

CS 543 - Computer Graphics: Polygonal Meshes

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(with help from Emmanuel Agu ;-)



3D Modeling

- We talked about basic geometric objects in GLUT
- □ Wireframe vs. solid models
- Composite objects using SDL file format

□ Basic objects

- Cylinder: glutWireCylinder(), glutSolidCylinder()
- Cone: glutWireCone(), glutSolidCone()
- Sphere: glutWireSphere(), glutSolidSphere()
- Cube: glutWireCube(), glutSolidCube()
- Newell Teapot
- Dodecahedron, Torus, *etc.*



Polygonal Meshes

- Modeling with basic shapes (cube, cylinder, sphere, etc.) is too primitive
- Difficult to approach realism
- Polygonal meshes
 - Collection of polygons, or faces, that form "skin" of object
 - Offer more flexibility
 - Model complex surfaces better
 - Examples
 - Human face
 - Animal structures
 - □ Arbitrary curves, *etc.*



Polygonal Meshes (cont.)

- □ Have become standard in CG
- □ OpenGL
 - Good at drawing polygons
 - Mesh = sequence of polygons
- □Simple meshes are exact (*e.g.*, barn)
- Complex meshes are approximate (e.g., human face)

□Later

Use shading technique to smoothen the appearance



Non-Solid Objects

- Examples: box, face
- □ Visualize as infinitely thin *skin*
- Meshes to approximate complex objects
- Shading used later to smoothen
- □ Non-trivial: creating mesh for complex objects (CAD)





What is a Polygonal Mesh?

Polygonal mesh defined by

- List of polygons
- Normal of each polygon
- Normal vectors used in shading
 - Normal & light vectors determine shading





Vertex Normals

- Use vertex normal instead of face normal
- See advantages later
 - Facilitates clipping / culling
 - Shading of smoothly curved shapes
 - Flat surfaces
 - All vertices associated with same n
 - Smoothly curved surfaces
 - \Box V₁, V₂ with common edge share **n**



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n



Defining a Polygonal Mesh

□ Barn example





Defining a Polygonal Mesh

□ Three lists:

- Vertex list
 - □ Distinct vertices (vertex number, $V_{x'}$, $V_{y'}$, V_z)
- Normal list
 - □ Normals to faces (normalized $n_{x'}$, $n_{y'}$, n_z)
- Face list
 - Indices into vertex and normal lists. *i.e.*, vertices and normals associated with each face

Face list convention

- Traverse vertices counter-clockwise
- Interior on left, exterior on right

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Newell Method for Normal Vectors

- Martin Newell at Utah
 - Yeah, the "teapot" guy
- Normal vector
 - Calculation is difficult by hand
 - Given formulae, it is suitable for the computer
 - Compute during mesh generation
- □ Simple approach used previously
 - Start with any three vertices V₁, V₂, V₃
 - Form two vectors, say V_1 - V_2 , V_3 - V_2
 - Normal = cross product (perpendicular) of vectors

Newell Method for Normal Vectors (cont.)



- If two vectors are almost parallel, cross product is small
- Numerical inaccuracy may result
- Newell method is more robust
- Formulae: Normal N = (m_x, m_y, m_z)

$$m_{x} = \sum_{i=0}^{N-1} (y_{i} - y_{next(i)})(z_{i} + z_{next(i)})$$
$$m_{y} = \sum_{i=0}^{N-1} (z_{i} - z_{next(i)})(x_{i} + x_{next(i)})$$
$$m_{z} = \sum_{i=0}^{N-1} (x_{i} - x_{next(i)})(y_{i} + y_{next(i)})$$



Newell Method Example

Example: Find normal of polygon with vertices

$$P_0 = (6,1,4), P_1 = (7,0,9) \text{ and } P_2 = (1,1,2)$$

Solution: Using simple cross product: ((7,0,9)-(6,1,4)) X ((1,1,2)-(6,1,4)) = (2,-23,-5)

Using Newell method, plug in values, result is the same:

Normal is (2, -23, -5)



Meshes in Programs

- □ Class *Mesh*
- Helper classes
 - VertexID
 - Face
- Mesh Object
 - Normal list
 - Vertex list
 - Face list
- □ Use arrays of pt, norm, face
- Dynamic allocation at runtime
- □ Array lengths
 - numVerts, numNormals, numFaces



□ Face

- Vertex list
- Normal vector associated with each face
- Array of index pairs (vertex, normal)
- Example, vth vertex of fth face: Position: pt[face[f].vert[v].vertIndex]
 - Normal vector:
 - norm[face[f].vert[v].normIndex]
- Organized approach, permits random access



Tetrahedron example





```
Data structures
```

```
// Vertex ID
```

```
class VertexID {
```

public:

```
int vertIndex; // index of this vertex in the vertex list
int normIndex; // index of this vertex's normal
```

};

};

// Face

```
class Face {
```

public:

```
int nVerts; // number of vertices in this face
VertexID *vert; // the list of vertex and normal indices
Face() { nVerts = 0; vert = NULL; }; // constructor
~Face() { nVerts = 0; delete[] vert; }; // destructor
```



// Mesh
class Mesh {
private:
int numVerts; // number of vertices in the mesh
Point3 *pt; // array of 3D vertices
int numNormals; // number of normal vertices for the mesh
Vector3 *norm; // array of normals
int numFaces; // number of faces in the mesh
Face *face; // array of face data
<pre>// others to be added later</pre>
public:
Mesh(); // constructor
<pre>~Mesh(); // destructor</pre>
int readFile(char *fileName); // to read in mesh file.
// other methods

Drawing Meshes Using OpenGL

Pseudo-code

```
for( each face f in Mesh ) {
```

```
glBegin( GL_POLYGON );
```

```
for( each vertex v in face f ) {
```

```
glNormal3f( normal at vertex v );
```

```
glVertex3f( position of vertex v );
```

glEnd();

Drawing Meshes Using OpenGL (cont.)



□ Actual code

```
void Mesh::draw( void ) { // use openGL to draw this mesh
for( int f = 0; f < numFaces; f++ ) {
  glBegin( GL_POLYGON );
  // for each vertex of this polygon
  for( int v = 0; v < face[f].nVerts; v++ ) {
    // index of the normal for this vertex
    int in = face[f].vert[v].normIndex;
    glNormal3f( norm[in].x, norm[in].y, norm[in].z );
    // index of this vertex
    int iv = face[f].vert[v].vertIndex;
    glVertex3f( pt[iv].x, pt[iv].y, pt[iv].z );
    }
    glEnd( );
}
```



Drawing Meshes Using SDL

- □ Scene class reads SDL files
- Accepts keyword mesh
- Example
 - Pawn stored in mesh file "pawn.3vn"
 - Add line
 - push translate 3 5 4 scale 3 3 3 mesh pawn.3vn pop



More on Meshes

- Simple meshes are easy to create by hand
- Complex meshes
 Mathematical functions

 - Algorithms
 - Digitize real objects
- Libraries of meshes available
- Mesh trends
 - 3D scanning
 - Mesh Simplification



3D Simplification Example





References

□Hill: 6.1-6.2