

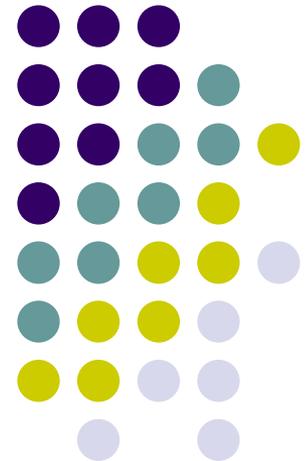
Computer Graphics

CS 543 Lecture 13 (Part 1)

Curves

Prof Emmanuel Agu

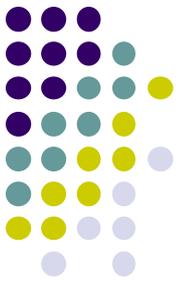
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So Far...

- Dealt with straight lines and flat surfaces
- Real world objects include curves
- Need to develop:
 - Representations of curves
 - Tools to render curves



Curve Representation: Explicit

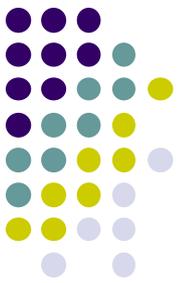
- One variable expressed in terms of another
- Example:

$$z = f(x, y)$$

- Works if one x-value for each y value
- Example: does not work for a sphere

$$z = \sqrt{x^2 + y^2}$$

- Rarely used in CG because of this limitation



Curve Representation: Implicit

- Represent 2D curve or 3D surface as zeros of a formula
- Example: sphere representation

$$x^2 + y^2 + z^2 - 1 = 0$$

- May limit classes of functions used
- Polynomial: function which can be expressed as linear combination of integer powers of x , y , z
- Degree of algebraic function: highest power in function
- Example: mx^4 has degree of 4



Curve Representation: Parametric

- Represent 2D curve as 2 functions, 1 parameter

$$(x(u), y(u))$$

- 3D surface as 3 functions, 2 parameters

$$(x(u, v), y(u, v), z(u, v))$$

- Example: parametric sphere

$$x(\theta, \phi) = \cos \phi \cos \theta$$

$$y(\theta, \phi) = \cos \phi \sin \theta$$

$$z(\theta, \phi) = \sin \phi$$



Choosing Representations

- Different representation suitable for different applications
- Implicit representations good for:
 - Computing ray intersection with surface
 - Determining if point is inside/outside a surface
- Parametric representation good for:
 - Dividing surface into small polygonal elements for rendering
 - Subdivide into smaller patches
- Sometimes possible to convert one representation into another

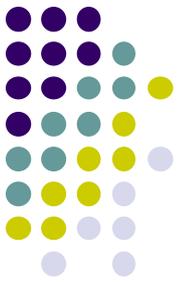
Continuity



- Consider parametric curve

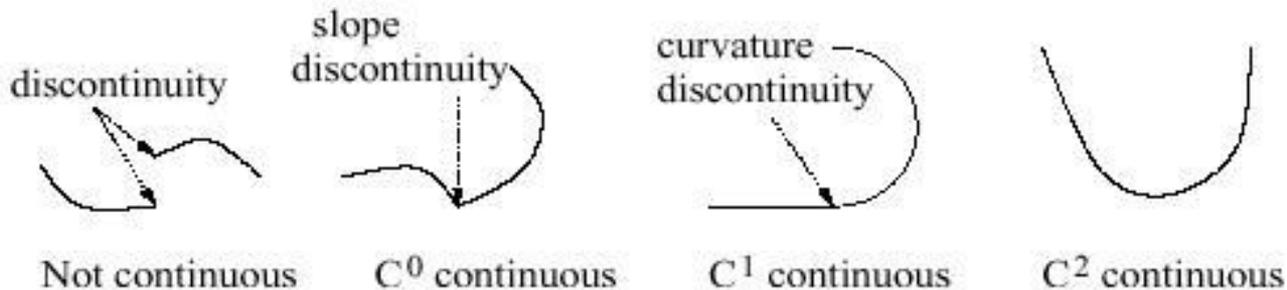
$$P(u) = (x(u), y(u), z(u))^T$$

- We would like smoothest curves possible
- Mathematically express smoothness as continuity (no jumps)
- **Defn:** if k th derivatives exist, and are continuous, curve has k th order parametric continuity denoted C^k



Continuity

- 0th order means curve is continuous
- 1st order means curve tangent vectors vary continuously, etc





Interactive Curve Design

- Mathematical formula unsuitable for designers
- Prefer to interactively give sequence of points (control points)
- Write procedure:
 - **Input:** sequence of points
 - **Output:** parametric representation of curve

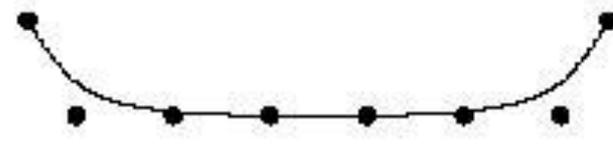


Interactive Curve Design

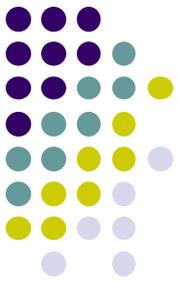
- 1 approach: curves pass through control points (interpolate)
- **Example:** Lagrangian Interpolating Polynomial
- Difficulty with this approach:
 - Polynomials always have “wiggles”
 - For straight lines wiggling is a problem
- Our approach: approximate control points (Bezier, B-Splines) called **De Casteljau’s algorithm**



Interpolation



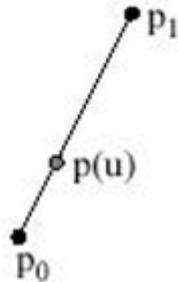
Approximation



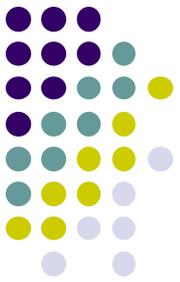
De Casteljau Algorithm

- Consider smooth curve that approximates sequence of control points $[p_0, p_1, \dots]$

$$p(u) = (1-u)p_0 + up_1 \quad 0 \leq u \leq 1$$



- Blending functions: u and $(1-u)$ are non-negative and sum to one

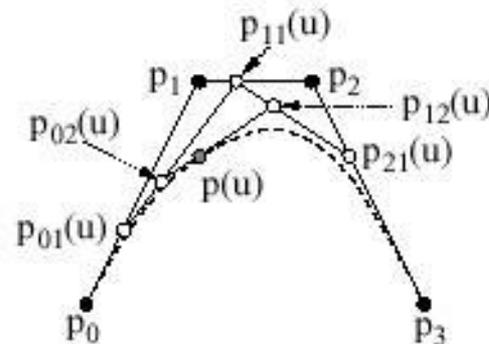
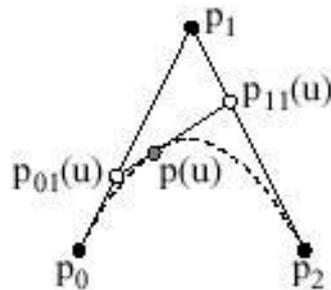
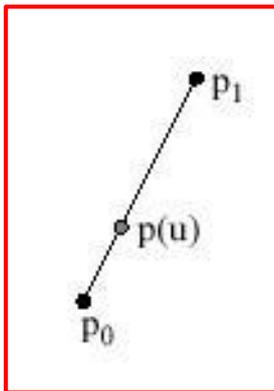


De Casteljau Algorithm

- Now consider 3 points
- 2 line segments, P0 to P1 and P1 to P2

$$p_{01}(u) = (1-u)p_0 + up_1$$

$$p_{11}(u) = (1-u)p_1 + up_2$$





De Casteljau Algorithm

Substituting known values of $p_{01}(u)$ and $p_{11}(u)$

$$\begin{aligned} p(u) &= (1-u)p_{01} + up_{11}(u) \\ &= (1-u)^2 \boxed{p_0} + (2u(1-u)) \boxed{p_1} + u^2 \boxed{p_2} \end{aligned}$$

$b_{02}(u)$ $b_{12}(u)$ $b_{22}(u)$

Red arrows point from the labels $b_{02}(u)$, $b_{12}(u)$, and $b_{22}(u)$ to the corresponding terms in the equation above.

Blending functions for degree 2 Bezier curve

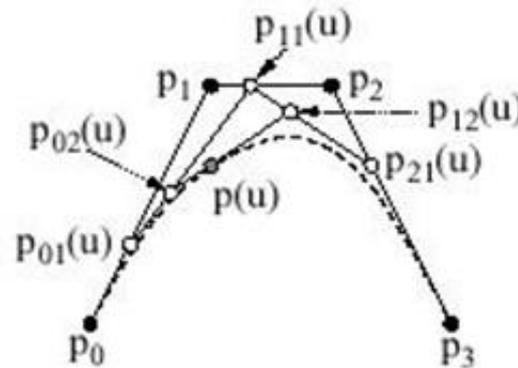
$$b_{02}(u) = (1-u)^2 \quad b_{12}(u) = 2u(1-u) \quad b_{22}(u) = u^2$$

Note: blending functions, non-negative, sum to 1



De Casteljau Algorithm

- Extend to 4 control points P_0, P_1, P_2, P_3



$$p(u) = (1-u)^3 \boxed{p_0} + (3u(1-u)^2) \boxed{p_1} + (3u^2(1-u)) \boxed{p_2} + u^3$$

$b_{03}(u)$ $b_{13}(u)$ $b_{23}(u)$ $b_{33}(u)$

- Final result above is Bezier curve of degree 3



De Casteljau Algorithm

$$p(u) = (1-u)^3 \boxed{p_0} + (3u(1-u)^2) \boxed{p_1} + (3u^2(1-u)) \boxed{p_2} + u^3$$

$b_{03}(u)$ $b_{13}(u)$ $b_{23}(u)$ $b_{33}(u)$

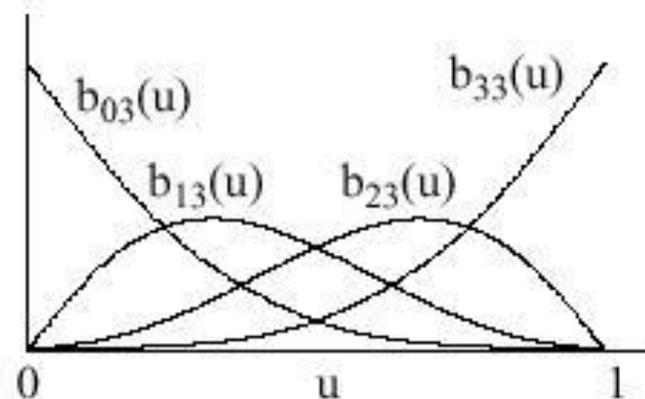
- Blending functions are polynomial functions called **Bernstein's polynomials**

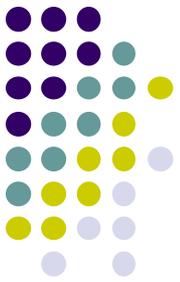
$$b_{03}(u) = (1-u)^3$$

$$b_{13}(u) = 3u(1-u)^2$$

$$b_{23}(u) = 3u^2(1-u)$$

$$b_{33}(u) = u^3$$





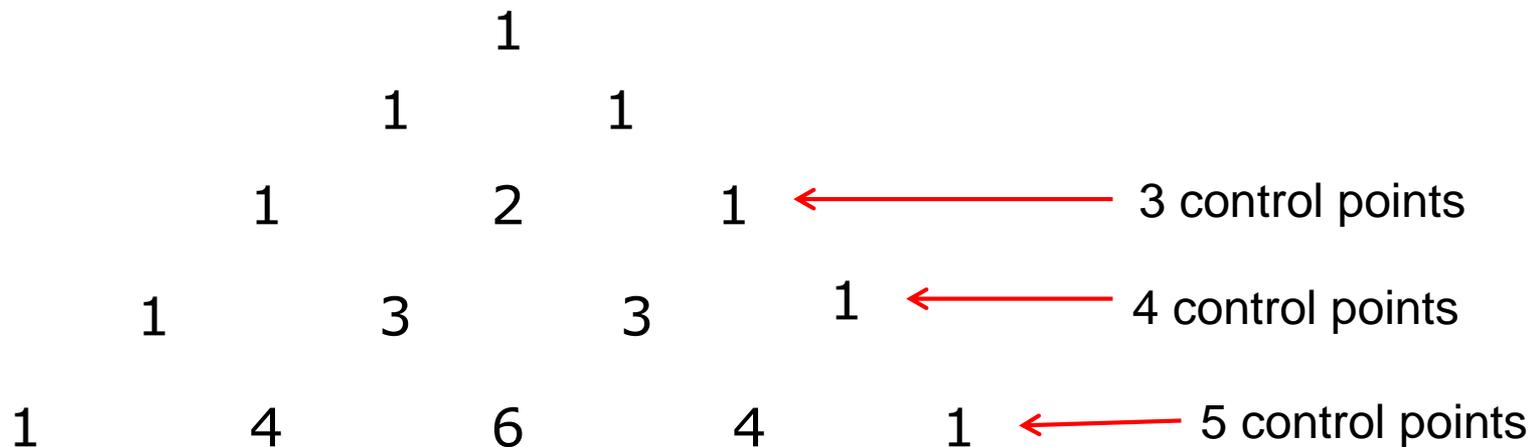
De Casteljau Algorithm

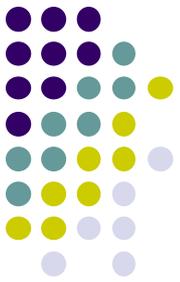
$$p(u) = (1-u)^3 p_0 + (3u(1-u)^2) p_1 + (3u^2(1-u)) p_2 + u^3$$

1 3 3 1

(Note: In the original image, the coefficients 1, 3, 3, 1 are indicated by red arrows pointing to the terms in the equation above. The terms p_0 , p_1 , and p_2 are enclosed in red boxes.)

- Writing coefficient of blending functions gives Pascal's triangle





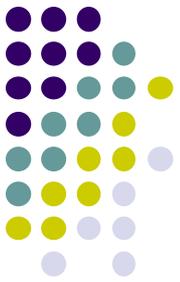
De Casteljau Algorithm

- In general, blending function for k Bezier curve has form

$$b_{ik}(u) = \binom{k}{i} (1-u)^{k-i} u^i$$

- Example

$$b_{03}(u) = \binom{3}{0} (1-u)^{3-0} u^0 = (1-u)^3$$



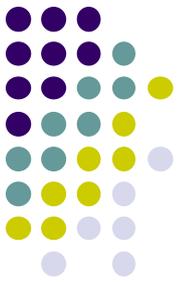
De Casteljau Algorithm

- Can express cubic parametric curve in matrix form

$$p(u) = [1, u, u^2, u^3] M_B \begin{bmatrix} p_0 \\ p_1 \\ p_2 \\ p_3 \end{bmatrix}$$

where

$$M_B = \begin{bmatrix} 1 & 0 & 0 & 0 \\ -3 & 3 & 0 & 0 \\ 3 & -6 & 3 & 0 \\ -1 & 3 & -3 & 1 \end{bmatrix}$$



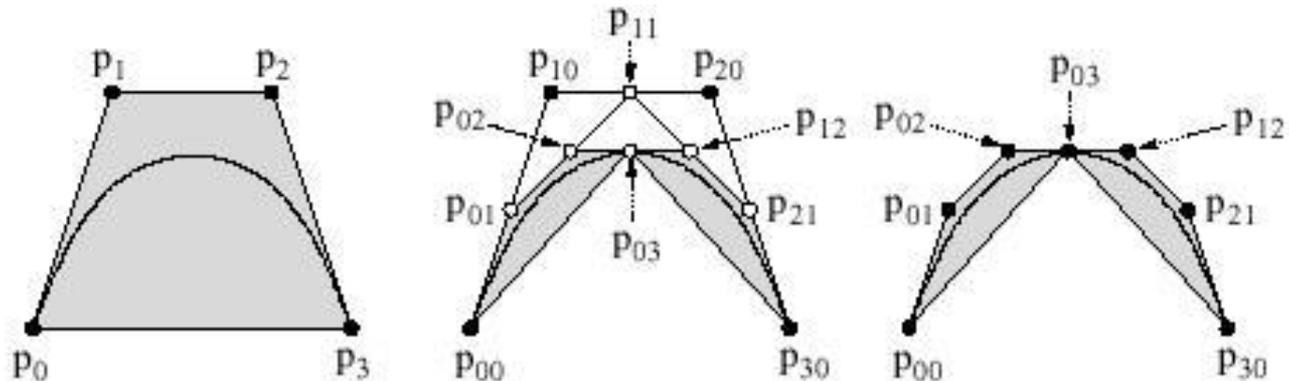
Subdividing Bezier Curves

- OpenGL renders flat objects
- To render curves, approximate with small linear segments
- Subdivide surface to polygonal patches
- Bezier curves useful for elegant, recursive subdivision



Subdividing Bezier Curves

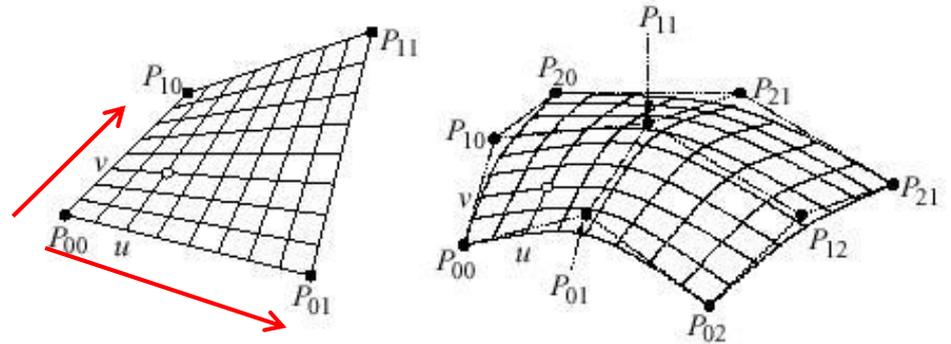
- Let $(P_0 \dots P_3)$ denote original sequence of control points
- Recursively interpolate with $u = \frac{1}{2}$ as below
- Sequences $(P_{00}, P_{01}, P_{02}, P_{03})$ and $(P_{03}, P_{12}, P_{21}, P_{30})$ define Bezier curves also
- Bezier Curves can either be straightened or curved recursively in this way



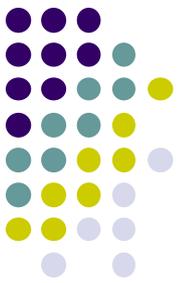


Bezier Surfaces

- Bezier surfaces: interpolate in two dimensions
- This called Bilinear interpolation
- Example: 4 control points, P_{00} , P_{01} , P_{10} , P_{11} , 2 parameters u and v
- Interpolate between
 - P_{00} and P_{01} using u
 - P_{10} and P_{11} using u
 - P_{00} and P_{10} using v
 - P_{01} and P_{11} using v



$$p(u, v) = (1 - v)((1 - u)p_{00} + up_{01}) + v((1 - u)p_{10} + up_{11})$$



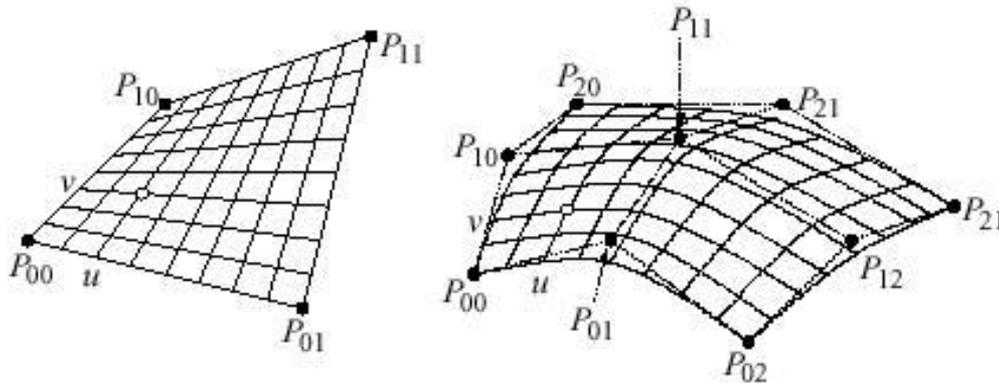
Bezier Surfaces

- Expressing in terms of blending functions

$$p(u, v) = b_{01}(v)b_{01}(u)p_{00} + b_{01}(v)b_{11}b_{01}(u)p_{01} + b_{11}(v)b_{11}(u)p_{11}$$

Generalizing

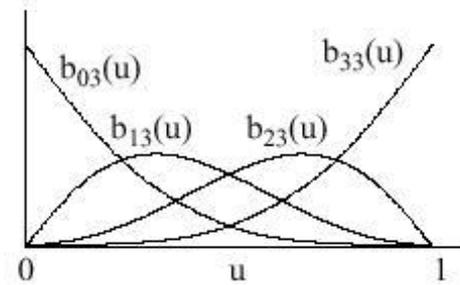
$$p(u, v) = \sum_{i=0}^3 \sum_{j=0}^3 b_{i,3}(v)b_{j,3}(u)p_{i,j}$$





Problems with Bezier Curves

- Bezier curves are elegant but too many control points
- To achieve smoother curve
 - = more control points
 - = higher order polynomial
 - = more calculations
- **Global support problem:** All blending functions are non-zero for all values of u
- All control points contribute to all parts of the curve
- Means after modelling complex surface (e.g. a ship), if one control point is moves, recalculate everything!

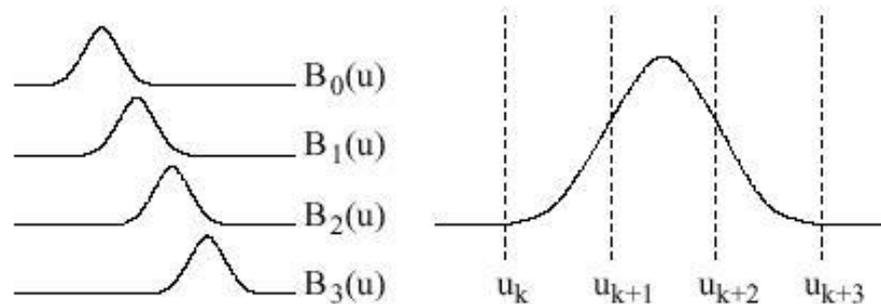




B-Splines

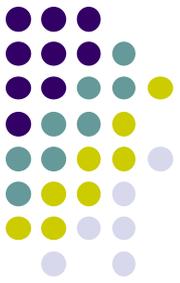
- B-splines designed to address Bezier shortcomings
- B-Spline given by blending control points
- **Local support:** Each spline contributes in limited range
- Only non-zero splines contribute in a given range of u

$$p(u) = \sum_{i=0}^m B_i(u) p_i$$



B-spline blending functions, order 2

NURBS



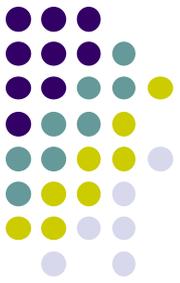
- Encompasses both Bezier curves/surfaces and B-splines
- Non-uniform Rational B-splines (NURBS)
- Rational function is ratio of two polynomials
- Some curves can be expressed as rational functions but not as simple polynomials
- No known exact polynomial for circle
- Rational parametrization of unit circle on xy-plane:

$$x(u) = \frac{1 - u^2}{1 + u^2}$$

$$y(u) = \frac{2u}{1 + u^2}$$

$$z(u) = 0$$

NURBS



- We can apply homogeneous coordinates to bring in w

$$x(u) = 1 - u^2$$

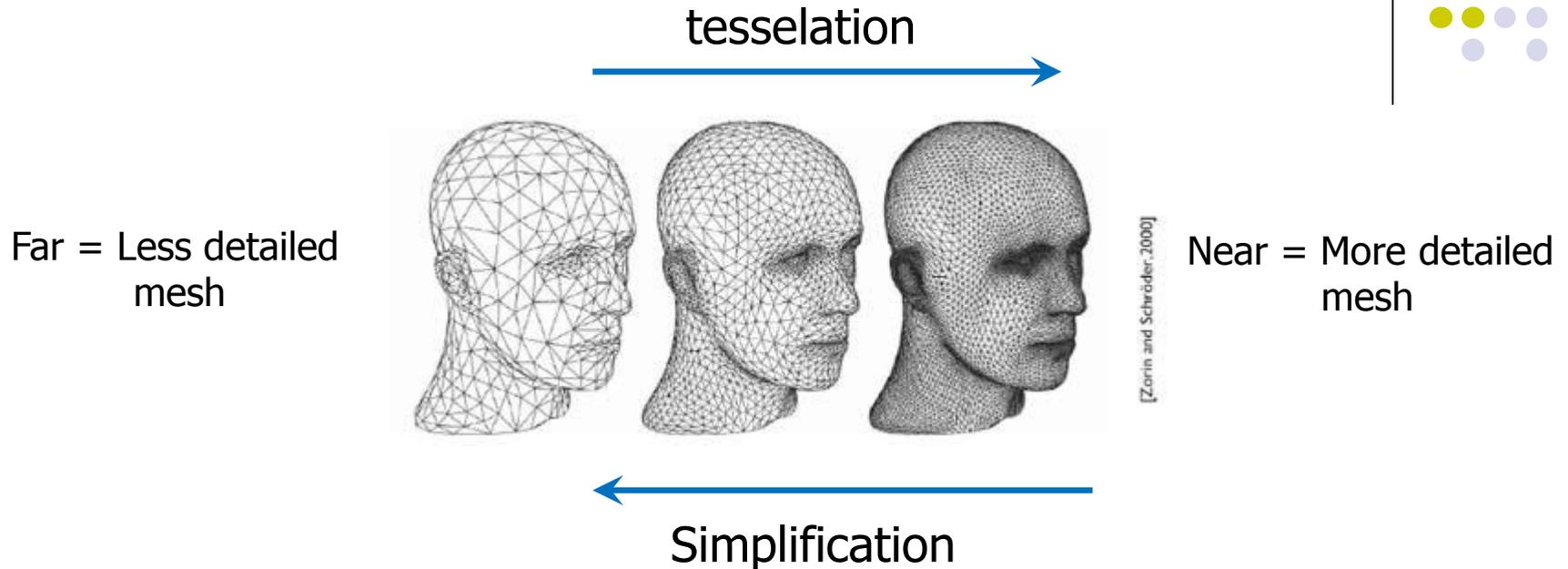
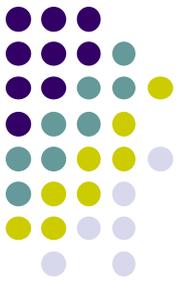
$$y(u) = 2u$$

$$z(u) = 0$$

$$w(u) = 1 + u^2$$

- Useful property of NURBS: preserved under transformation
 - E.g. Rotate sphere defined as NURBS, still a sphere

Tessellation



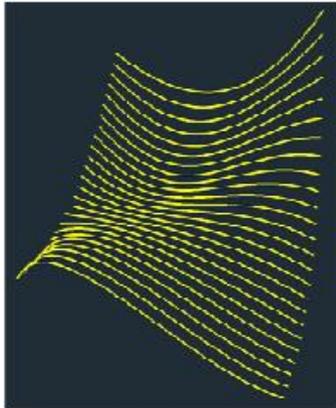
- **Previously:** Pre-generate mesh versions offline
- Tessellation shader unit new to GPU in DirectX 10 (2007)
 - Subdivide faces to yield finer detail, generate new vertices, primitives
- Mesh simplification/tessellation on GPU = Real time LoD
- Tessellation: [Demo](#)

Tessellation Shaders

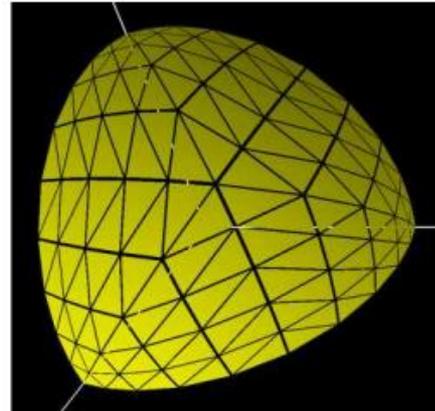


- Can subdivide curves, surfaces on the GPU

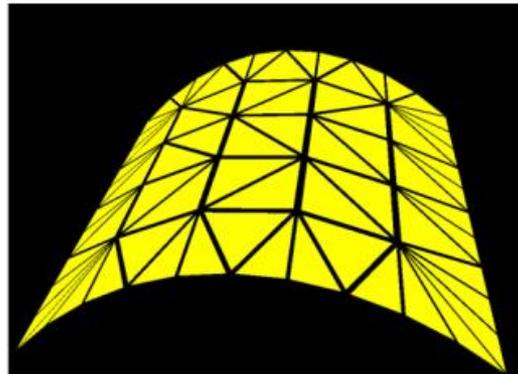
Lines



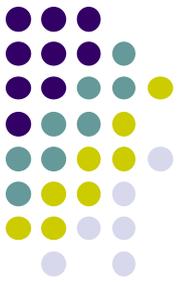
Triangles



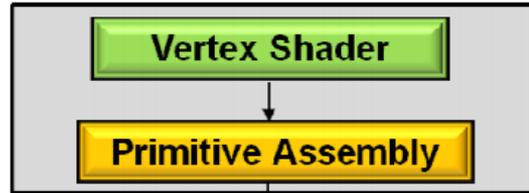
Quads (subsequently broken into triangles)



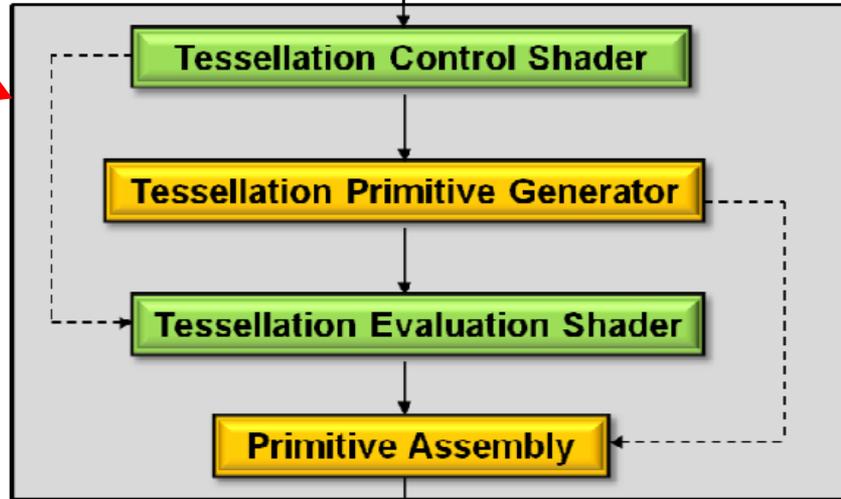
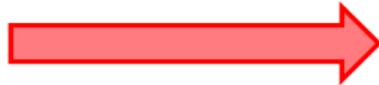
Where Does Tessellation Shader Fit?



Fixed number of vertices in/out



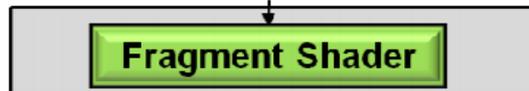
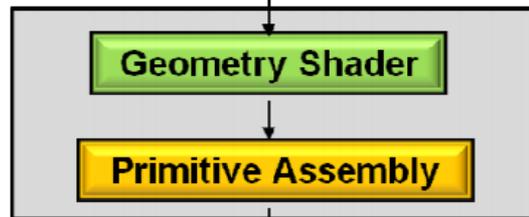
Can change number of vertices



= Fixed Function



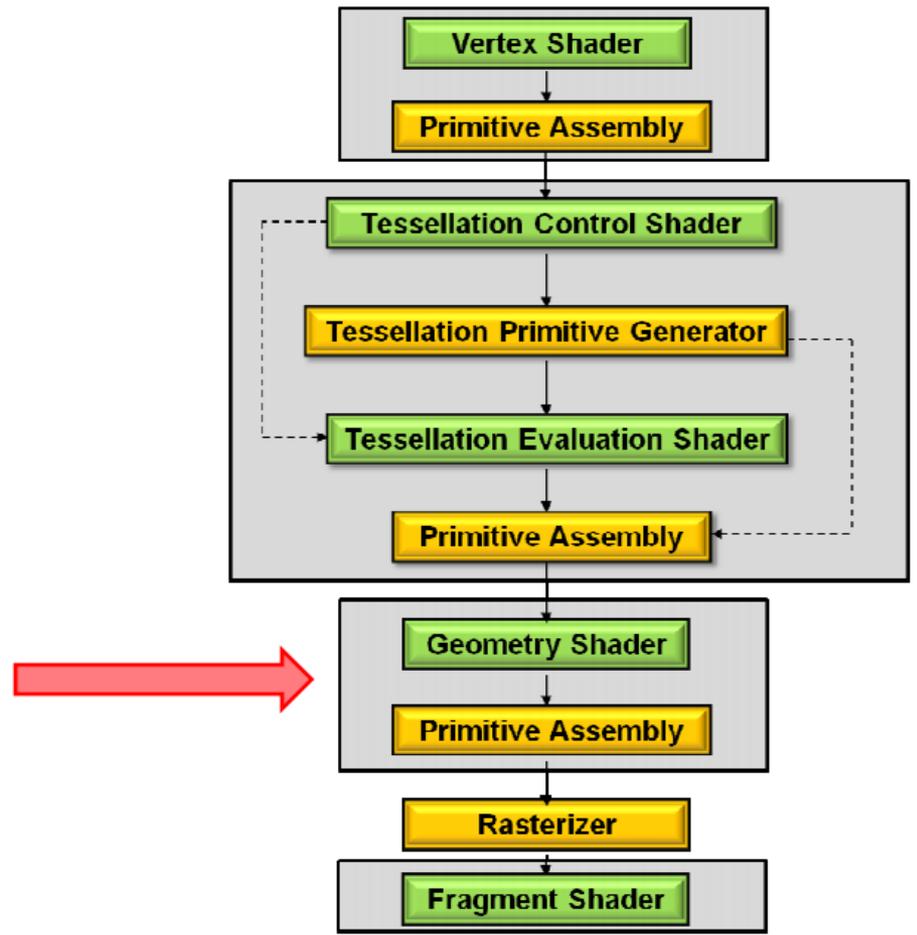
= Programmable





Geometry Shader

- After Tessellation shader. Can
 - Handle whole primitives
 - Generate **new primitives**
 - Generate no primitives (cull)





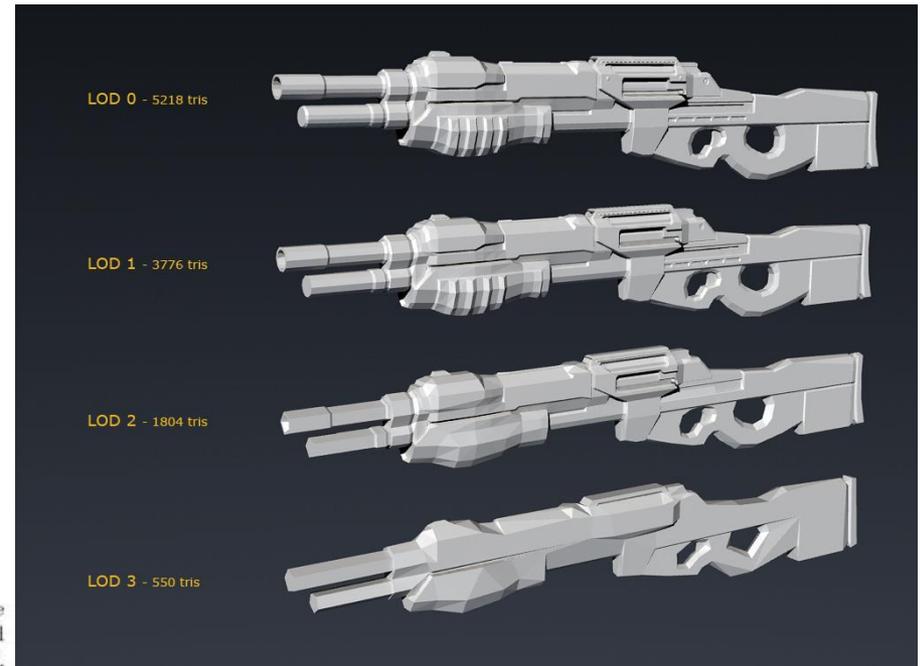
Level of Detail

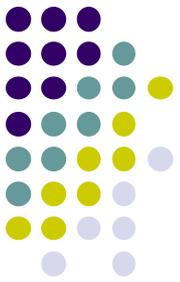
- Use simpler versions of objects if they make smaller contributions to the image
- LOD algorithms have three parts:
 - Generation: Models of different details are generated
 - Selection: Chooses which model should be used depending on criteria
 - Switching: Changing from one model to another
- Can be used for models, textures, shading and more

Level of Detail



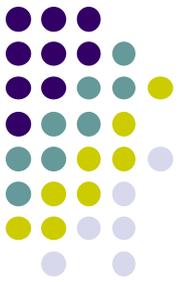
Figure 14.21. On the left, the original model consists of 1.5 million triangles. On the right, the model has 1100 triangles, with surface details stored as heightfield textures and rendered using relief mapping. (Image courtesy of Natalya Tatarchuk, ATI Research, Inc.)





LOD Switching

- Discrete Geometry LODs
 - LOD is switched suddenly from one frame to the next
- Blend LODs
 - Two LODs are blended together over time
 - New LOD is faded by increasing alpha value from 0 to 1
 - More expensive than rendering one LOD
 - Faded LODs are drawn last to avoid distant objects drawing over the faded LOD



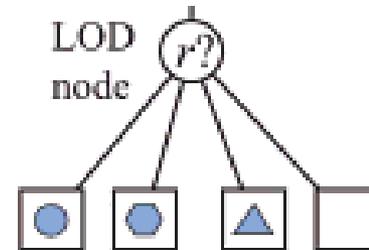
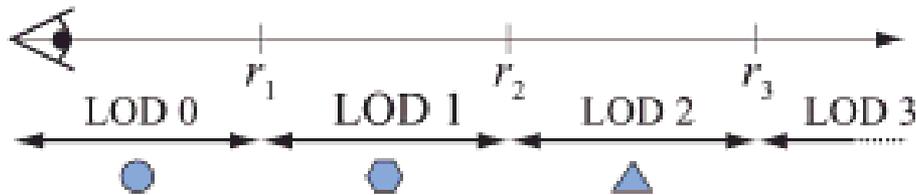
LOD Switching (cont.)

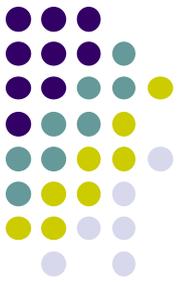
- Alpha LOD
 - Alpha value of object is lowered as distance increases
 - Experience is more continuous
 - Performance is only felt when object disappears
 - Requires sorting of scene based on transparency



LOD Selection

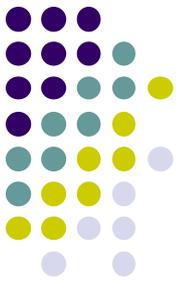
- Determining which LOD to render and which to blend
- Range-Based:
 - LOD choice based on distance





Time-Critical LOD Rendering

- Using LOD to ensure constant frame rates
- Predictive algorithm
 - Selects the LOD based on which objects are visible
- Heuristics:
 - Maximize $\sum_s \text{Benefit}(O, L)$
 - Constraint: $\sum_s \text{Cost}(O, L) \leq \text{TargetFrameTime}.$



References

- Hill and Kelley, chapter 11
- Angel and Shreiner, Interactive Computer Graphics, 6th edition, Chapter 10
- Shreiner, OpenGL Programming Guide, 8th edition