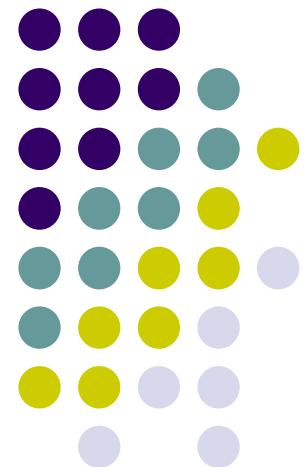


Computer Graphics (543)

Lecture 10 (Part 2): Texturing

Prof Emmanuel Agu

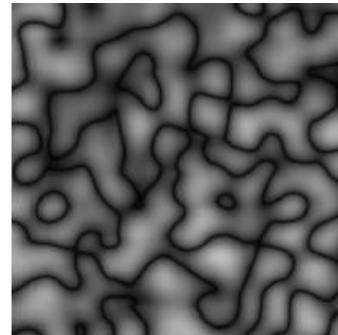
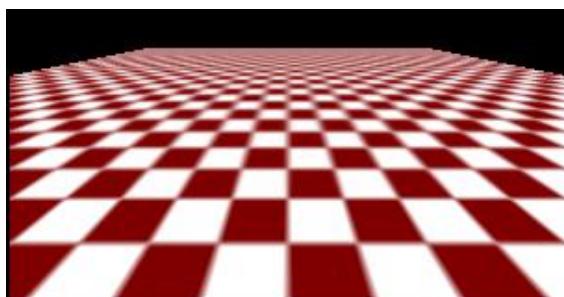
*Computer Science Dept.
Worcester Polytechnic Institute (WPI)*





The Limits of Geometric Modeling

- Although graphics cards can render over 10 million polygons per second, that number is insufficient for many phenomena
 - Clouds
 - Grass
 - Terrain
 - Skin
- Computationally inexpensive way to add details



Complexity of images does
Not affect the complexity
Of geometry processing
(transformation, clipping...)



Modeling an Orange

- Consider problem of modeling an orange (the fruit)
- Start with an orange-colored sphere: Too simple
- Replace sphere with a more complex shape
 - Does not capture surface characteristics (dimples)
 - Takes too many polygons to model all the dimples





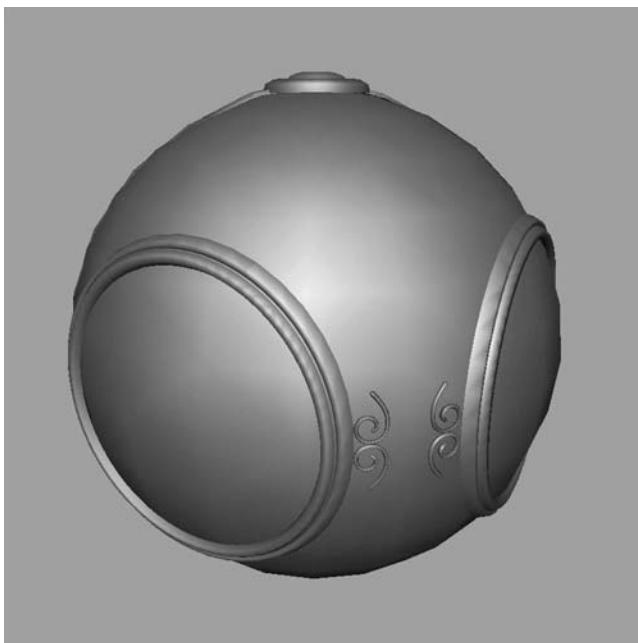
Modeling an Orange (2)

- Take a picture of a real orange, scan it, and “paste” onto simple geometric model
 - Known as texture mapping
- Still might not be sufficient because resulting surface will be smooth
 - Simulate surface roughness: bump mapping



Three Types of Mapping

- Texture Mapping
 - Paste image onto polygon



geometric model

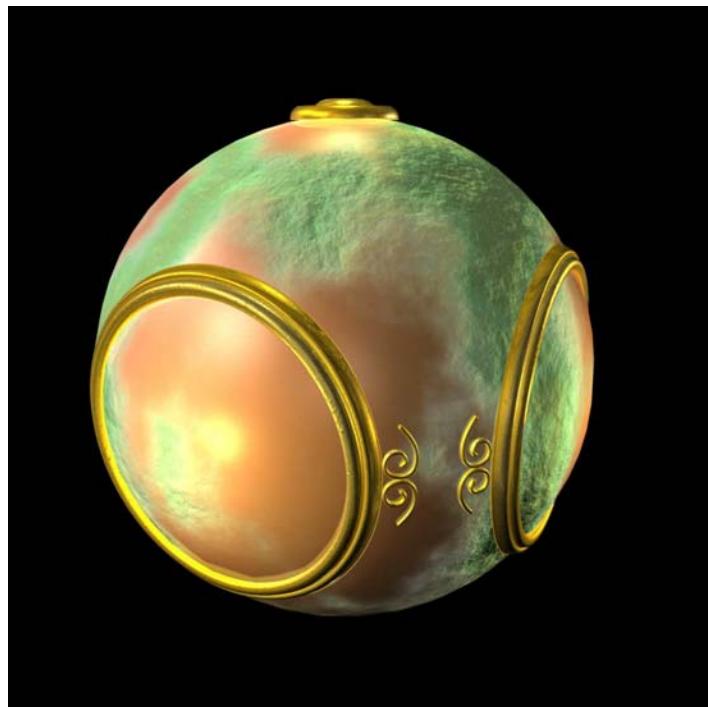


texture mapped



Three Types of Mapping

- Bump mapping
 - Alters normal vectors during rendering process to simulate surface roughness





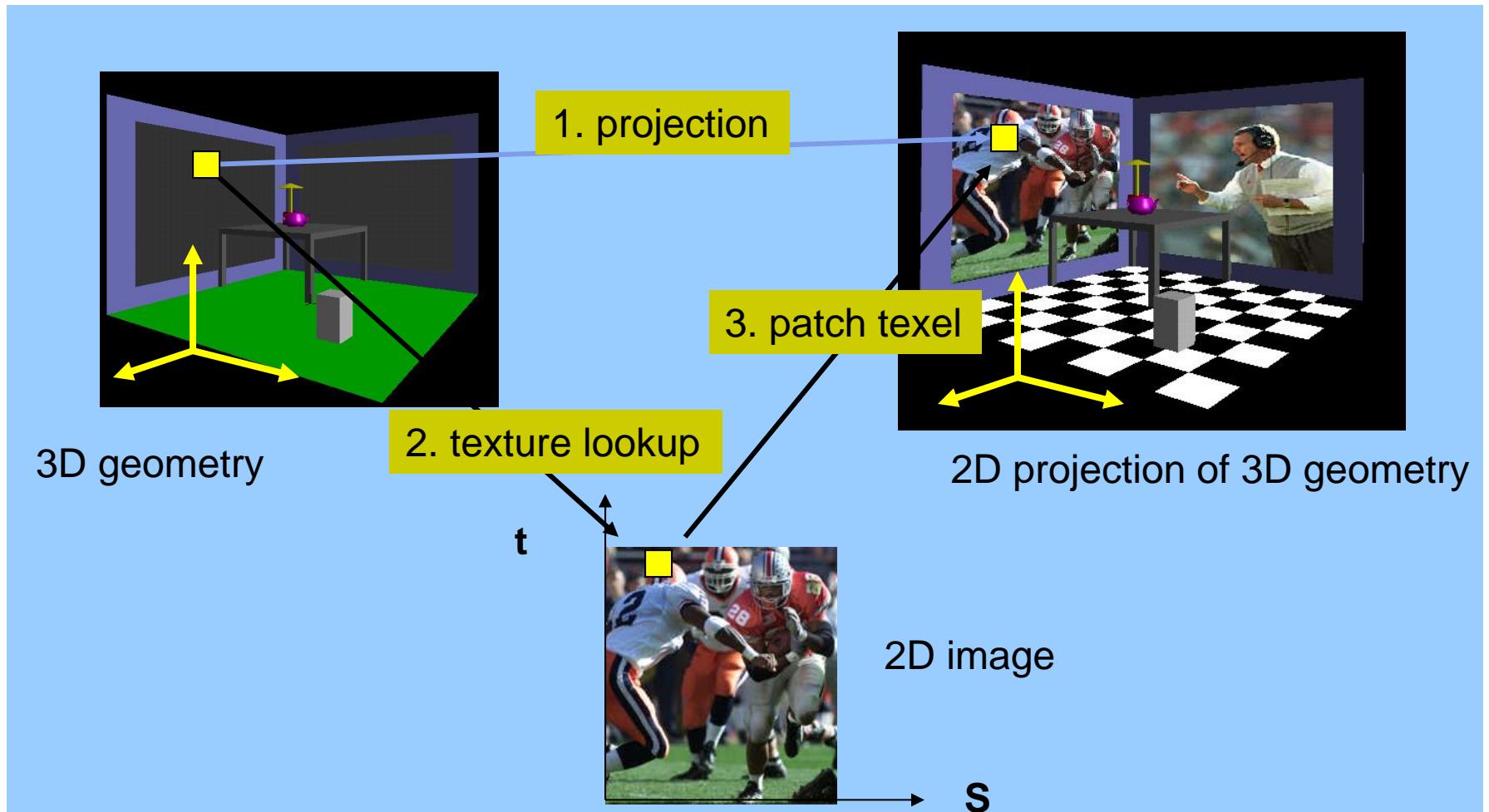
Three Types of Mapping

- Environment (reflection mapping)
 - Uses picture of the sky/environment for texture maps





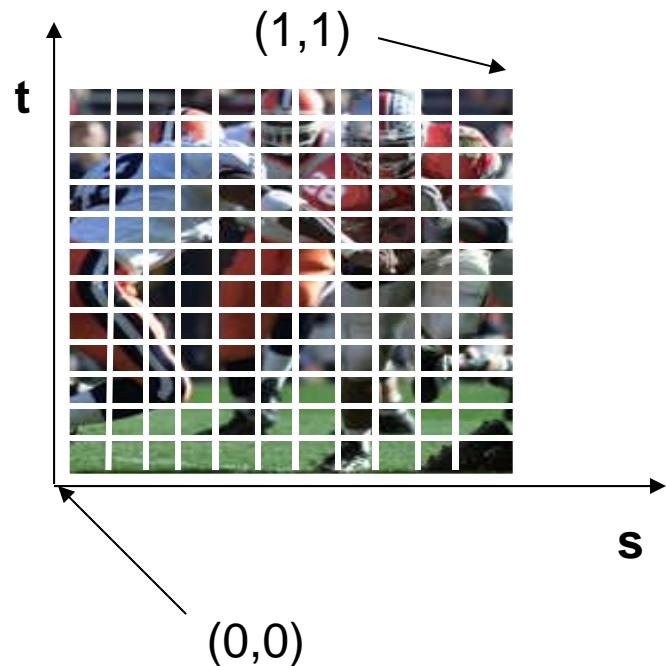
Texture Mapping





Texture Representation

- ✓ Bitmap (pixel map) textures (supported by OpenGL)
- Procedural textures (used in advanced rendering programs)



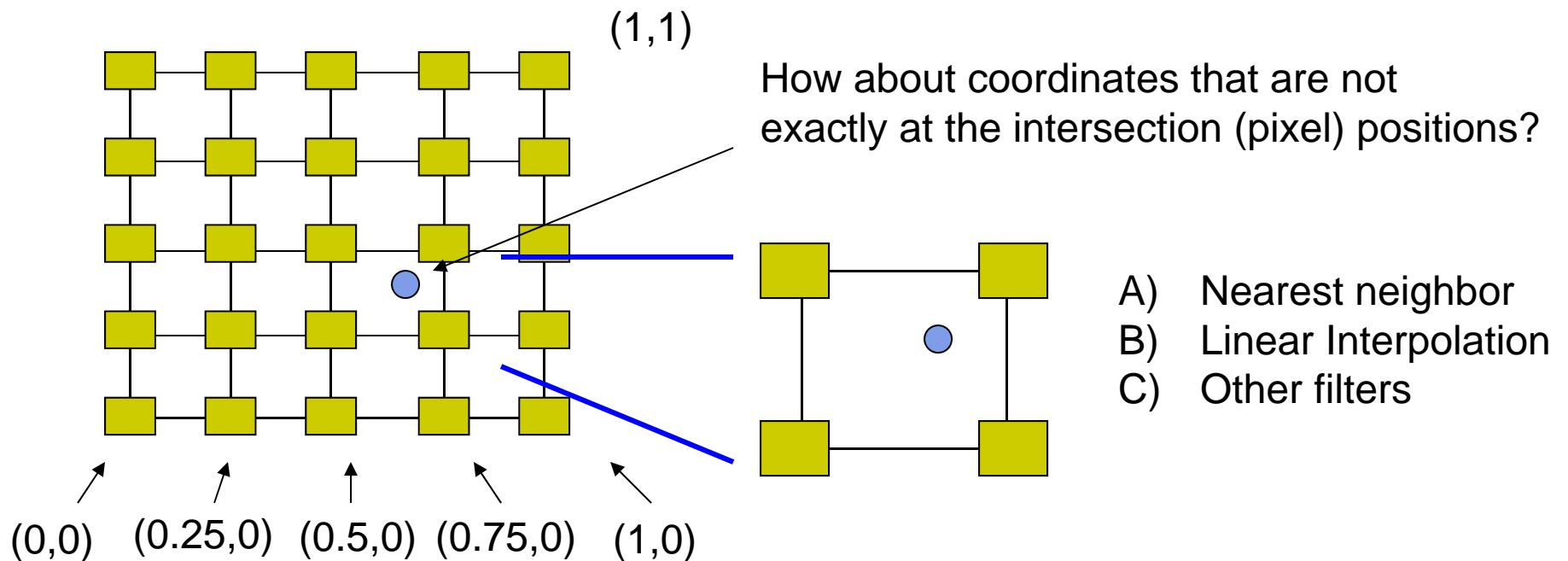
Bitmap texture:

- A 2D image - represented by 2D array `texture[height][width]`
- Each pixel (or called **texel**) by a unique pair texture coordinate (s, t)
- The s and t are usually normalized to a $[0,1]$ range
- For any given (s,t) in the normalized range, there is also a unique image value (i.e., a unique [red, green, blue] set)



Texture Value Lookup

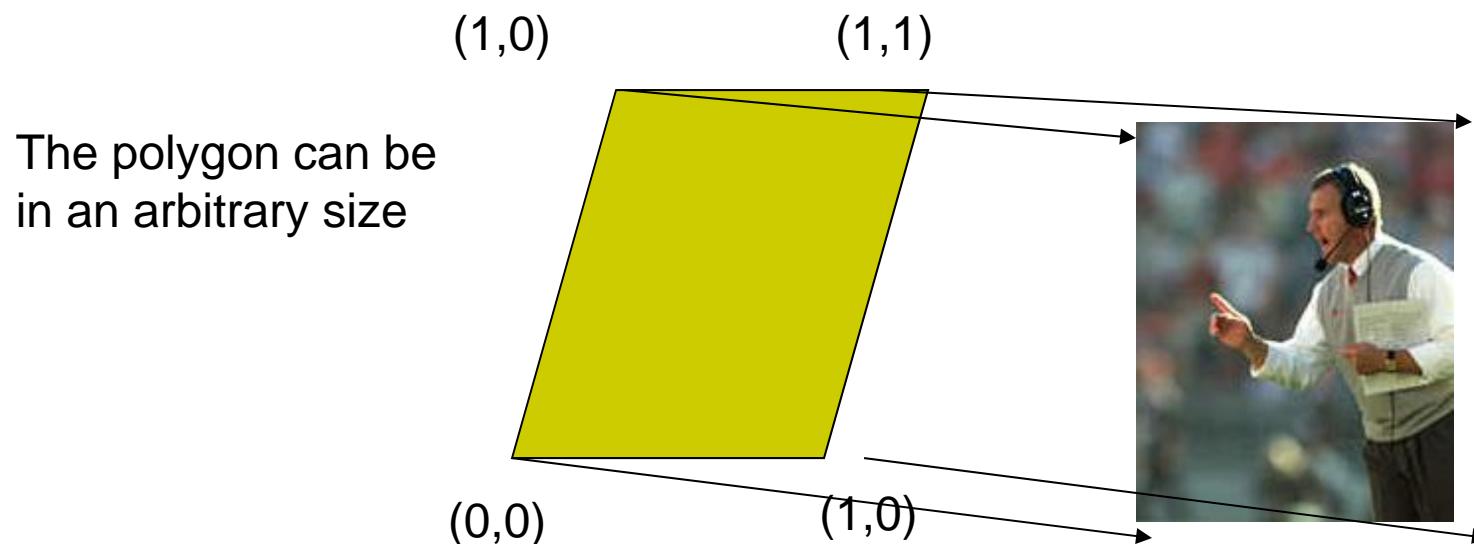
- For given texture coordinates (s,t) , we can find a unique image value from the texture map





Map textures to surfaces

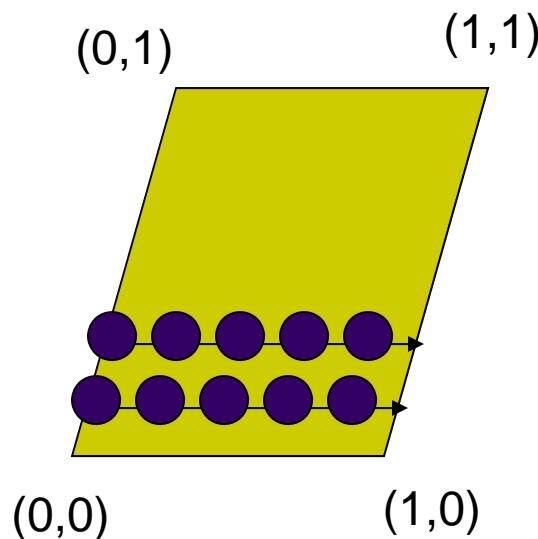
- Establish mapping from texture to surfaces (polygons):
 - Application program needs to specify **texture coordinates** for each corner of the polygon



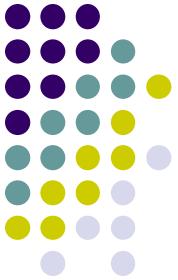


Map textures to surfaces

- Texture mapping is performed in rasterization



- For each pixel that is to be painted, its texture coordinates (s, t) are determined (interpolated) based on the corners' texture coordinates (why not just interpolate the color?)
- The interpolated texture coordinates are then used to perform texture lookup



Fix texture size

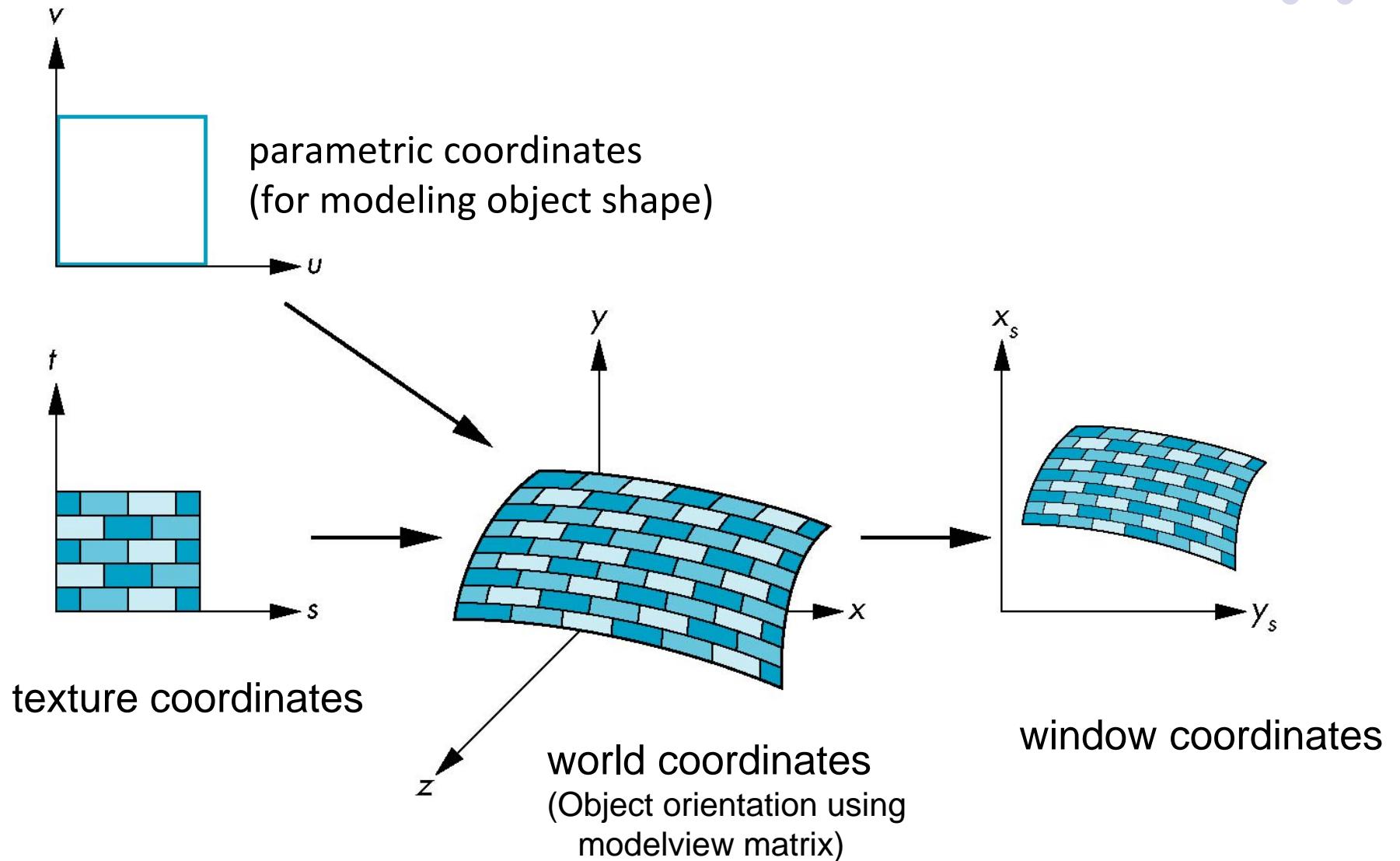
- OpenGL textures must be power of 2
- If the dimensions of the texture map are not power of 2, you can
 - 1) Pad zeros
 - 2) Scale the Image



128

Remember to adjust the texture coordinates
for your polygon corners – you don't want to
Include black texels in your final picture

Texture Mapping



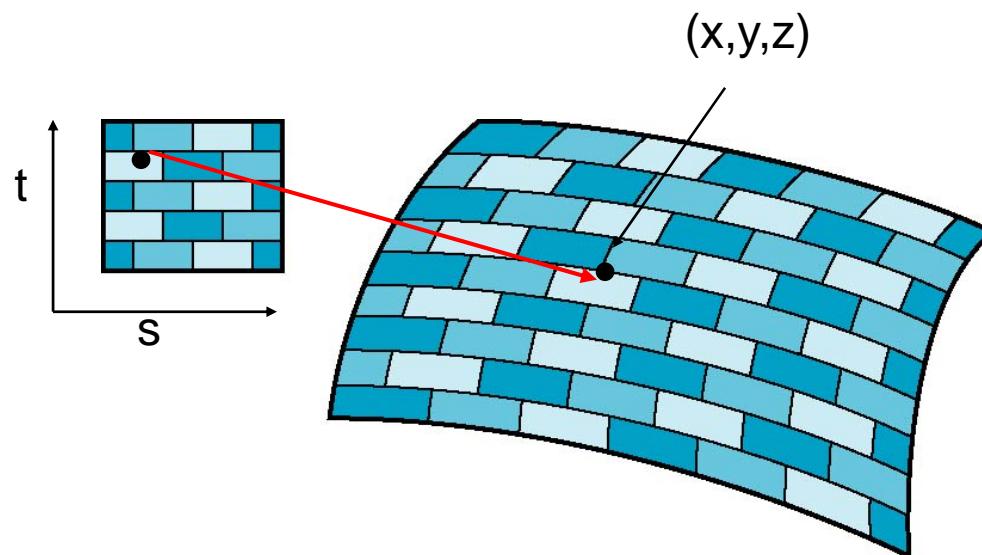


Texture Mapping

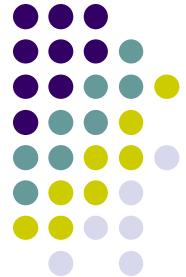
- Given a point on an object, we want to know to which point in the texture it corresponds
- Need a map of the form

$$s = s(x, y, z)$$

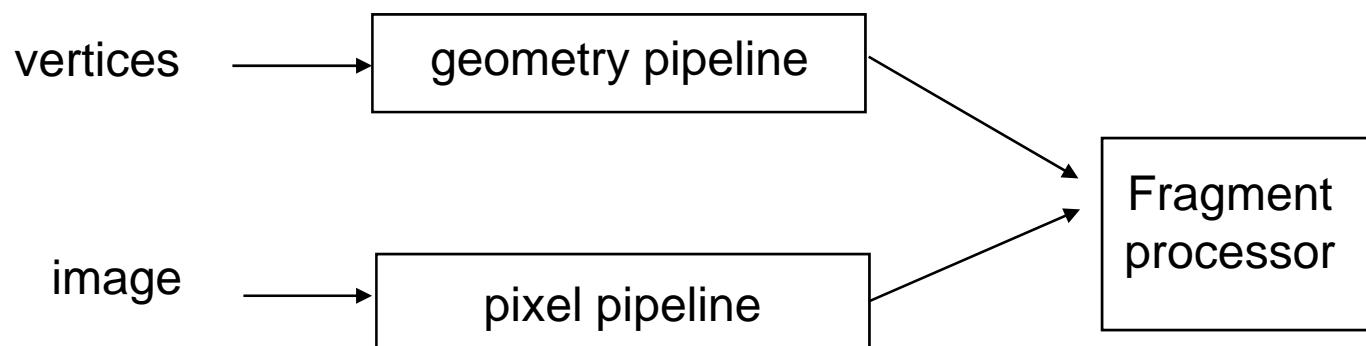
$$t = t(x, y, z)$$

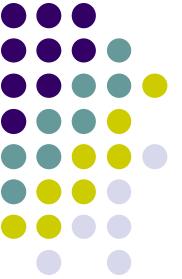


Texture Mapping and the OpenGL Pipeline



- Images and geometry flow through separate pipelines that join during fragment processing
 - Object geometry: geometry pipeline
 - Image: pixel pipeline
 - “complex” textures do not affect geometric complexity

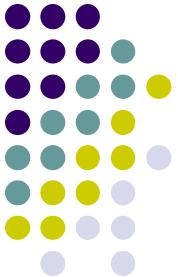




Basic Strategy

Three steps to applying a texture

1. specify the texture
 - Read or generate image
 - assign to texture
 - enable texturing
2. assign texture coordinates to vertices
 - Proper mapping function is left to application
3. specify texture parameters
 - wrapping, filtering

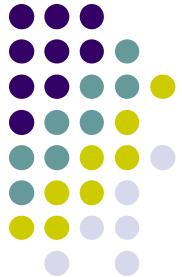


2D Texture Mapping

- OpenGL has **texture objects** for storing each texture image + texture parameters
- So, first step is to setting up texture object

```
GLuint mytex[1];
glGenTextures(1, mytex);           // Get new texture identifier
 glBindTexture(GL_TEXTURE_2D, mytex[0]); // Form new texture object
```

- Subsequent texture functions use this object
- Another call to **glBindTexture** with new name starts new texture object



Step 1: Specifying a Texture Image

- Define a texture image from an array of *texels* (texture elements) in CPU memory

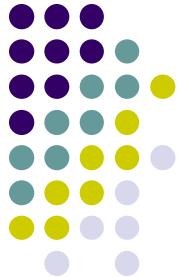
```
Glubyte my_texels[512][512][3];
```

- Define as any other pixel map

- Read in scanned images (jpeg, png, bmp, etc files)
- If uncompressed (e.g bitmap), read in directly from disk into array
- If compressed (e.g. jpeg), you may use third party tools like Qt or devil

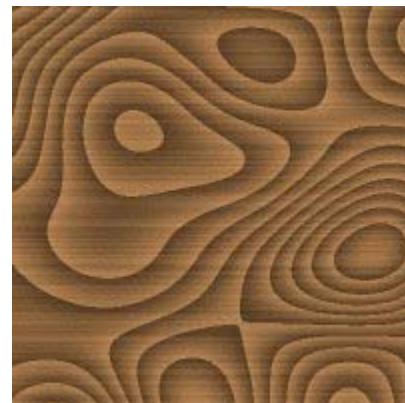
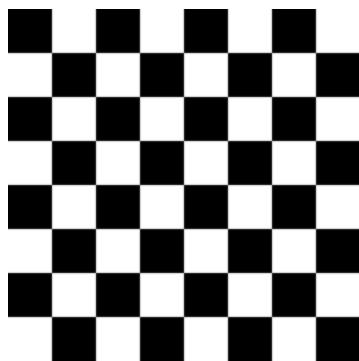


bmp, jpeg, png, etc



Step 1: Specifying a Texture Image

- Define as any other pixel map
 - Alternatively generate by application code. E.g. procedural texture



- Enable texture mapping
 - `glEnable(GL_TEXTURE_2D)`
 - OpenGL supports 1-4 dimensional texture maps



Define Image as a Texture

```
glTexImage2D( target, level, components,  
              w, h, border, format, type, texels );
```

target: type of texture, e.g. `GL_TEXTURE_2D`

level: used for mipmapping (discussed later)

components: elements per texel

w, h: width and height of `texels` in pixels

border: used for smoothing (discussed later)

format and type: describe texels

texels: pointer to texel array

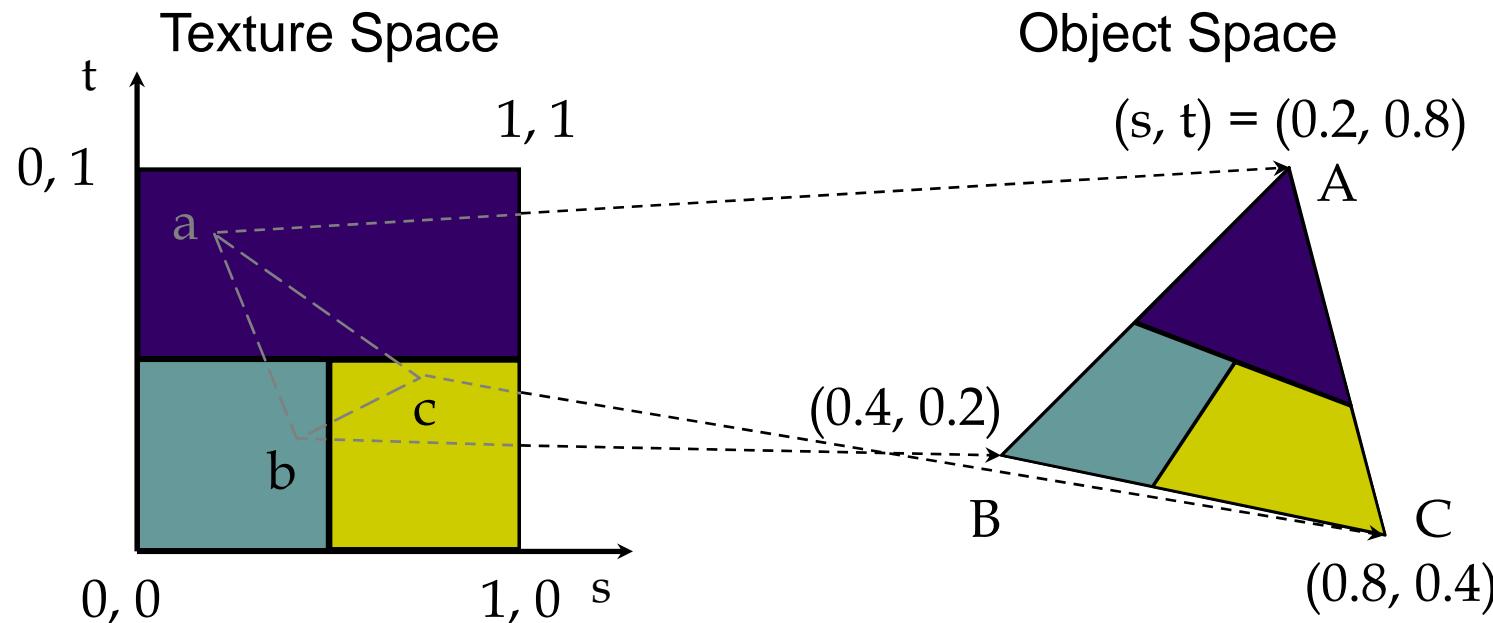
E.g

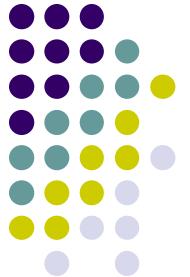
```
glTexImage2D(GL_TEXTURE_2D, 0, 3, 512, 512, 0,  
             GL_RGB, GL_UNSIGNED_BYTE, my_texels);
```



Assigning Texture Coordinates

- Specify texture (s,t) coordinate each vertex (x,y,z) coordinate maps to
- E.g: (s,t) of *a* in texture => (x,y,z) of *A* on object
- Texture coordinates specified at each vertex

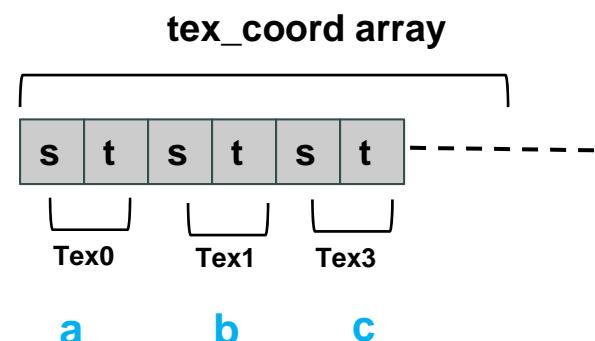
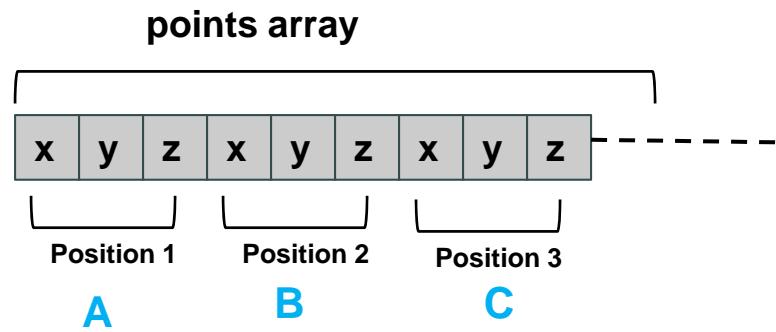




Code for Assigning Texture Coordinates

- Example: Trying to map a picture to a quad
- For each quad specify vertex (x,y,z), as well as texture coordinate it maps to in picture
- May generate array of vertices + array of texture coordinates

```
points[i] = point3(2,4,6);
tex_coord[i] = point2(0.0, 1.0);
```





Adding Texture Coordinates

```
void quad( int a, int b, int c, int d )  
{  
    quad_colors[Index] = colors[a];  
    points[Index] = vertices[a];  
    tex_coords[Index] = vec2( 0.0, 0.0 );  
    index++;  
    quad_colors[Index] = colors[b];  
    points[Index] = vertices[b];  
    tex_coords[Index] = vec2( 0.0, 1.0 );  
    Index++;  
  
    // other vertices  
}
```



Passing Texture data

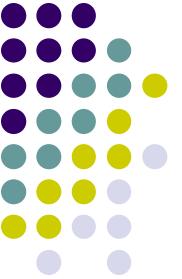
- Pass vertex, texture coordinate data as vertex array
- Set texture unit

```
offset = 0;
GLuint vPosition = glGetAttribLocation( program, "vPosition" );
 glEnableVertexAttribArray( vPosition );
 glVertexAttribPointer( vPosition, 4, GL_FLOAT, GL_FALSE,
 0,BUFFER_OFFSET(offset) );

offset += sizeof(points);
GLuint vTexCoord = glGetAttribLocation( program, "vTexCoord" );
 glEnableVertexAttribArray( vTexCoord );
 glVertexAttribPointer( vTexCoord, 2,GL_FLOAT,
 GL_FALSE, 0, BUFFER_OFFSET(offset) );

// Set the value of the fragment shader texture sampler variable
// ("texture") to the the appropriate texture unit.

glUniform1i( glGetUniformLocation(program, "texture"), 0 );
```



Vertex Shader

- Vertex shader receives data, output texture coordinates to be rasterized => to fragment shader
- Must do all other standard tasks too
 - Compute vertex position
 - Compute vertex color if needed

```
in vec4 vPosition; //vertex position in object coordinates  
in vec4 vColor; //vertex color from application  
in vec2 vTexCoord; //texture coordinate from application
```

```
out vec4 color; //output color to be interpolated  
out vec2 texCoord; //output tex coordinate to be interpolated
```

```
texCoord = vTexCoord  
color = vColor  
gl_Position = modelview * projection * vPosition
```



Applying Textures

- Textures are applied during fragments shading by a **sampler**
- Samplers return a texture color from a texture object

```
in vec4 color; //color from rasterizer  
in vec2 texCoord; //texture coordinate from rasterizer  
uniform sampler2D texture; //texture object from application
```

```
void main() {  
    gl_FragColor = color * texture2D( texture, texCoord );  
}
```

Output color
Of fragment

Original color
Of fragment

Lookup color of
texCoord (s,t) in texture



Linking with Shaders

```
GLuint vTexCoord = glGetUniformLocation( program, "vTexCoord" );
glEnableVertexAttribArray( vTexCoord );
 glVertexAttribPointer( vTexCoord, 2, GL_FLOAT, GL_FALSE, 0,
                      BUFFER_OFFSET(offset) );

// Set the value of the fragment shader texture sampler variable
// ("texture") to the the appropriate texture unit. In this case,
// zero, for GL_TEXTURE0 which was previously set by calling
// glActiveTexture().
glUniform1i( glGetUniformLocation(program, "texture"), 0 );
```



Texture Parameters

- OpenGL has a variety of parameters that determine how texture is applied
 - **Wrapping parameters** determine what happens if s and t are outside the (0,1) range
 - **Filter modes allow us to use area averaging instead of point samples**
 - **Mipmapping** allows us to use textures at multiple resolutions
 - **Environment** parameters determine how texture mapping interacts with shading

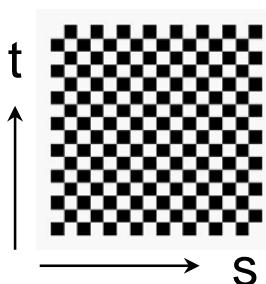


Wrapping Mode

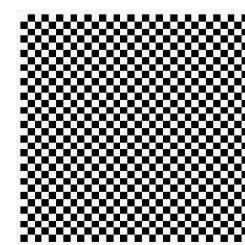
Clamping: if $s, t > 1$ use 1, if $s, t < 0$ use 0

Wrapping: use s, t modulo 1

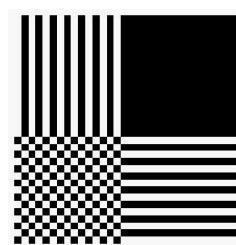
```
glTexParameteri( GL_TEXTURE_2D,  
                  GL_TEXTURE_WRAP_S, GL_CLAMP )  
  
glTexParameteri( GL_TEXTURE_2D,  
                  GL_TEXTURE_WRAP_T, GL_REPEAT )
```



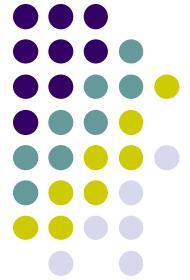
texture



GL_REPEAT
wrapping



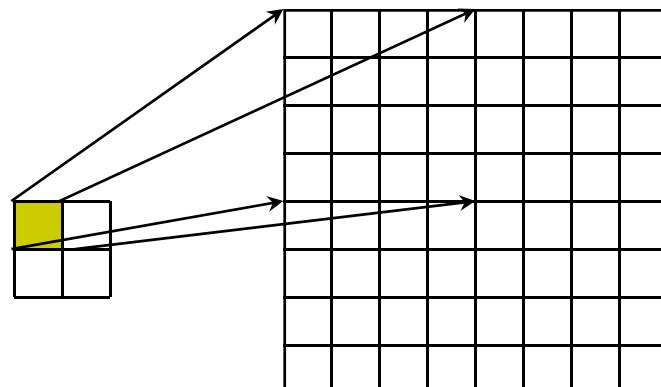
GL_CLAMP
wrapping



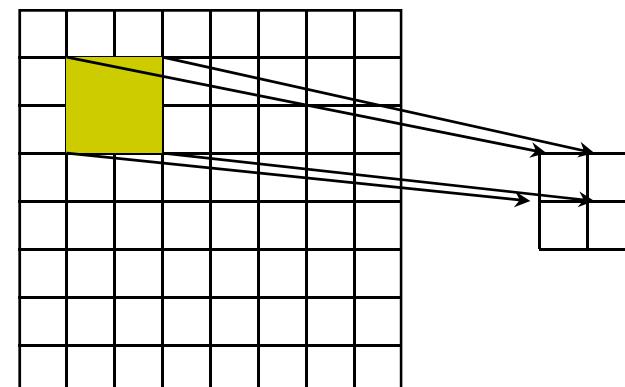
Magnification and Minification

More than one texel can cover a pixel (*minification*) or more than one pixel can cover a texel (*magnification*)

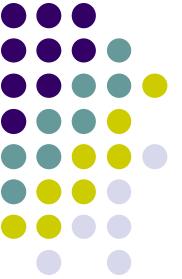
Can use point sampling (nearest texel) or linear filtering (2 x 2 filter) to obtain texture values



Texture
Magnification



Texture
Minification



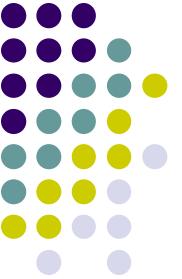
Filter Modes

Modes determined by

- `glTexParameterI(target, type, mode)`

```
glTexParameterI(GL_TEXTURE_2D, GL_TEXTURE_MAG_FILTER,  
                GL_NEAREST);
```

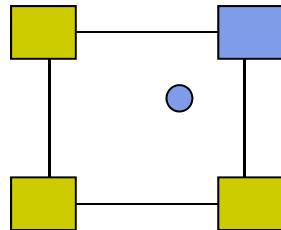
```
glTexParameterI(GL_TEXTURE_2D, GL_TEXTURE_MIN_FILTER,  
                GL_LINEAR);
```



Texture mapping parameters

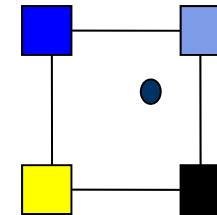
- OpenGL texture filtering:
- E.g. minification: pixel maps to more than 1 texel

1) Nearest Neighbor (lower image quality)



```
glTexParameteri(GL_TEXTURE_2D,  
GL_TEXTURE_MIN_FILTER, GL_NEAREST);
```

2) Linear interpolate the neighbors
(better quality, slower)



```
glTexParameteri(GL_TEXTURE_2D,  
GL_TEXTURE_MIN_FILTER,  
GL_LINEAR)
```

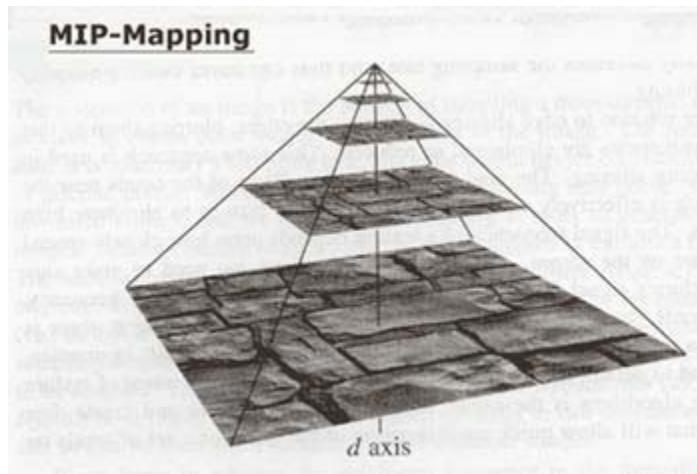
Or `GL_TEXTURE_MAX_FILTER`



Mipmapped Textures

- *Mipmapping* allows for prefiltered texture maps of decreasing resolutions
- Declare mipmap level during texture definition

```
glTexImage2D( GL_TEXTURE_*D, level, ... )
```





Texture Functions

- Controls how texture is applied
 - `glTexEnv{fi}[v](GL_TEXTURE_ENV, prop, param)`
- `GL_TEXTURE_ENV_MODE` modes
 - `GL_MODULATE`: multiply texture and object color
 - `GL_BLEND`: linear combination of texture and object color
 - `GL_REPLACE`: use only texture color
 - `GL(GL_TEXTURE_ENV, GL_TEXTURE_ENV_MODE,
GL_MODULATE);`
- E.g: `glTexEnvf(GL_TEXTURE_ENV, GL_TEXTURE_ENV_MODE,
GL_REPLACE);`



Other Stuff

- Wrapping texture onto curved surfaces. E.g. cylinder, can, etc

$$s = \frac{\theta - \theta_a}{\theta_b - \theta_a} \quad t = \frac{z - z_a}{z_b - z_a}$$

- Wrapping texture onto sphere

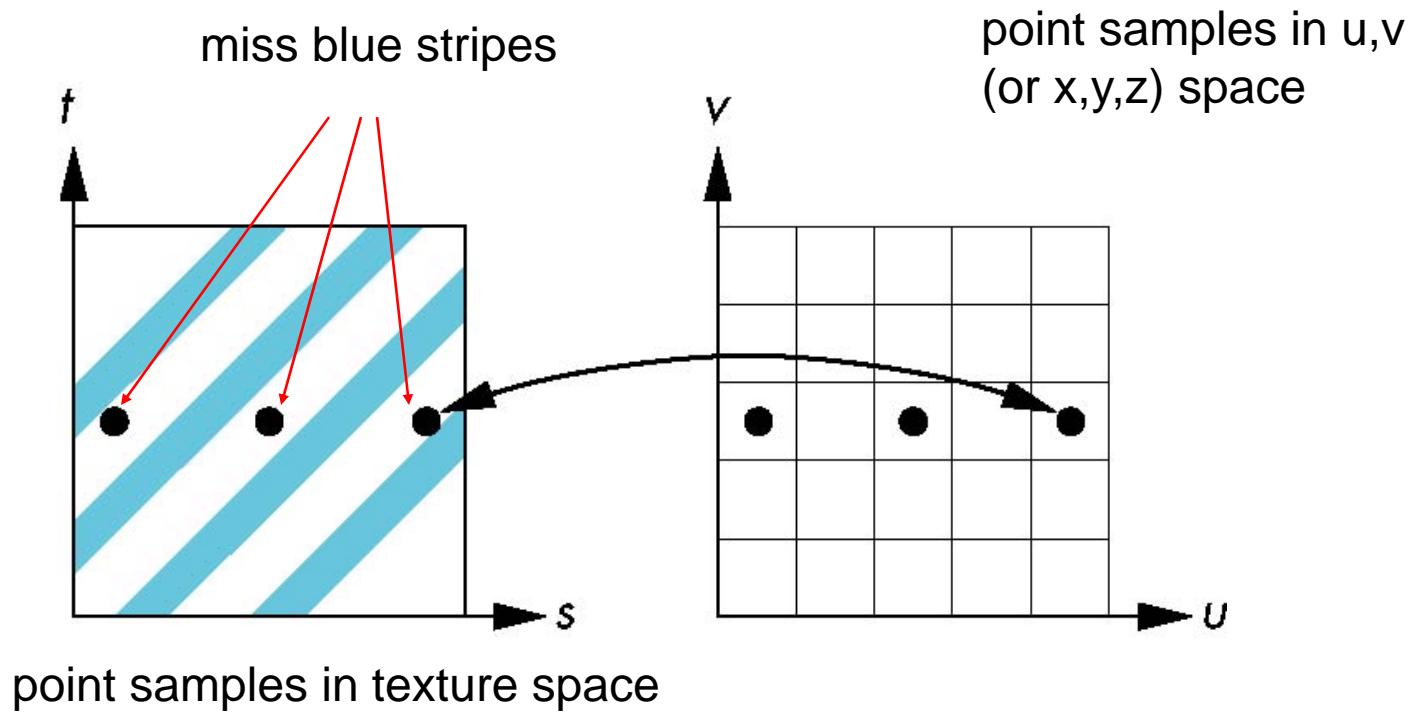
$$s = \frac{\theta - \theta_a}{\theta_b - \theta_a} \quad t = \frac{\phi - \phi_a}{\phi_b - \phi_a}$$

- Bump mapping: perturb surface normal by a quantity proportional to texture



Aliasing

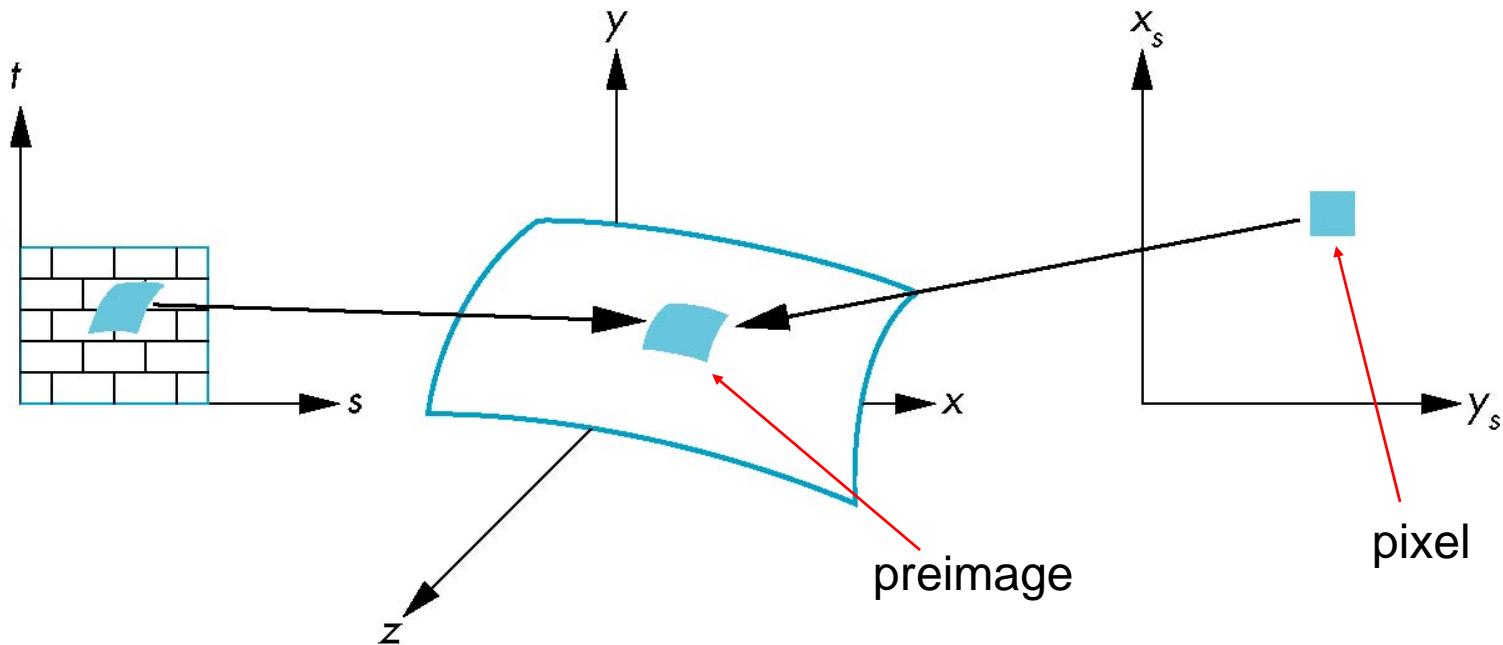
- Point sampling of the texture can lead to aliasing errors





Area Averaging

A better but slower option is to use *area averaging*

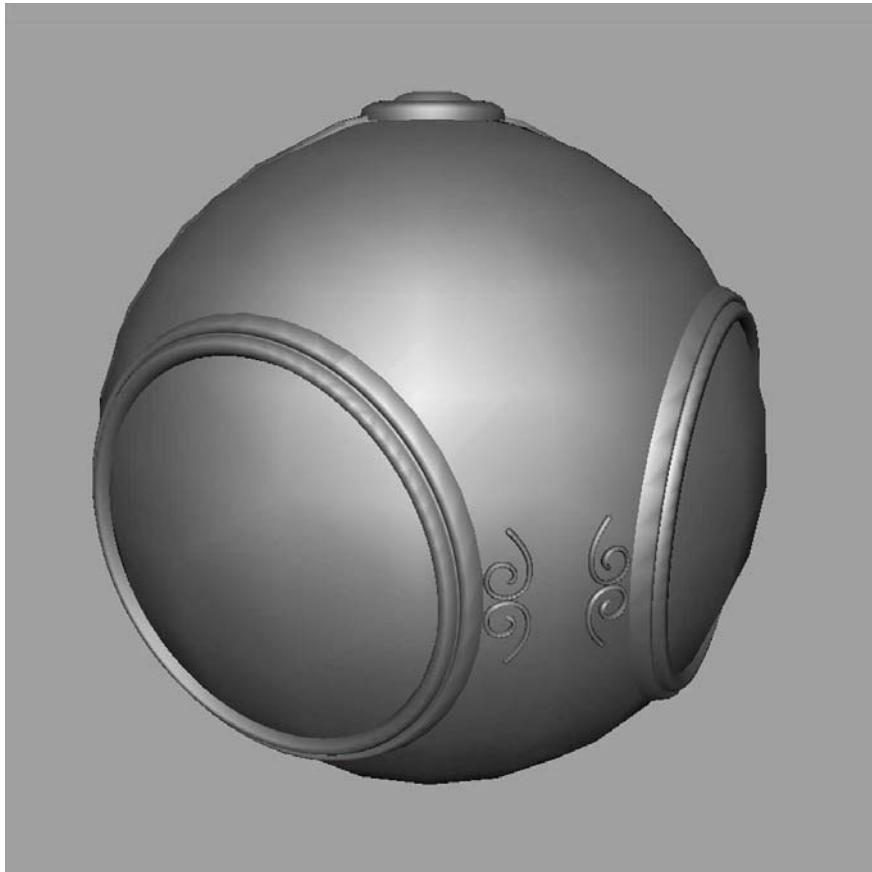


Note that *preimage* of pixel is curved



Environment Mapping

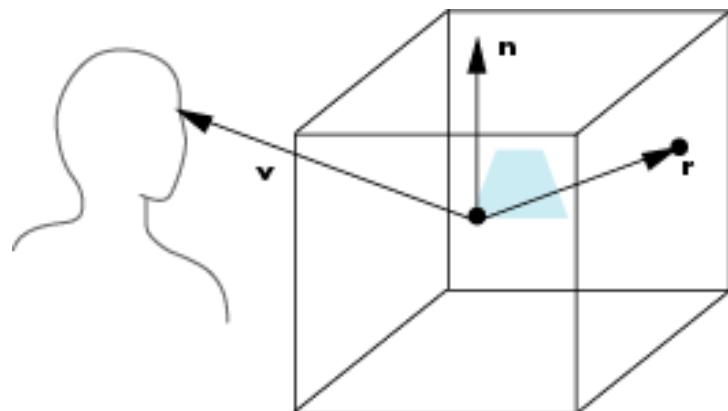
- Environmental mapping is way to create the appearance of highly reflective surfaces





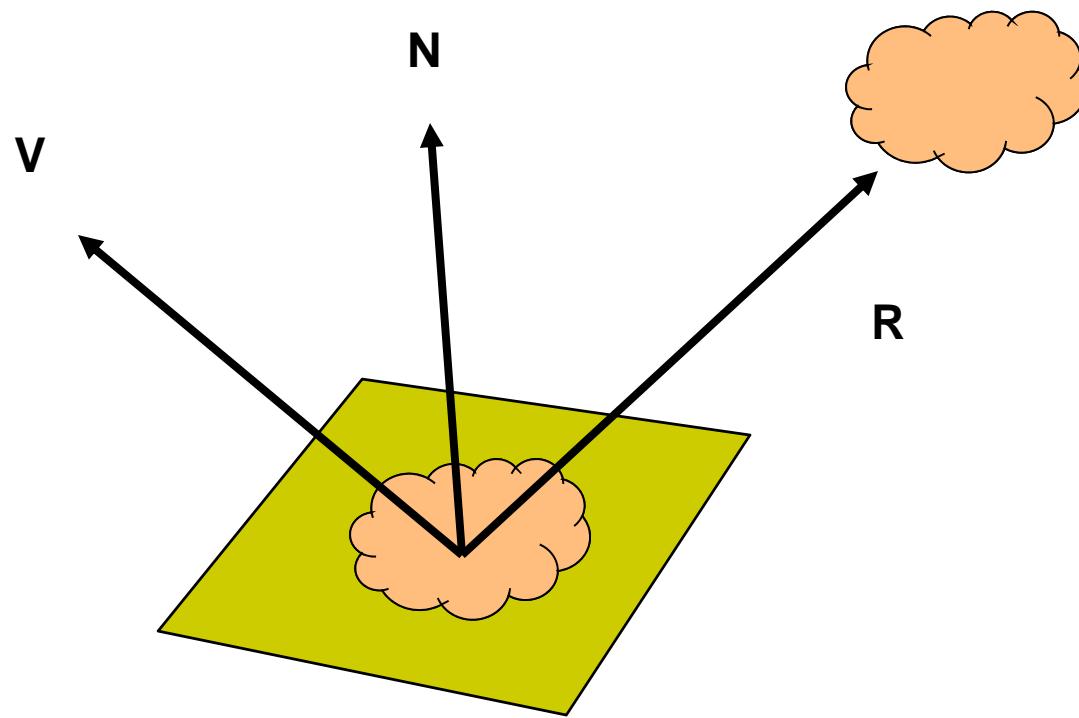
Environment Map

Use reflection vector to locate texture in cube map



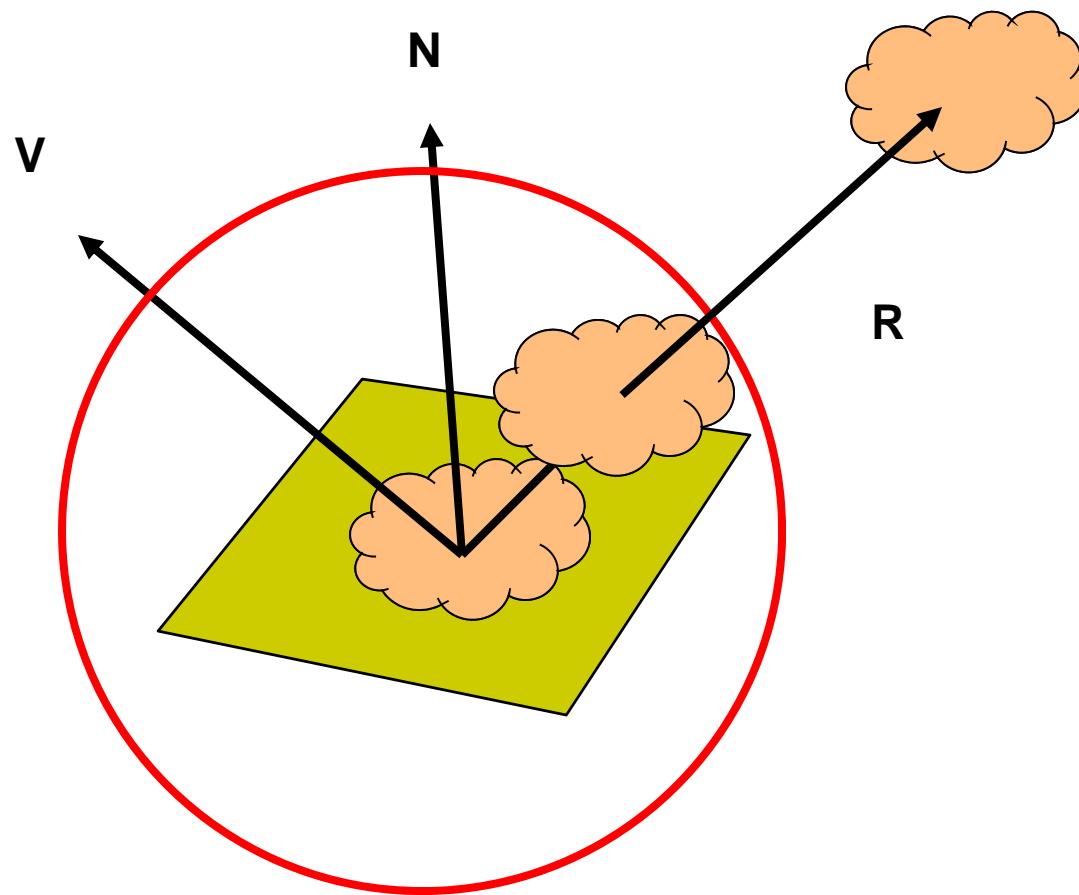


Reflecting the Environment

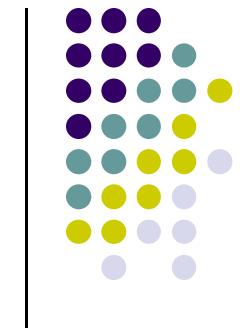
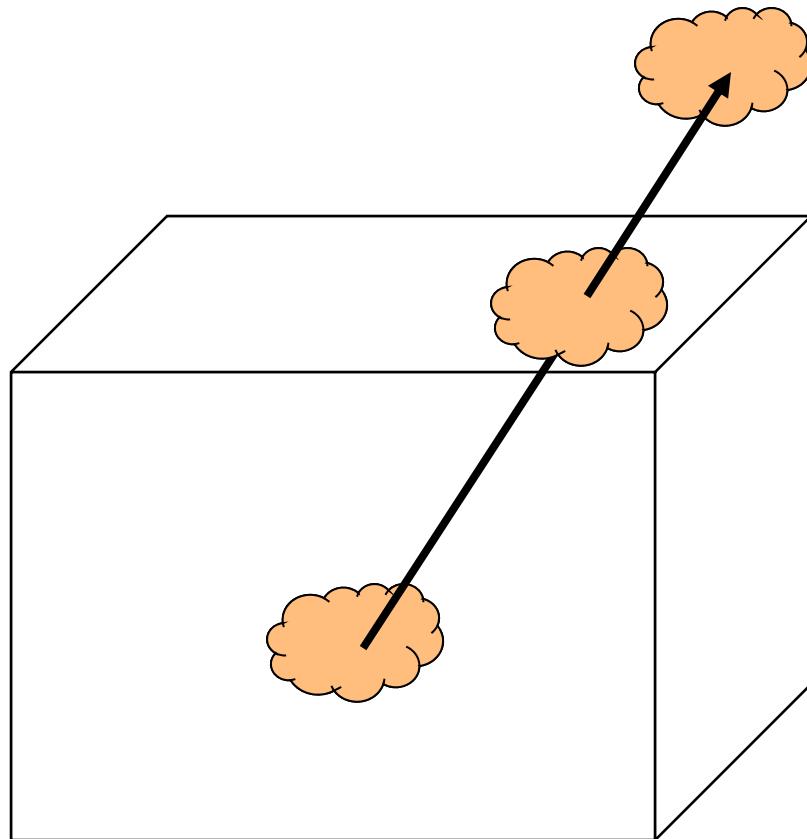




Mapping to a Sphere



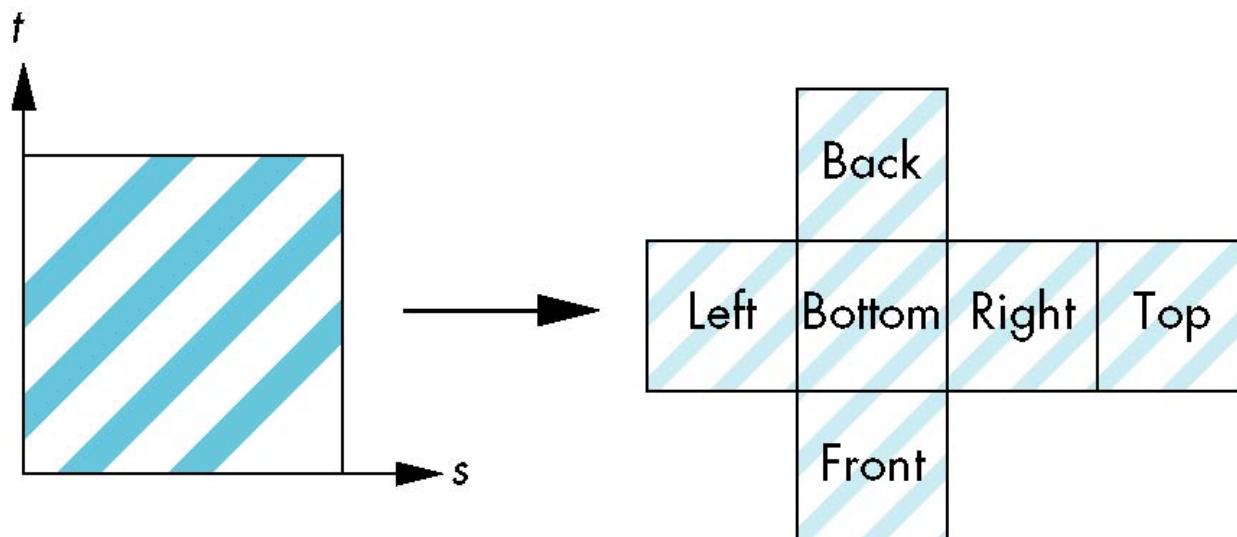
Cube Map



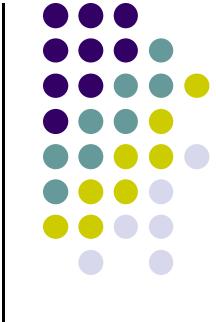


Box Mapping

- Map environment map to sides of a box

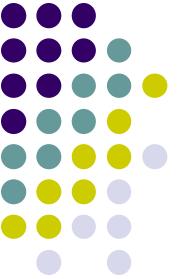


Cube Maps



- Cube map texture (as 6 sides of box) supported by OpenGL
- Can be accessed in GLSL through cubemap sampler

```
vec4 texColor = textureCube(mycube, texcoord);
```
- Texture coordinates must be 3D



References

- Interactive Computer Graphics (6th edition), Angel and Shreiner
- Computer Graphics using OpenGL (3rd edition), Hill and Kelley