ind
Mouse	Relative	Integrated	Digital	Isotonic	Position	General	Both
Glove	Absolute	Integrated		Isotonic			
...							
...							
...							

# Verification and Comparison

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- Framework for user studies
- Interesting to fill in the empty spaces
  - Isotonic position control for rotation?
  - Other novel combinations?
- Very active field right now
  - ACM CHI, IEEE VR, 3DUI Symposium, ACM SIGGRAPH

# More Info

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- Shumin Zhai at Google, used to be at IBM Almaden, and U. of Toronto
- Bill Buxton at Microsoft Research, used to be at U. of Toronto, and Alias|Wavefront (now part of Autodesk)