Computer Graphics (CS 543) Lecture 12 (Part 1): 3D Clipping

Prof Emmanuel Agu

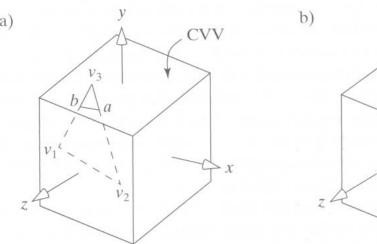
Computer Science Dept.
Worcester Polytechnic Institute (WPI)

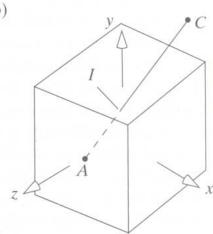






- Want to clip edge-by-edge of an object against CVV
- Now describe a version embellished by Jim Blinn
- Problem:
 - Two points, A = (Ax, Ay, Az, Aw) and C = (Cx, Cy, Cz, Cw), in homogeneous coordinates
 - If segment intersects with CVV, need to compute intersection point I= =(Ix,Iy,Iz,Iw)









_		<i>y</i> = 1	
	•	y= -1	
		x = -1	X = 1

Determine whether a point (x,y,z) is inside or outside CVV?

Point (x,y,z) is inside CVV

if
$$(-1 <= x <= 1)$$

and
$$(-1 <= y <= 1)$$

and
$$(-1 <= z <= 1)$$

else the point is outside CVV

$$=CVV = = 6 \text{ infinite planes } (x=-1,1; y=-1,1; z=-1,1)$$





	y/w = 1	
	•	
•	y/w= -1	
	x/w = -1	x/w= 1

- What if point is in homogeneous coordinates?
- Point specified as (x,y,z,w)
- Use scaled version of x,y,z!

Point (x/w, y/w, z/w) is inside CVV

if
$$(-1 \le x/w \le 1)$$

and $(-1 \le y/w \le 1)$
and $(-1 \le z/w \le 1)$

else the point is outside CVV





	y/w = 1	
	•	
•	y/w= -1	
	x/w = -1	x/w= 1

Consider plane x = 1, point A = (Ax,Ay,Az,Aw) is inside if

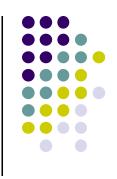
$$Ax/Aw < 1$$

$$=> Aw - Ax > 0$$
or $w - x > 0$

Point A = (Ax,Ay,Az,Aw) plane x = -1 if

$$Ax/Aw > -1$$

=> $Aw + Ax > 0$
or $w + x > 0$



Determining if point is inside CVV

- So, point is
 - inside (right of) plane x=-1 if w+x > 0
 - inside (left of) plane x=1 if w-x>0



- Point (0.5, 0.2, 0.7) inside planes (x = -1,1) because -1 <= 0.5 <= 1
- If scaled by w = 10, (0.5, 0.2, 0.7) = (5, 2, 7, 10)
- Use scaled version, point is inside because 1 <= 5/10 <= 1</p>

To test if inside
$$x = -1$$
, $w + x = 10 + 5 = 15 > 0$

To test if inside
$$x = 1$$
, $w - x = 10 - 5 = 5 > 0$





Notation (Aw +Ax) = w + x, boundary coordinates for 6 planes as:

Boundary coordinate (BC)	Homogenous coordinate	Clip plane	Example (5,2,7,10)
BC0	W+X	x=-1	15
BC1	W-X	x=1	5
BC2	w+y	y=-1	12
BC3	w-y	y=1	8
BC4	W+Z	z=-1	17
BC5	W-Z	z=1	3

■Trivial accept: 12 BCs (6 for pt. A, 6 for pt. C) are positive

•Trivial reject: Both endpoints outside of same plane

Edges as Parametric Equations



- Implicit form F(x, y) = 0
- Parametric forms:
 - points specified based on single parameter value
 - Typical parameter: time t

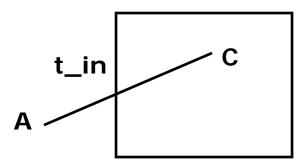
$$P(t) = P_0 + (P_1 - P_0) * t 0 \le t \le 1$$

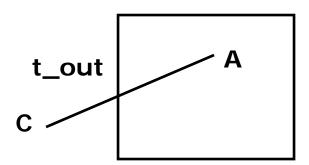
- Some algorithms work in parametric form
 - Clipping: exclude line segment ranges
 - Animation: Interpolate between endpoints by varying t
- Represent each edge parametrically as A + (C − A)t
- Intepretation: a point is traveling such that:
 - at time t=0, point at A
 - at time t=1, point at C

Inside/outside?



- Test against 6 walls
- If BCs have opposite signs = edge hits plane at time t_hit
 - i.e. if pt. A is outside, C is inside
- Define: "entering" = as t increases, outside to inside
- Define "leaving": as t increases, inside to outside (A inside, C outside)









- How to calculate t_hit?
- Represent an edge t as:

$$Edge(t) = ((Ax + (Cx - Ax)t, (Ay + (Cy - Ay)t, (Az + (Cz - Az)t, (Aw + (Cw - Aw)t))))$$

E.g. If
$$x = 1$$
,
$$\frac{Ax + (Cx - Ax)t}{Aw + (Cw - Aw)t} = 1$$

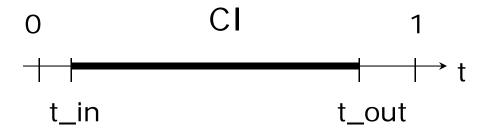
Solving for t above,

$$t = \frac{Aw - Ax}{(Aw - Ax) - (Cw - Cx)}$$

Candidate Interval



- If not trivial accept/reject, then clip
- Define Candidate Interval (CI) as time interval during which edge might still be inside CVV. i.e. CI = t_in to t_out
- Initialize CI to [0,1]
- For each of 6 planes, calculate t_in or t_out, shrink Cl



Conversely: values of t outside CI = edge is outside CVV





Algorithm:

- Test for trivial accept/reject (stop if either occurs)
- Set CI to [0,1]
- For each of 6 planes:
 - Find hit time t_hit
 - If t_in, new t_in = max(t_in,t_hit)
 - If t_out, new t_out = min(t_out, t_hit)
 - If t_in > t_out => exit (no valid intersections)

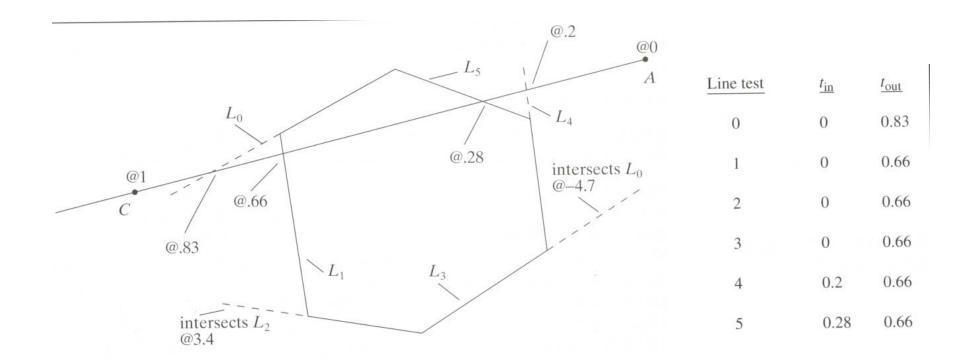
Note: seeking smallest valid CI without t_in crossing t_out

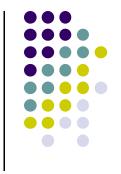


Shortening Candidate Interval

Example to illustrate search for t_in, t_out

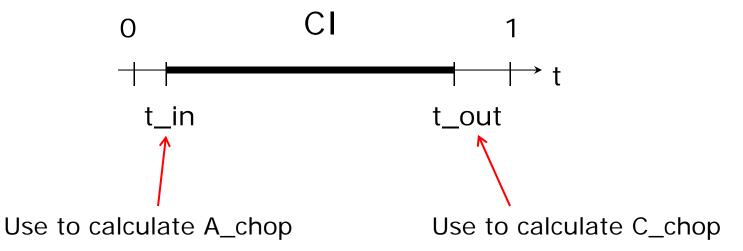
Note: CVV is a cube (different shape). This is just an example





Calculate choppped A and C

- If valid t_in, t_out, calculate adjusted edge endpoints A, C as
- A_chop = A + t_in (C A) (calculate for Ax,Ay, Az)
- C_chop = A + t_out (C A) (calculate for Cx,Cy,Cz)



3D Clipping Implementation



- Function clipEdge()
- Input: two points A and C (in homogenous coordinates)
- Output:
 - 0, if no part of line AC lies in CVV
 - 1, otherwise
 - Also returns clipped A and C
- Store 6 BCs for A, 6 for C

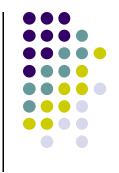
Store BCs as Outcodes



- Use outcodes to track in/out
 - Number walls x = +1, -1; y = +1, -1, and z = +1, -1 as 0...5
 - Bit i of A's outcode = 1 if A is outside ith wall
 - 1 otherwise
- Example: outcode for point outside walls 1, 2, 5

Wall no.
OutCode

0	1	2	3	4	5
0	1	1	0	0	1



Trivial Accept/Reject using Outcodes

Trivial accept: inside (not outside) all walls

Wall no.
A Outcode
C OutCode

0	1	2	3	4	5
0	0	0	0	0	0
0	0	0	0	0	0

Logical bitwise test: $A \mid C == 0$

• Trivial reject: point outside same wall. Example Both A and C outside wall 1

Wall no.
A Outcode
C OutCode

Logical bitwise test: A & C != 0

3D Clipping Implementation



- Compute BCs for A,C store as outcodes
- Test A, C outcodes for trivial accept, trivial reject
- If not trivial accept/reject, for each wall:
 - Compute tHit
 - Update t in, t out
 - If t_in > t_out, early exit

3D Clipping Pseudocode

```
int clipEdge(Point4& A, Point4& C)
   double tln = 0.0, tOut = 1.0, tHit;
   double aBC[6], cBC[6];
   int aOutcode = 0, cOutcode = 0;
   .....find BCs for A and C
   .....form outcodes for A and C
   if((aOutCode & cOutcode) != 0) // trivial reject
     return 0;
   if((aOutCode | cOutcode) == 0) // trivial accept
     return 1;
```





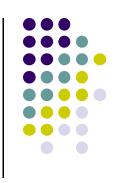
```
for(i=0;i<6;i++) // clip against each plane
{
   if(cBC[i] < 0) // C is outside wall i (exit so tOut)</pre>
          tHit = aBC[i]/(aBC[i] - cBC[I]); // calculate tHit
          tOut = MIN(tOut, tHit);
    else if(aBC[i] < 0) // A is outside wall I (enters so tIn)
          tHit = aBC[i]/(aBC[i] - cBC[i]); // calculate tHit
          tln = MAX(tln, tHit);
   if(tln > tOut) return 0; // Cl is empty: early out
```



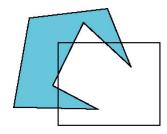


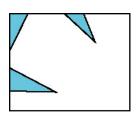
```
Point4 tmp; // stores homogeneous coordinates
If(aOutcode != 0) // A is outside: tln has changed. Calculate A_chop
   tmp.x = A.x + tln * (C.x - A.x);
   // do same for y, z, and w components
If(cOutcode != 0) // C is outside: tOut has changed. Calculate C_chop
   C.x = A.x + tOut * (C.x - A.x);
   // do same for y, z and w components
A = tmp;
Return 1; // some of the edges lie inside CVV
```





- Not as simple as line segment clipping
 - Clipping a line segment yields at most one line segment
 - Clipping a polygon can yield multiple polygons





 However, clipping a convex polygon can yield at most one other polygon



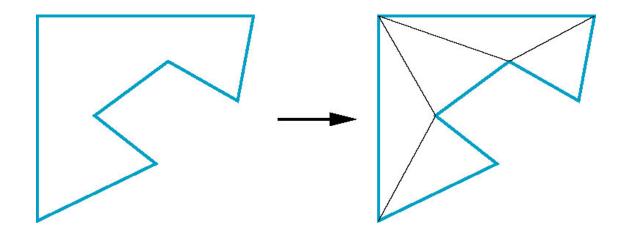


- Need more sophisticated algorithms to handle polygons:
 - Sutherland-Hodgman: any a given polygon against a convex clip polygon (or window)
 - Weiler-Atherton: Both subject polygon and clip polygon can be concave





- One strategy is to replace nonconvex (concave)
 polygons with a set of triangular polygons (a
 tessellation)
- Also makes fill easier





References

- Angel and Shreiner, Interactive Computer Graphics, 6th edition
- Hill and Kelley, Computer Graphics using OpenGL, 3rd edition