

# Computer Graphics (CS 543)

## Lecture 10: Soft Shadows (Maps and Volumes), Normal and Bump Mapping

Prof Emmanuel Agu

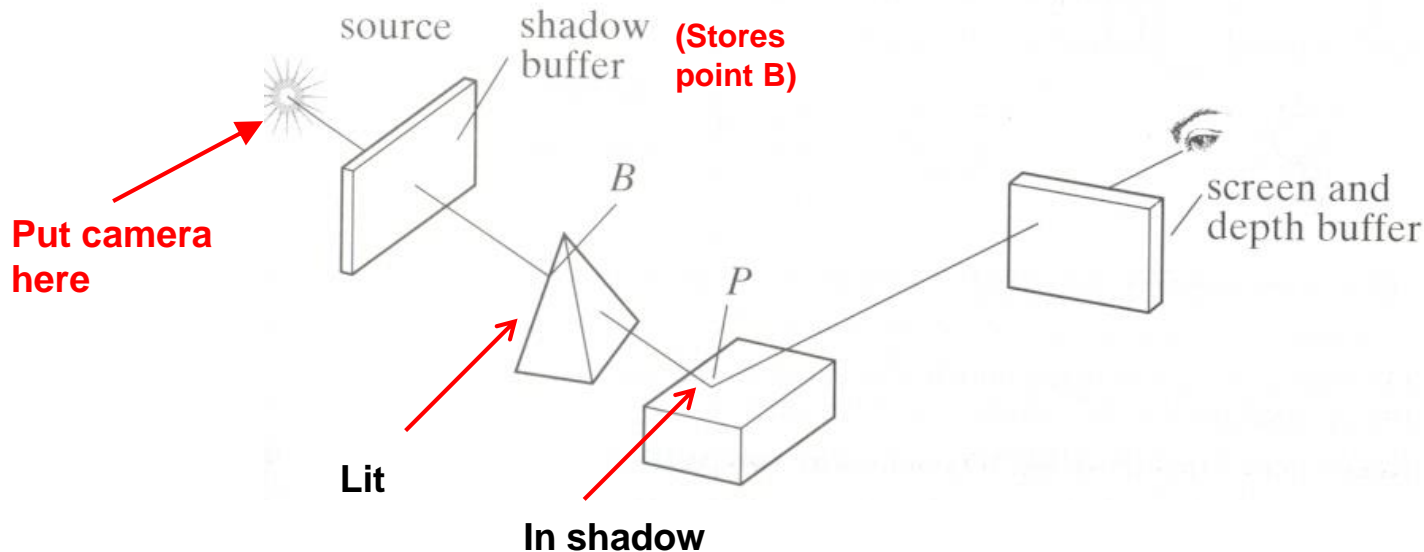
*Computer Science Dept.  
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# Shadow Buffer Theory

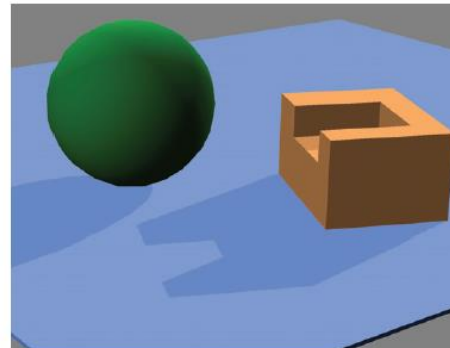
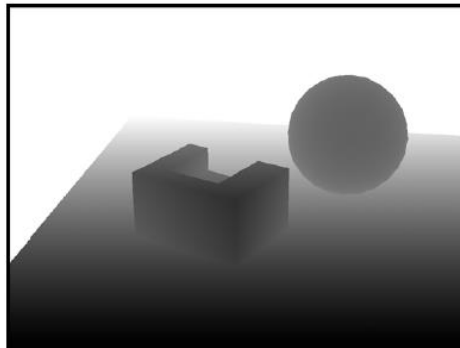
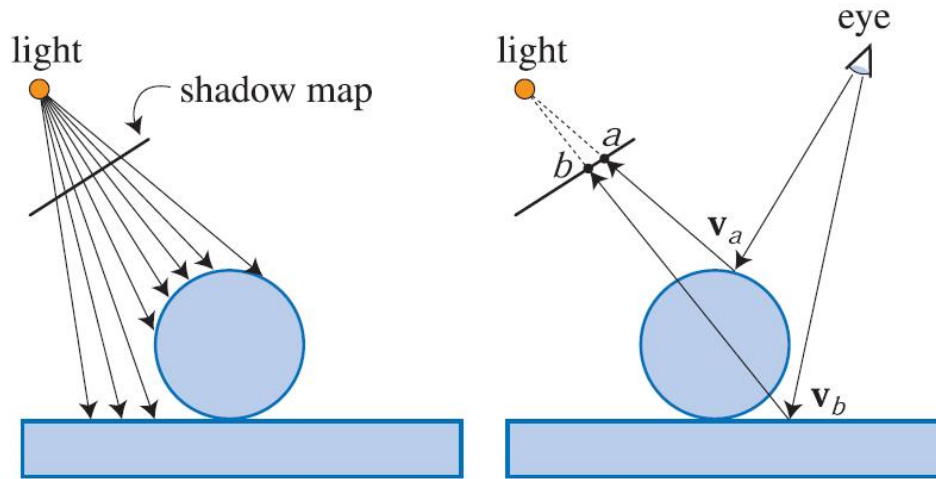
- **Observation:** Along each path from light
  - Only closest object is lit
  - Other objects on that path in shadow
- Shadow Buffer Method
  - Position a camera at light source.
  - uses second depth buffer called the **shadow map**
  - Shadow buffer stores closest object on each path





# Shadow Map Illustrated

- Point  $v_a$  stored in element  $a$  of shadow map: lit!
- Point  $v_b$  **NOT** in element  $b$  of shadow map: In shadow

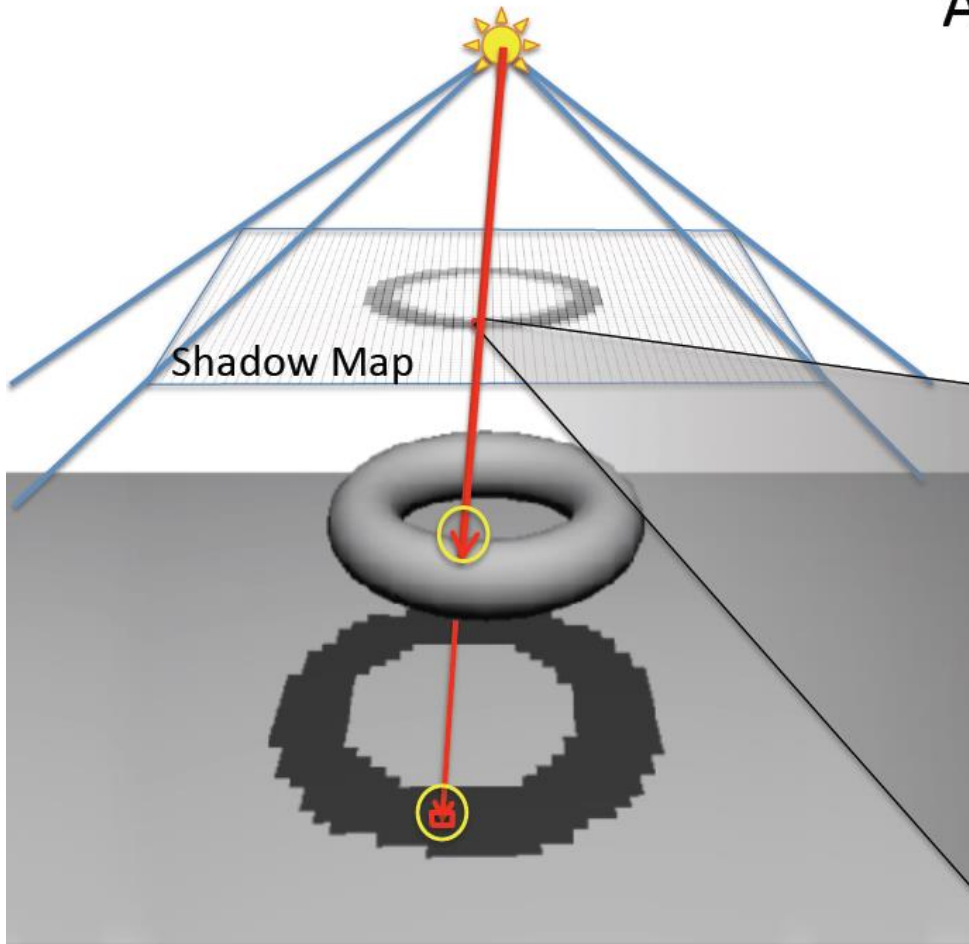


Not limited to planes



# Shadow Map: Depth Comparison

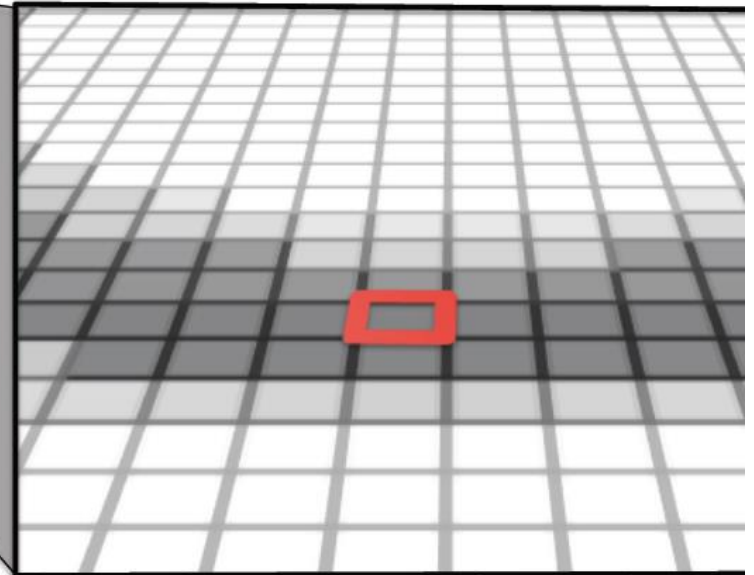
Render depth image from light



Shadow Map

Camera's view

A fragment is in shadow if its depth is greater than the corresponding depth value in the shadow map

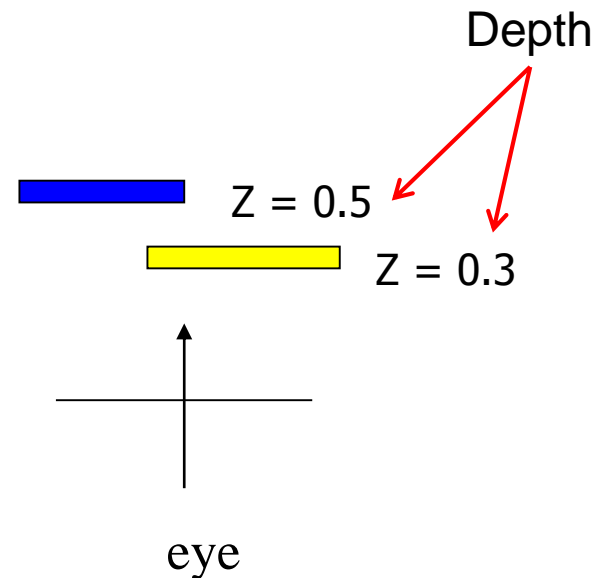




## Recall: OpenGL Depth Buffer (Z Buffer)

- **Depth:** While drawing objects, depth buffer stores distance of each polygon from viewer
- **Why?** If multiple polygons overlap a pixel, only closest one is drawn

1.0	1.0	1.0	1.0
1.0	0.3	0.3	1.0
0.5	0.3	0.3	1.0
0.5	0.5	1.0	1.0





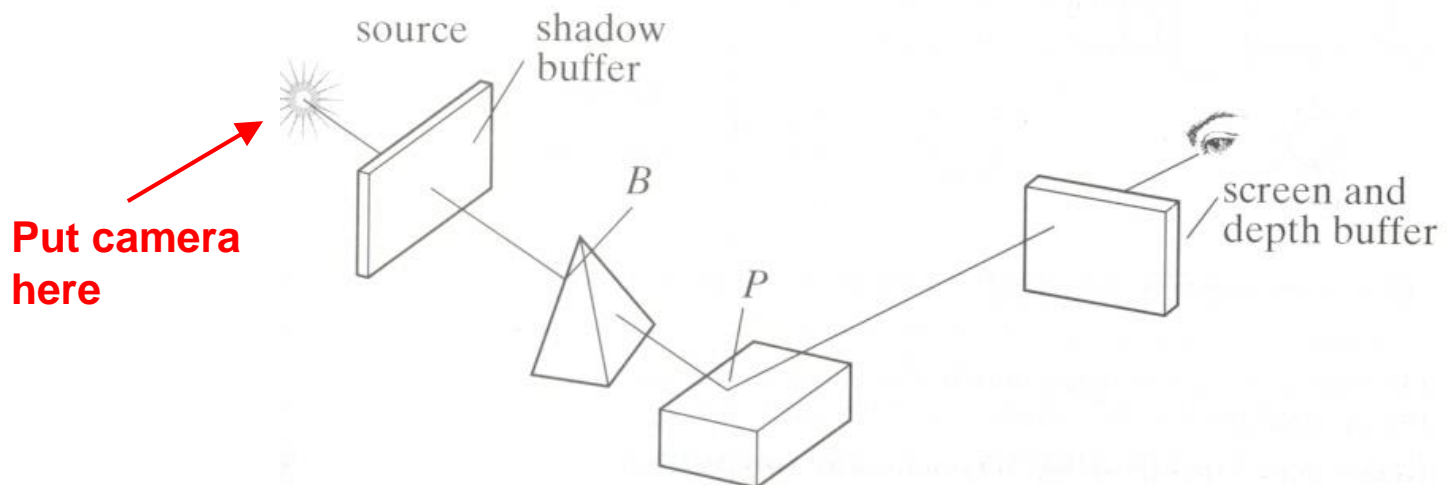
# Shadow Map Approach

- Rendering in two stages:
  - Generate/load shadow Map
  - Render the scene



# Loading Shadow Map

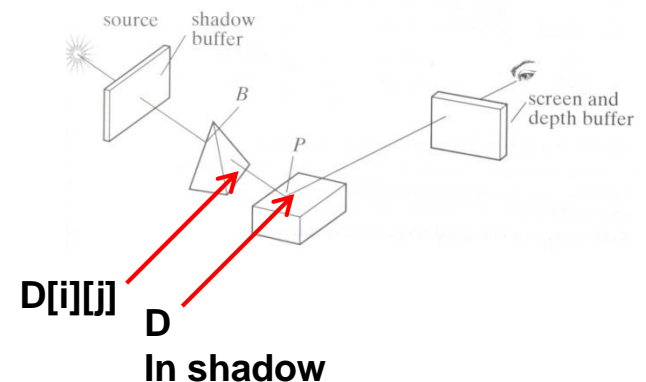
- Initialize each element to 1.0
- Position a camera at light source
- Rasterize each face in scene updating closest object
- Shadow map (buffer) tracks smallest depth on each path





# Shadow Map (Rendering Scene)

- Render scene using camera as usual
- While rendering a pixel find:
  - pseudo-depth  $D$  from light source to  $P$
  - Index location  $[i][j]$  in shadow buffer, to be tested
  - Value  $d[i][j]$  stored in shadow buffer
- If  $d[i][j] < D$  (other object on this path closer to light)
  - point  $P$  is in shadow
  - lighting = ambient
- Otherwise, not in shadow
  - Lighting = amb + diffuse + specular

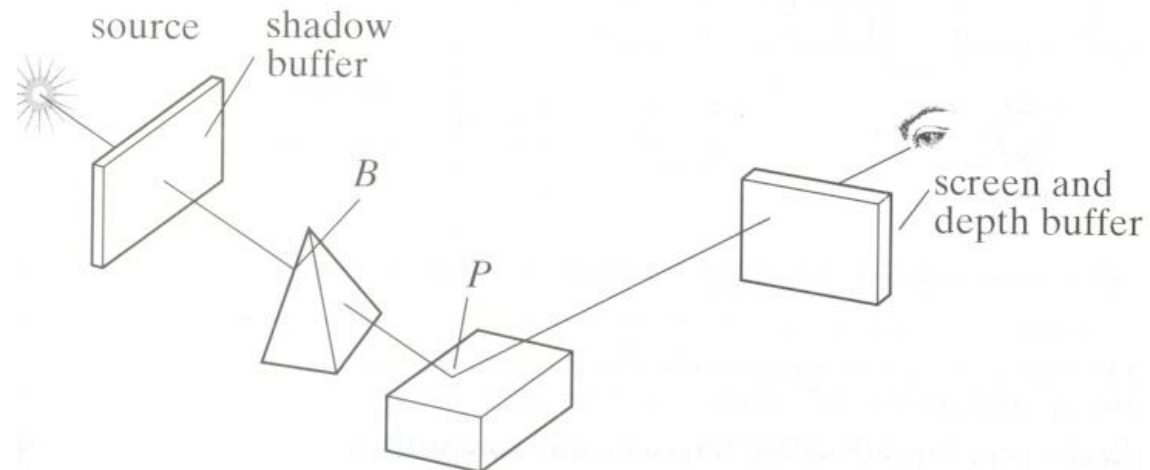




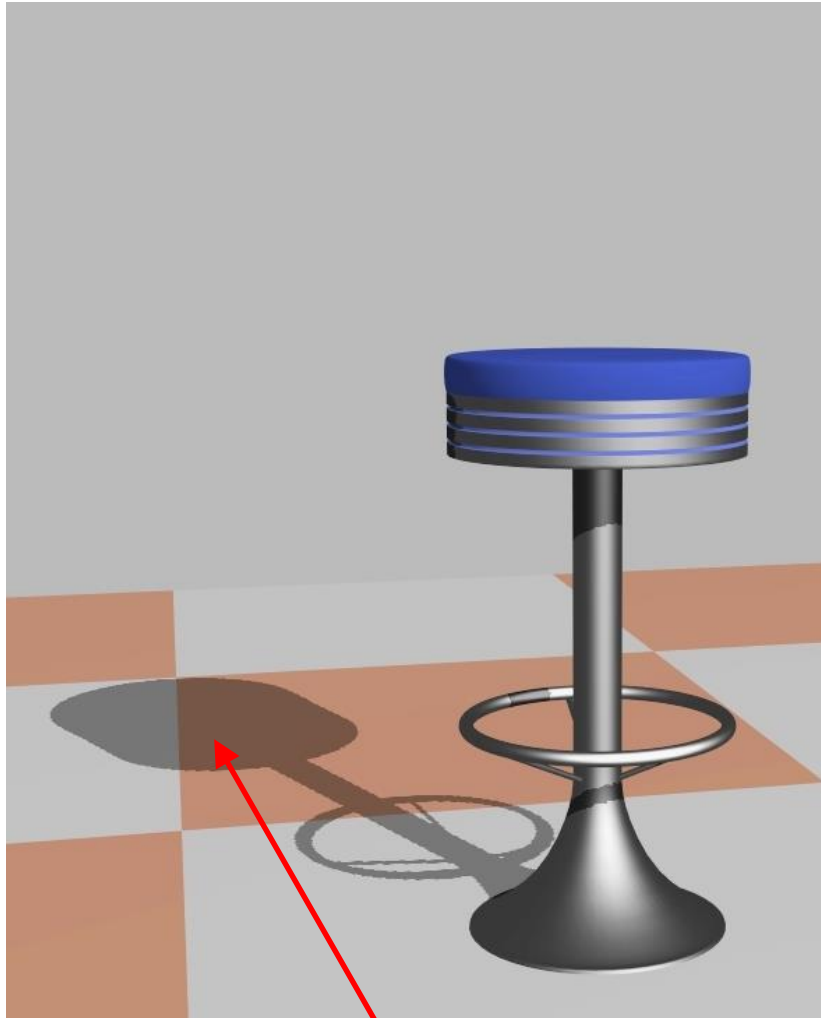


# Loading Shadow Map

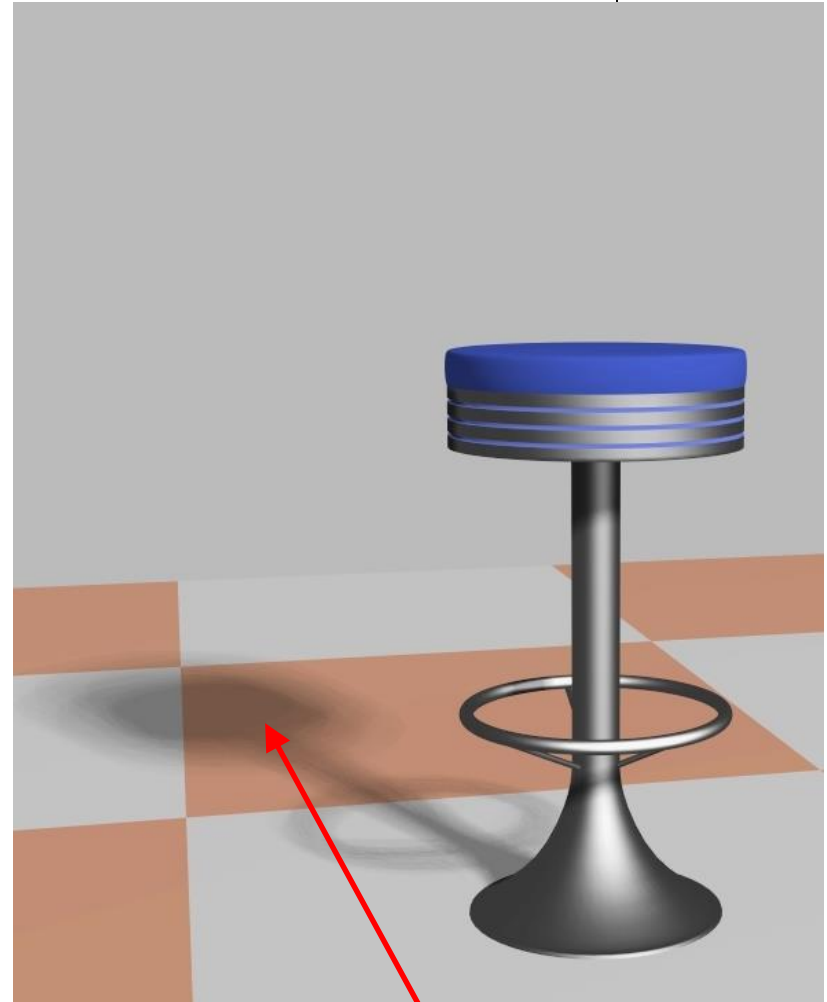
- Shadow map calculation is independent of eye position
- In animations, shadow map loaded once
- If eye moves, no need for recalculation
- If objects move, recalculation required



# Example: Hard vs Soft Shadows



**Hard Shadow**

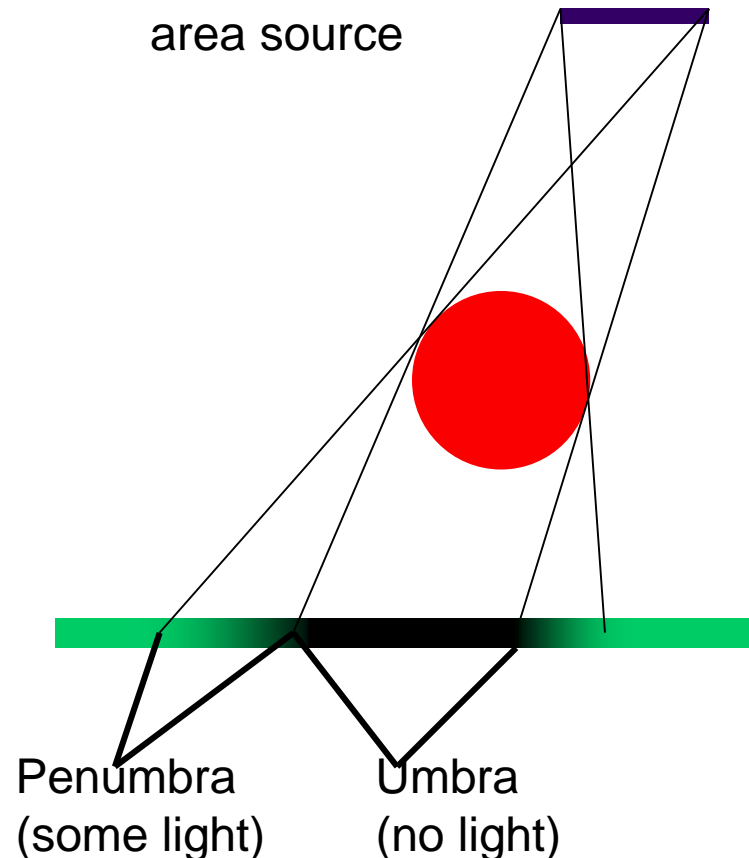
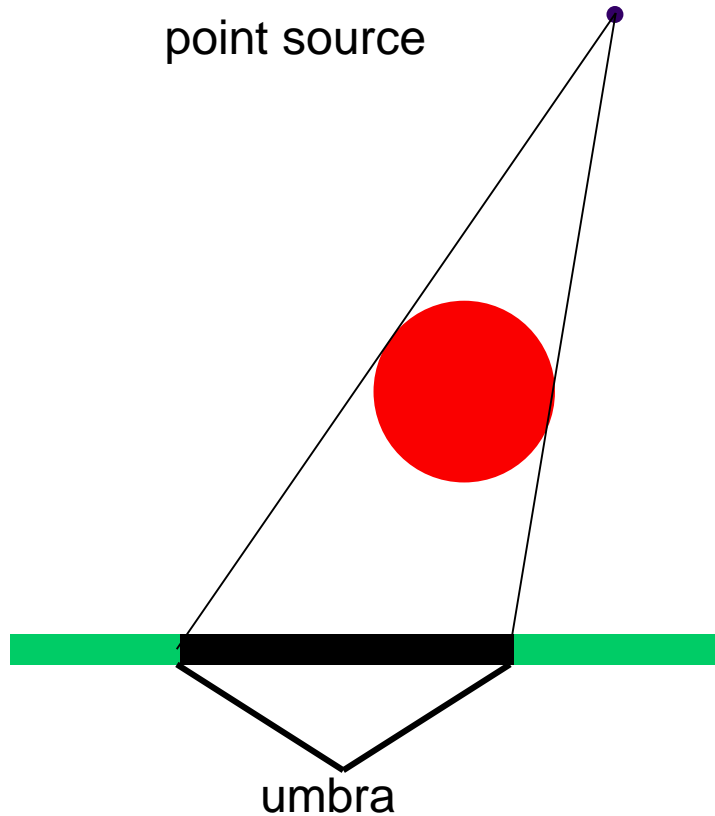


**Soft Shadow**



# Definitions

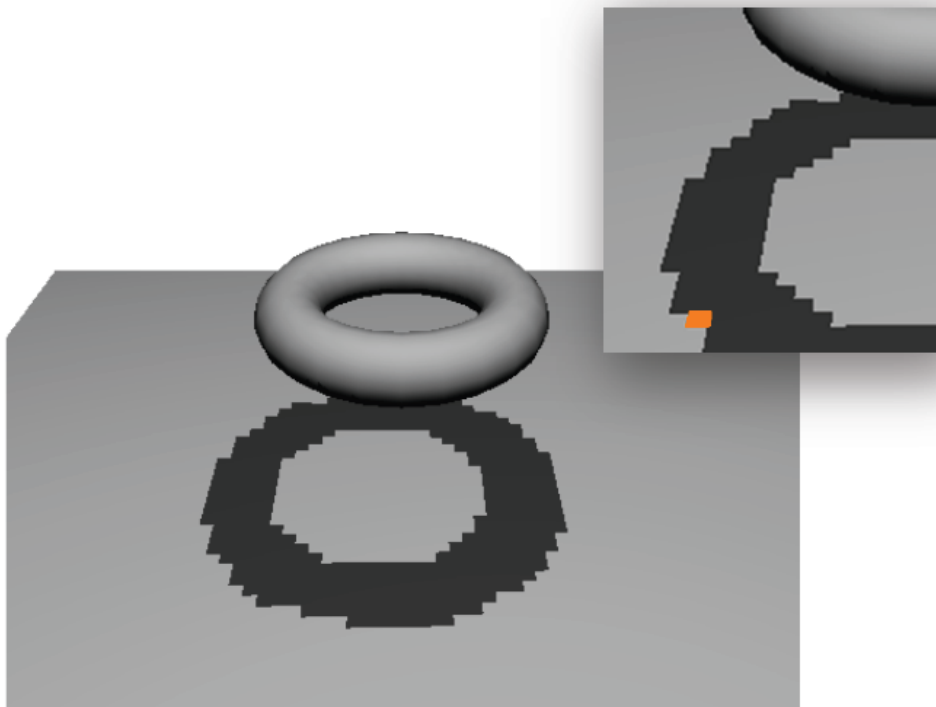
- Point light: create hard shadows (unrealistic)
- Area light: create soft shadows (more realistic)



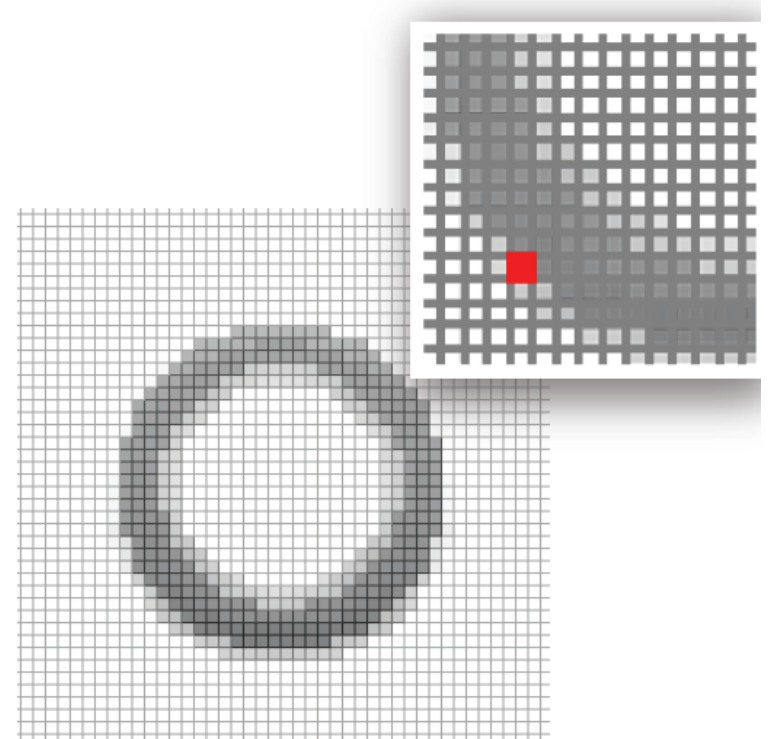
# Shadow Map Problems



- Low shadow map resolution results in jagged shadows



from viewpoint

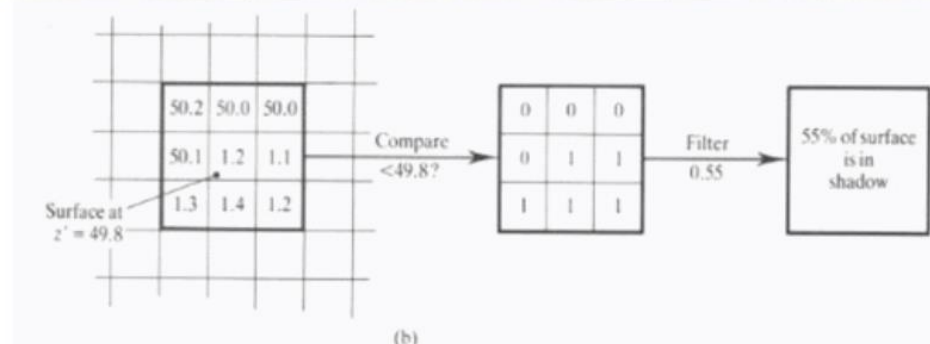
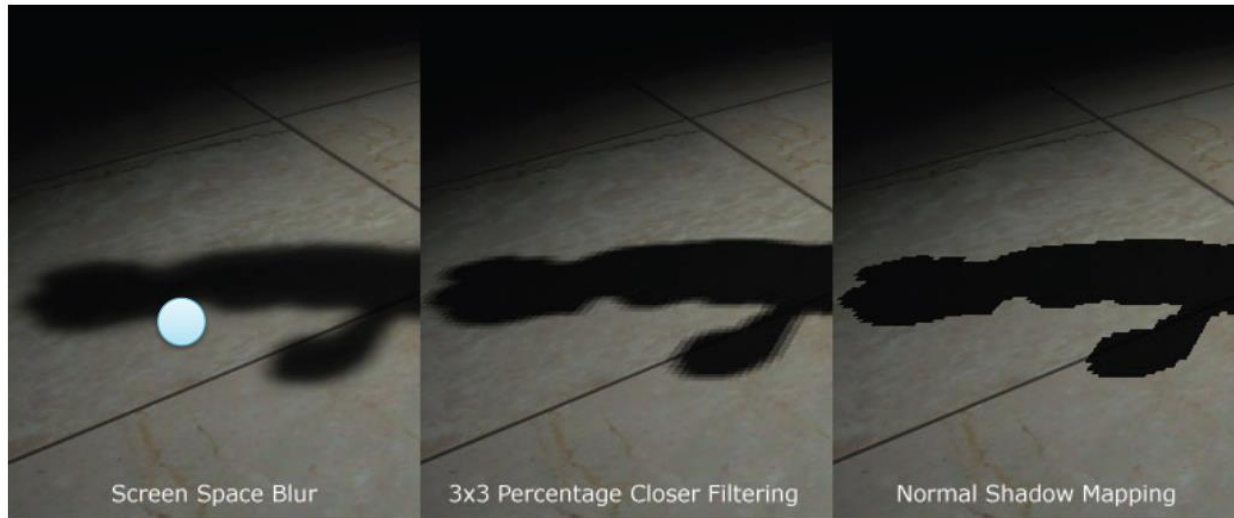


from light

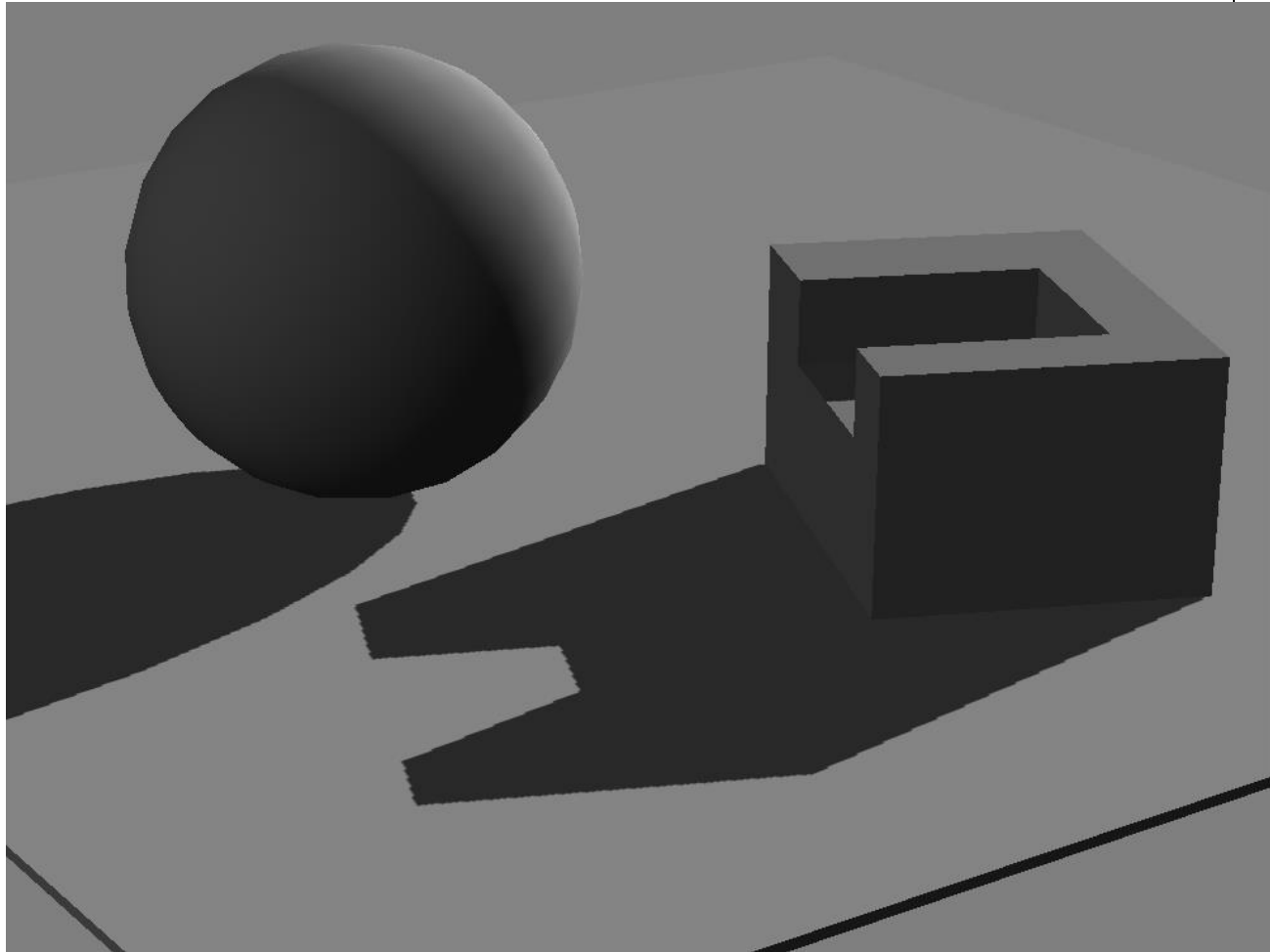


# Percentage Closer Filtering

- Instead of retrieving just 1 value from shadow map, retrieve neighboring shadow map values as well
- Blend multiple shadow map samples to reduce jaggies



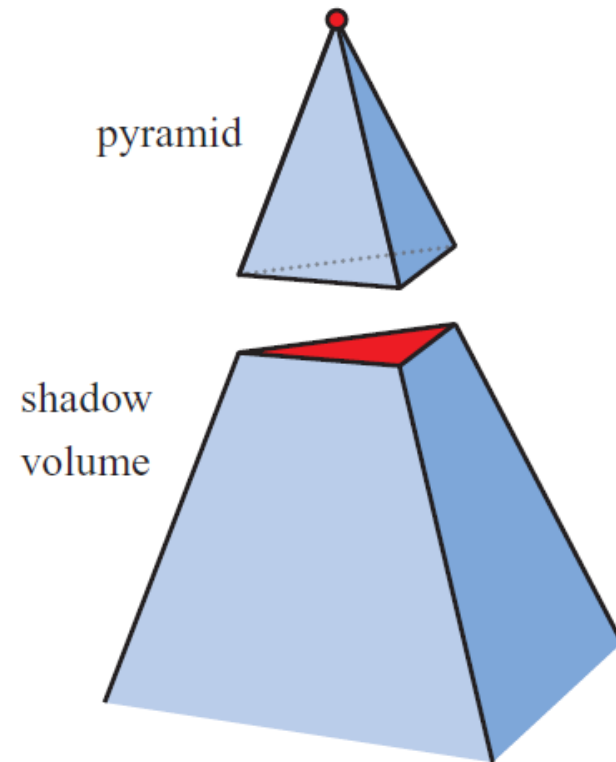
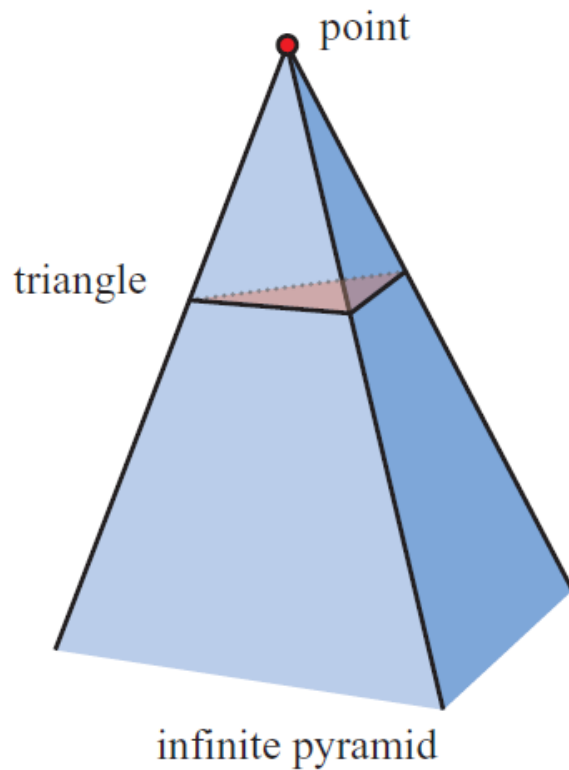
# Shadow Map Result





# Shadow volumes

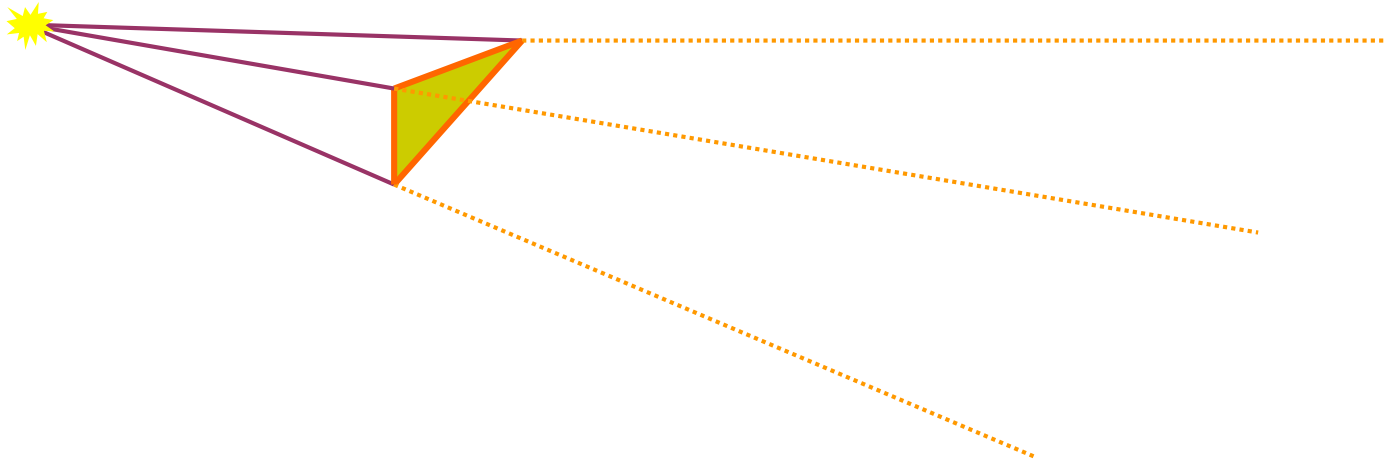
- Most popular method for real time
- Shadow volume concept





# Shadow volumes

- Create volumes of space in shadow from each polygon in light
- Each triangle creates 3 projecting quads

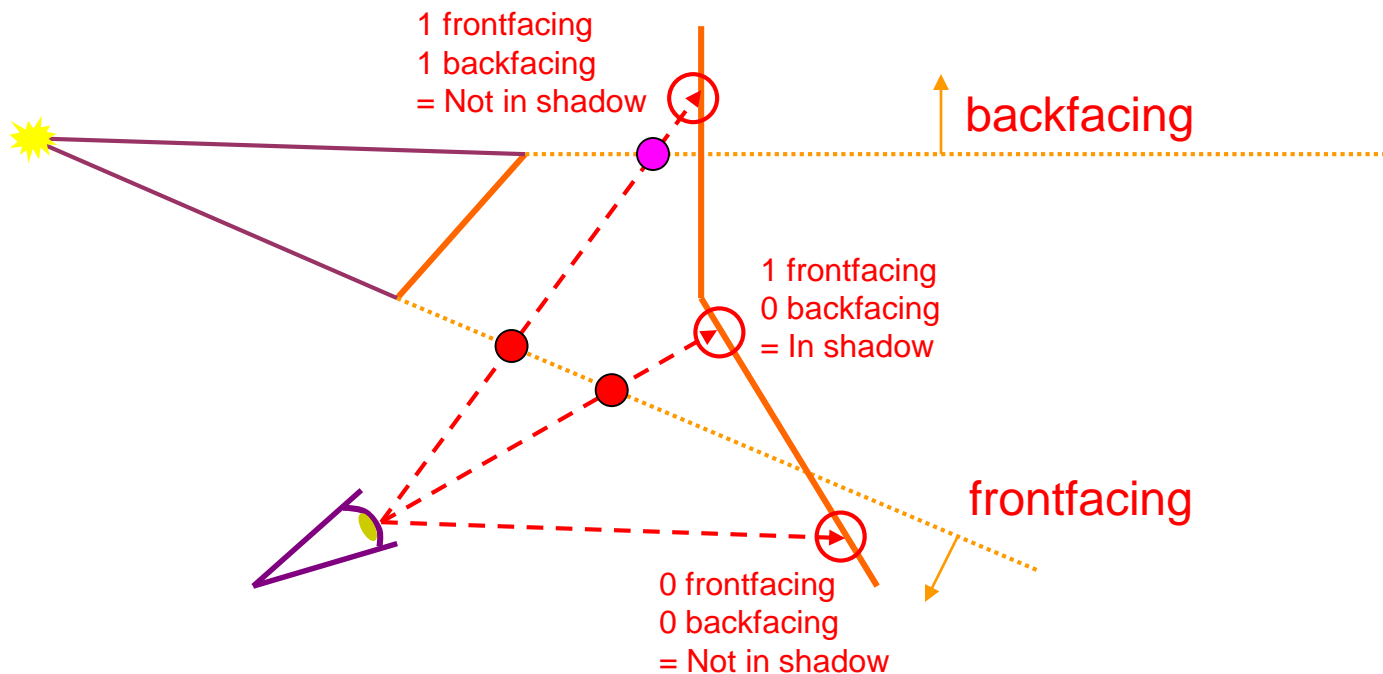






# Using Shadow Volume

- To test a point, count number of polygon intersections between the point and the eye.
- If we look through more frontfacing than backfacing polygons, then in shadow.



# Shadow Volume Example

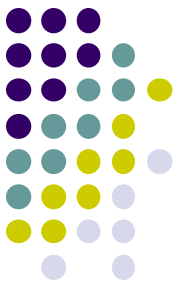
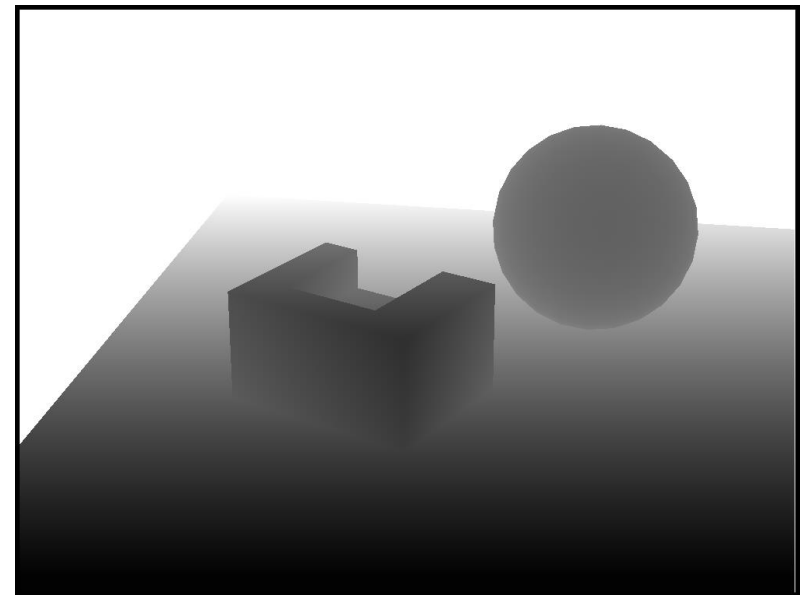


Image courtesy of NVIDIA Inc.



# Arbitrary geometry

- Shadow mapping and shadow volumes can render shadows onto arbitrary geometry
  - Recent focus on shadow volumes, because currently most popular, and works on most hardware
- Works in real time...
- Shadow mapping is used in Pixar's rendering software





# Normal Mapping

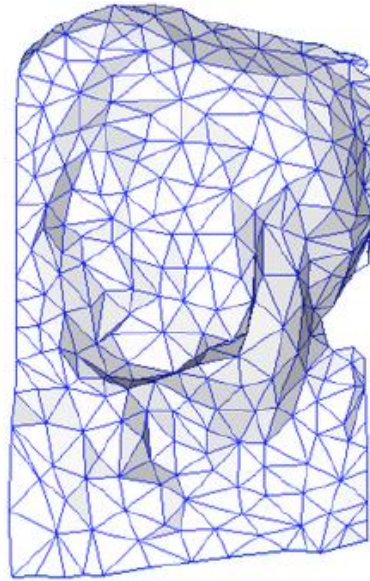


# Normal Mapping

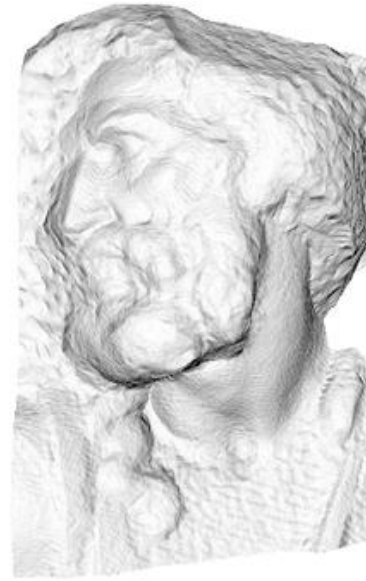
- Store normals in texture
- Normals  $\langle x, y, z \rangle$  stored in  $\langle r, g, b \rangle$  values in texture
- **Idea:** Use low resolution mesh + high resolution normal map
- Normal map may change a lot, simulate fine details
- Low rendering complexity method for making low-resolution geometry look like it's much more detailed



original mesh  
4M triangles



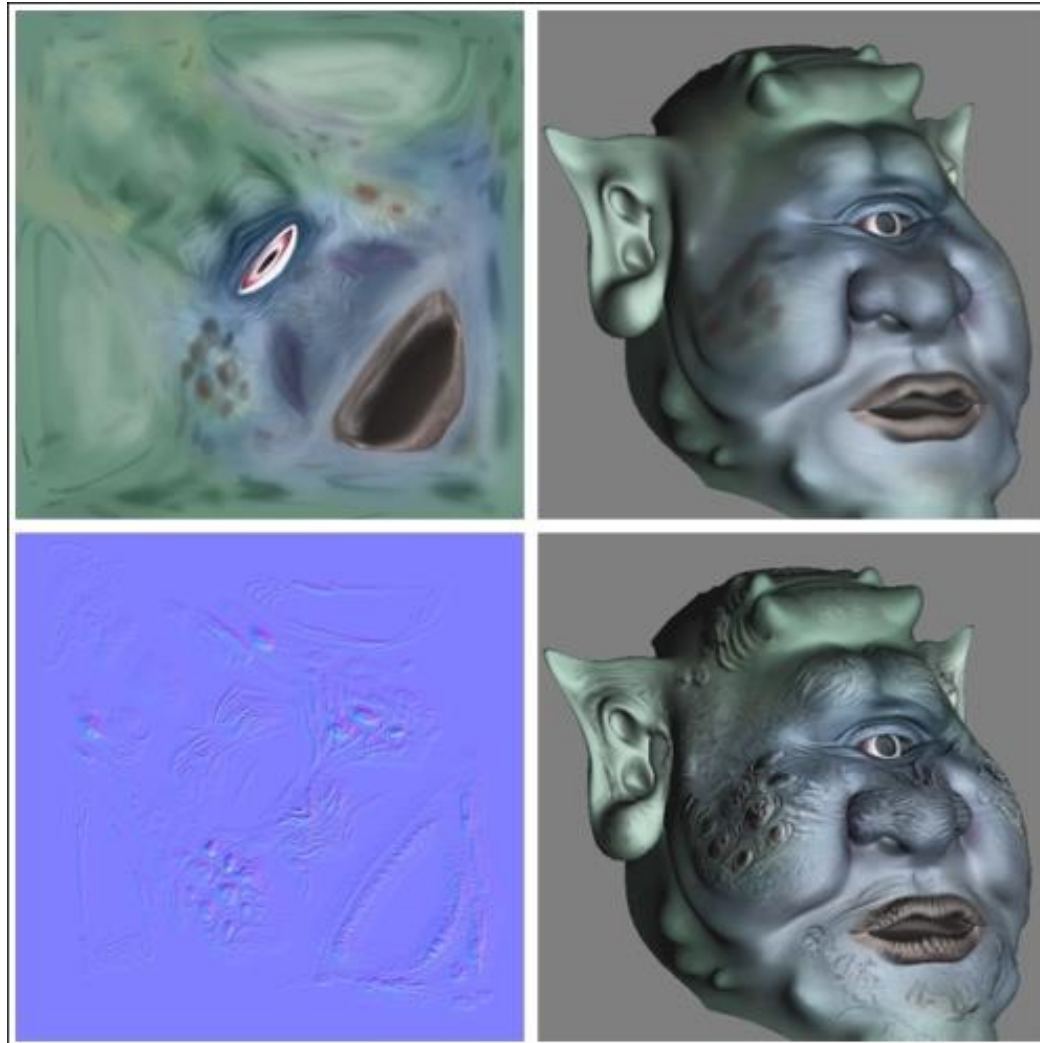
simplified mesh  
500 triangles



simplified mesh  
and normal mapping  
500 triangles

# Normal Mapping Example: Ogre

OpenGL 4 Shading Language Cookbook (3rd edition) by David Wolff (pg 157)



**Base color texture  
(used this in place of  
diffuse component)**

**Texture mapped  
Ogre (Uses mesh  
normals)**

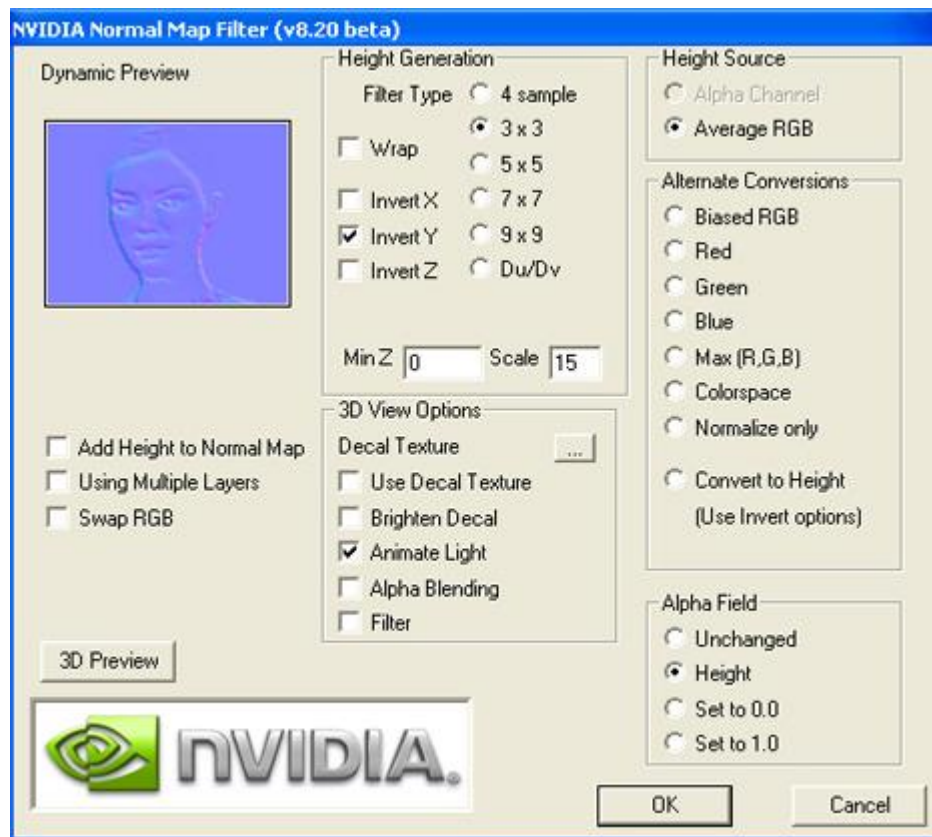
**Normal texture map**

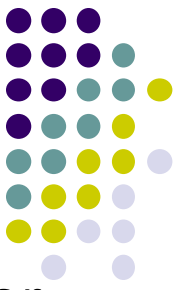
**Texture and normal  
mapped Ogre (Uses  
normal map to  
modify mesh  
normals)**



# Creating Normal Maps

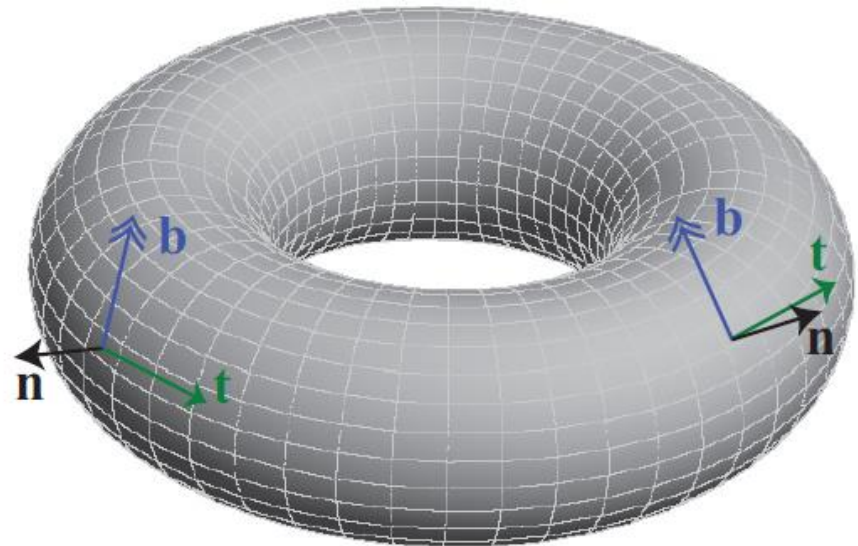
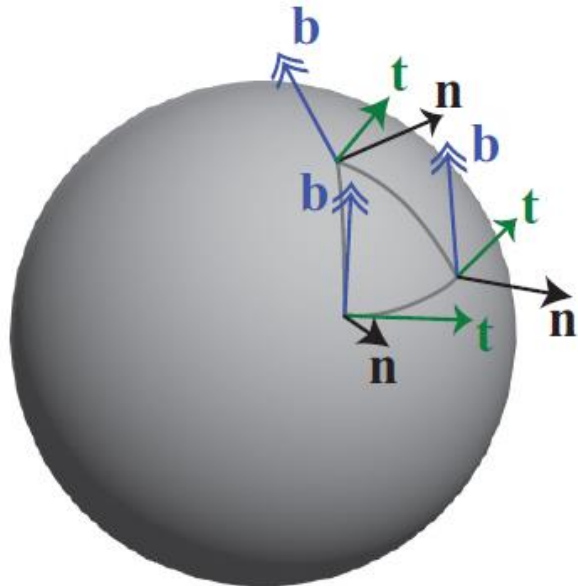
- Many tools for creating normal map
- E.g. Nvidia texture tools for Adobe photoshop
  - <https://developer.nvidia.com/nvidia-texture-tools-adobe-photoshop>





# Tangent Space Vectors

- Normals in normal map stored in object local coord. frame (or tangent space)
- Object Local coordinate space? Axis positioned on surface of object (NOT global x,y,z)
- Need Tangent, normal and bi-tangent vectors at each vertex
  - z axis aligned with mesh normal at that point

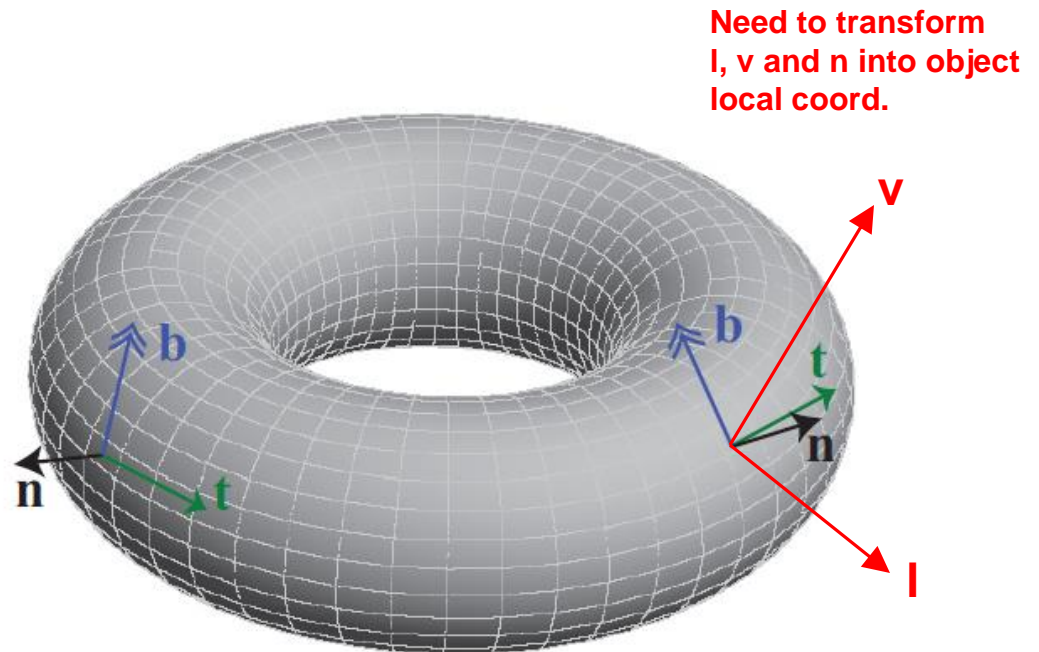
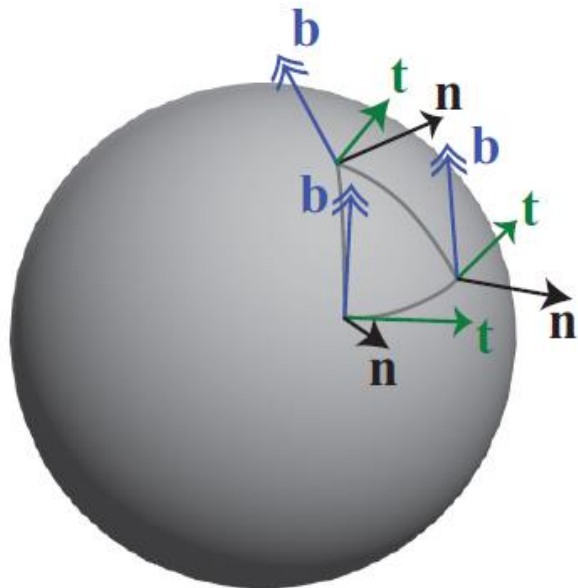




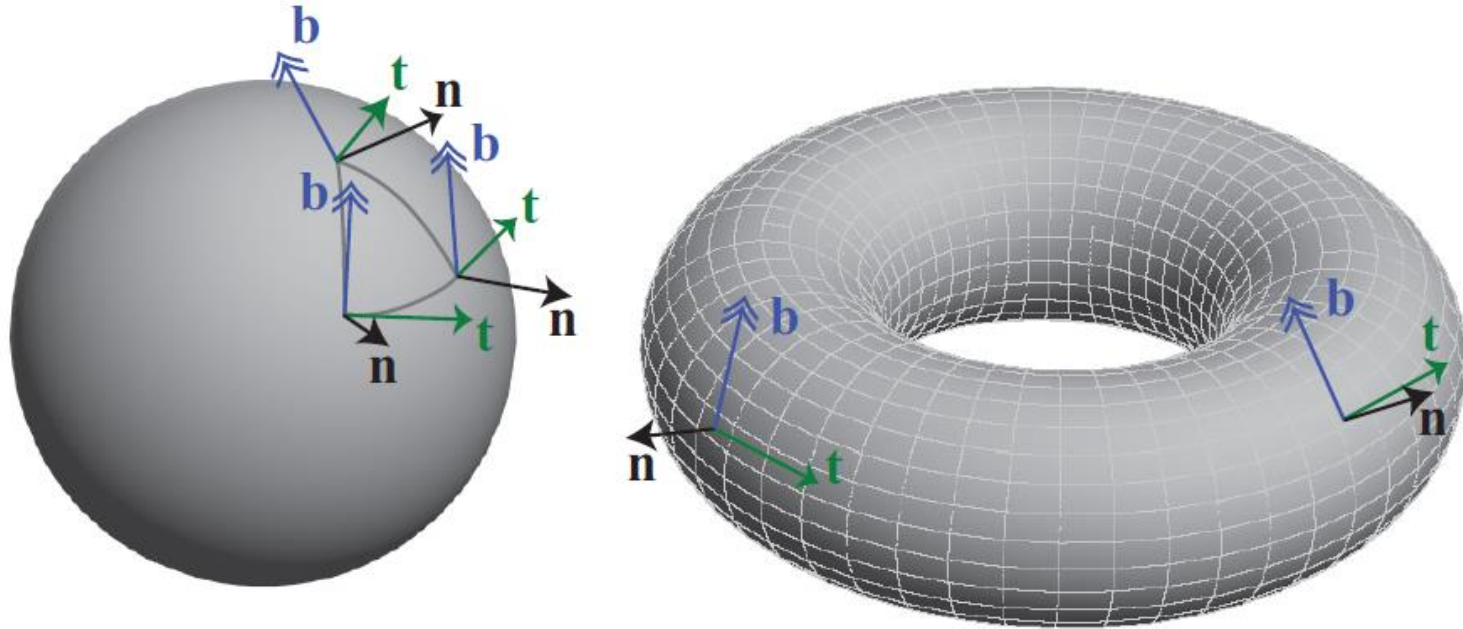
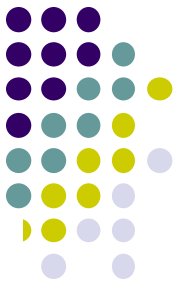


# Tangent Space Vectors

- Normals stored in texture includes mesh transformation + local deviation (e.g. bump)
- Reflection model must be evaluated in object's local coordinate (n, t, b)
- Need to transform view, light and normal vectors into object's local coordinate space



# Transforming V,L and N into Object's Local Coordinate Frame

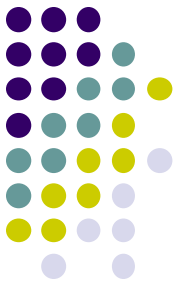


- To transform a point  $P$  eye into a corresponding point  $S$  in object's local coordinate frame:

Point  $S$  in object's local coordinate frame  $\longrightarrow$  
$$\begin{bmatrix} S_x \\ S_y \\ S_z \end{bmatrix} = \begin{bmatrix} t_x & t_y & t_z \\ b_x & b_y & b_z \\ n_x & n_y & n_z \end{bmatrix} \begin{bmatrix} P_x \\ P_y \\ P_z \end{bmatrix} \longleftarrow$$
 Point  $P$  in eye coordinate frame

# Normal Mapping Example

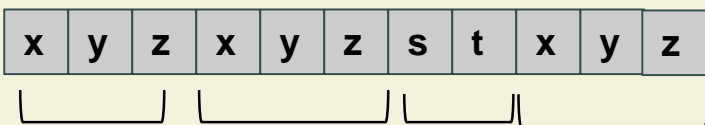
OpenGL 4 Shading Language Cookbook (3rd edition) by David Wolff (pg 159)



## Vertex Shader

```
VertexPosition  layout (location = 0) in vec3 VertexPosition;  
VertexNormal    layout (location = 1) in vec3 VertexNormal;  
VertexTexCoord layout (location = 2) in vec2 VertexTexCoord;  
VertexTangent   layout (location = 3) in vec4 VertexTangent;
```

## Vertex 1 Attributes



VertexPosition VertexNormal VertexTexCoord VertexTangent

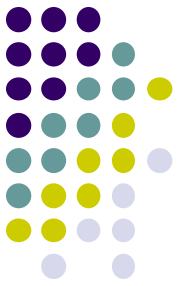
layout (location) = 0

layout (location) = 1

OpenGL Program

# Normal Mapping Example

OpenGL 4 Shading Language Cookbook (3rd edition) by David Wolff (pg 159)



## Vertex Shader

```
layout (location = 0) in vec3 VertexPosition;
layout (location = 1) in vec3 VertexNormal;
layout (location = 2) in vec2 VertexTexCoord;
layout (location = 3) in vec4 VertexTangent;
```

```
.....

uniform mat4 ModelViewMatrix;
uniform mat3 NormalMatrix;
uniform mat4 ProjectionMatrix;
uniform mat4 MVP;

void main()
{
    // Transform normal and tangent to eye space
    vec3 norm = normalize(NormalMatrix * VertexNormal);
    vec3 tang = normalize(NormalMatrix *
                        vec3(VertexTangent));

    // Compute the binormal
    vec3 binormal = normalize( cross( norm, tang ) ) *
    VertexTangent.w;
}
```

Transform normal and  
tangent to eye space

.....  
Compute bi-normal vector

```
.....

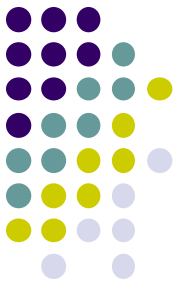
// Matrix for transformation to tangent space
mat3 toObjectLocal = mat3(
    tang.x, binormal.x, norm.x,
    tang.y, binormal.y, norm.y,
    tang.z, binormal.z, norm.z );
```

Form matrix to convert from  
eye to local object coordinates

$$\begin{bmatrix} S_x \\ S_y \\ S_z \end{bmatrix} = \begin{bmatrix} t_x & t_y & t_z \\ b_x & b_y & b_z \\ n_x & n_y & n_z \end{bmatrix} \begin{bmatrix} P_x \\ P_y \\ P_z \end{bmatrix}$$

# Normal Mapping Example

OpenGL 4 Shading Language Cookbook (3rd edition) by David Wolff (pg 159)



## Vertex Shader

.....

```
// Get the position in eye coordinates
vec3 pos = vec3( ModelViewMatrix *
                vec4(VertexPosition,1.0) );

// Transform light dir. and view dir. to tangent space
LightDir = normalize( toObjectLocal *
                    (Light.Position.xyz - pos) );
ViewDir = toObjectLocal * normalize(-pos);

// Pass along the texture coordinate
TexCoord = VertexTexCoord;

gl_Position = MVP * vec4(VertexPosition,1.0);
}
```

Get position in eye coordinates

....

Transform light and view directions to tangent space

## Fragment Shader

```
in vec3 LightDir;
in vec2 TexCoord;
in vec3 ViewDir;

layout(binding=0) uniform sampler2D ColorTex;
layout(binding=1) uniform sampler2D NormalMapTex;
```

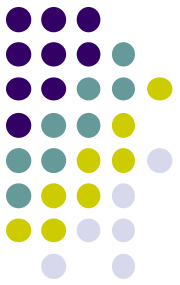
Receive Light, View directions and TexCoord set in vertex shader

.....

Declare Normal and Color maps

# Normal Mapping Example

OpenGL 4 Shading Language Cookbook (3rd edition) by David Wolff (pg 159)

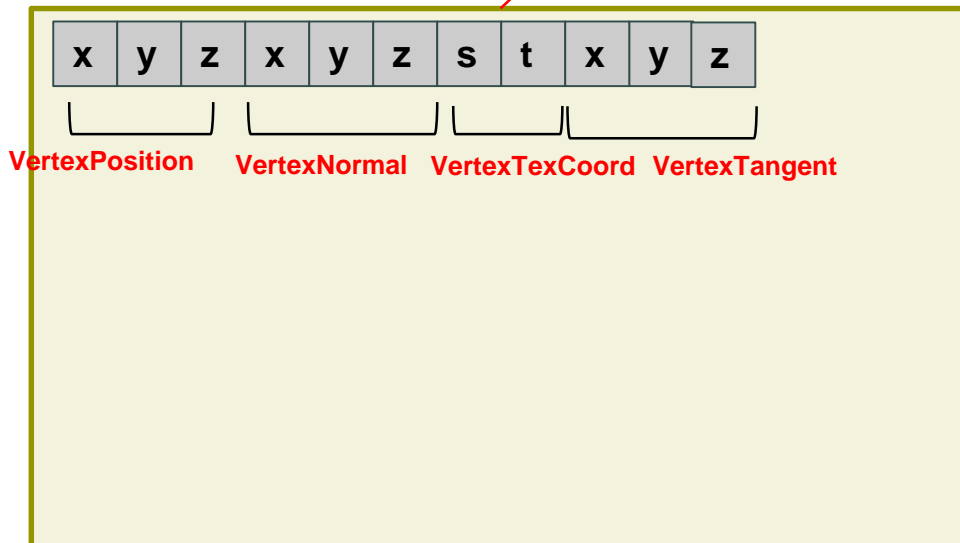


## Fragment Shader

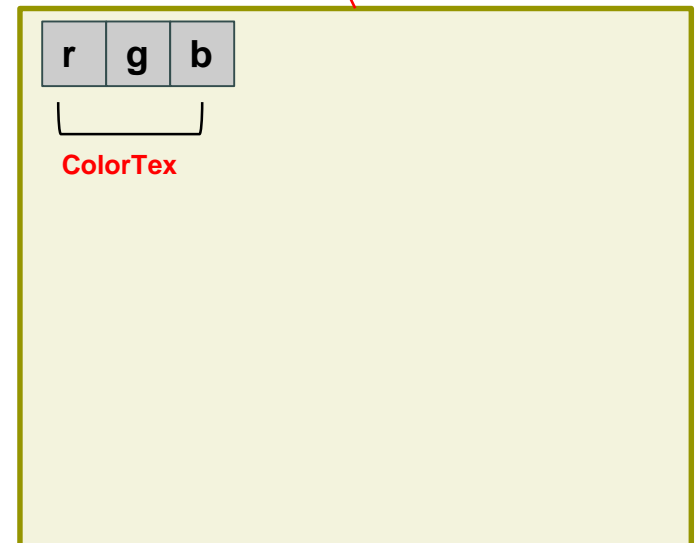
```
in vec3 LightDir;
in vec2 TexCoord;
in vec3 ViewDir;

layout(binding=0) uniform sampler2D ColorTex;
layout(binding=1) uniform sampler2D NormalMapTex;
```

.....



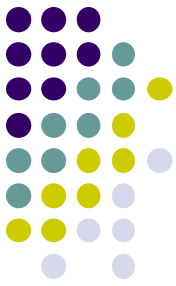
Normal Map



Diffuse Color Map

# Normal Mapping Example

OpenGL 4 Shading Language Cookbook (3rd edition) by David Wolff (pg 159)



## Fragment Shader

```
.....  
vec3 phongModel( vec3 norm, vec3 diffR ) {vec3 r = reflect( -LightDir, norm );  
  vec3 ambient = Light.Intensity * Material.Ka;  
  float sDotN = max( dot(LightDir, norm), 0.0 );  
  vec3 diffuse = Light.Intensity * diffR * sDotN;  
  
  vec3 spec = vec3(0.0);  
  if( sDotN > 0.0 )  
    spec = Light.Intensity * Material.Ks *  
          pow( max( dot(r,ViewDir), 0.0 ),  
              Material.Shininess );  
  
  return ambient + diffuse + spec;  
}  
  
void main() {  
  // Lookup the normal from the normal map  
  vec4 normal = 2.0 * texture( NormalMapTex, TexCoord ) -  
              1.0;  
  
  // The color texture is used as the diff. reflectivity  
  vec4 texColor = texture( ColorTex, TexCoord );  
  
  FragColor = vec4( phongModel(normal.xyz, texColor.rgb),  
                   1.0 );  
}
```

Function to compute  
Phong's lighting model

Look up normal from  
normal map  
Rescale from [0,1] to  
[-1,1] range  
.....

Look up diffuse coeff.  
from color texture

x	y	z	x	y	z	s	t	x	y	z
---	---	---	---	---	---	---	---	---	---	---

VertexPosition    VertexNormal    VertexTexCoord    VertexTangent

Normal Map

r	g	b
---	---	---

ColorTex

Diffuse Color Map