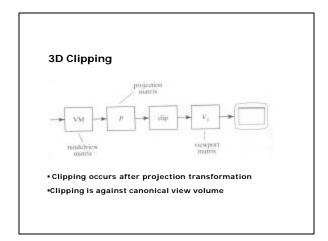
CS 4731: Computer Graphics Lecture 14: 3D Clipping andViewport Transformation Emmanuel Agu

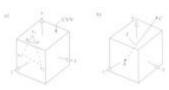


## **3D Clipping**

- 3D clipping against canonical view volume (CVV)
- Automatically clipping after projection matrix
- Liang-Barsky algorithm (embellished by Blinn)
- CVV == 6 infinite planes (x=-1,1;y=-1,1;z=-1,1)
- Clip edge-by-edge of the an object against CVV
- Chopping may change number of sides of an object. E.g. chopping tip of triangle may create quadrilateral

## **3D Clipping**

- Problem:
  - Two points, A = (Ax, Ay, Az, Aw) and C = (Cx, Cy, Cz, Cw), in homogeneous coordinates
     If segment intersects with CVV, need to compute intersection point I-=(Ix, Iy, Iz, Iw)



## **3D Clipping**

- Represent edge parametrically as A + (C A)t
- Intepretation: a point is traveling such that:
  - at time t=0, point at A
  - at time t=1, point at C
- Like Cohen-Sutherland, first determine trivial accept/reject
   E.g. to test edge against plane, point is:
- - Inside (right of plane x=-1) if Ax/Aw > -1 or (Aw+Ax)>0
  - Inside (left of plane x=1) if Ax/Aw < 1 or (Aw-Ax) > 0



#### 3D Clipping

■ Using notation (Aw +Ax) = w + x, write boundary coordinates for 6 planes as:

Boundary	Homogenous	Clip plane
BCO	W+X	x=-1
BC1		X=1
BC2	V+Y	y=-1
BC3	w-v	v=1
8C4	W+Z	i=-1
BC5	w-z	z=1

•Trivial accept: 12 BCs (6 for pt. A, 6 for pt. C) are positive

•Trivial reject: Both endpoints outside of same plane

## **3D Clipping**

- If not trivial accept/reject, then clip
- Define Candidate Interval (CI) as time interval during which edge might still be inside CVV. i.e. CI = t\_in to t\_out



- Conversely: values of t outside CI = edge is outside CVV
- Initialize CI to [0,1]

#### **3D Clipping**

- How to calculate t\_hit?
- Represent an edge t as:

Edge(t) = ((Ax + (Cx - Ax)t, (Ay + (Cy - Ay)t, (Az + (Cz - Az)t, (Aw + (Cw - Aw)t))))

• E.g. If 
$$x = 1$$
, 
$$\frac{Ax + (Cx - Ax)t}{Aw + (Cw - Aw)t} = 1$$

Solving for t above,

$$t = \frac{Aw - Ax}{(Aw - Ax) - (Cw - Cx)}$$

## **3D Clipping**

- Test against each wall in turn
- If BCs have opposite signs = edge hits plane at time t\_hit
- Define: "entering" = as t increases, outside to inside
- i.e. if pt. A is outside, C is inside
- Likewise, "leaving" = as t increases, inside to outside (A inside, C outside)

#### **3D Clipping**

- Algorithm:
  - Test for trivial accept/reject (stop if either occurs)
  - Set CI to [0,1]
  - For each of 6 planes:
    - Find hit time t\_hit
    - If, as t increases, edge entering, t\_in = max(t\_in,t\_hit)
    - If, as t increases, edge leaving, t\_out = min(t\_out, t\_hit)
    - If  $t_{in} > t_{out} =$  exit (no valid intersections)

Note: seeking smallest valid CI without t\_in crossing t\_out

# **3D Clipping** Example to illustrate search for t\_in, t\_out Note: CVV is different shape. This is just example 0.01 1110 Gris b mi

#### **3D Clipping**

- If valid t\_in, t\_out, calculate adjusted edge endpoints A, C as
- $\blacksquare$  A\_chop = A + t\_in ( C A)
- $\blacksquare$  C\_chop = C + t\_out ( C-A)

#### 3D Clipping Implementation

- Function clipEdge()
- Input: two points A and C (in homogenous coordinates)
- Output:
  - 0, if no part of line AC lies in CVV
    1, otherwise

  - Also returns clipped A and C
- Store 6 BCs for A, 6 for C

#### 3D Clipping Implementation

- Use outcodes to track in/out

  - Number walls 1... 6
    Bit i of A's outcode = 0 if A is inside ith wall
- 1 otherwiseTrivial accept: both A and Coutcodes = 0
- Trivial reject: bitwise AND of A and Coutcodes is non-zero
- If not trivial accept/reject:
  - Compute tHit

  - Update t\_in, t\_out
    If t\_in > t\_out, early exit

#### **3D Clipping Pseudocode**

```
int clipEdge(Point4& A, Point4& C)
    double tIn = 0.0, tOut = 1.0, tHit;
double aBC[6], cBC[6];
int aOutcode = 0, cOutcode = 0;
    .....find BCs for A and C .....form outcodes for A and C
    if((aOutCode & cOutcode) != 0) // trivial reject
    return 0;
if((aOutCode | cOutcode) == 0) // trivial accept
       return 1:
```

#### 3D Clipping Pseudocode

```
for(i=0;i<6;i++) // clip against each plane
   if(cBC[I] < 0) // exits: C is outside
         \mathsf{tHit} = \mathsf{aBC[I]/(aBC[I] - cBC[I])};
         tOut = MIN(tOut, tHit);
   else if(aBC[i] < 0) // enters: A is outside
         tHit = aBC[i]/(aBC[i] - cBC[i]);
tIn = MAX(tIn, tHit);
   if(tIn > tOut) return 0; // CI is empty: early out
```

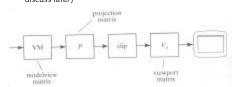
#### **3D Clipping Pseudocode**

```
Point4 tmp; // stores homogeneous coordinates If(aOutcode!= 0) // A is out: IIn has changed
   tmp.x = A.x + tIn * (C.x - A.x);
// do same for y, z, and w components
}
If(cOutcode != 0) // C is out: tOut has changed
   C.x = A.x + tOut * (C.x - A.x);
    // do same for y, z and w components
A = tmp;
Return 1; // some of the edges lie inside CVV
```

## **Viewport Transformation**

- After clipping, do viewport transformation
- We have used glViewport(x,y, wid, ht) before
   Use again here!!

- glViewport shifts x, y to screen coordinates
  Also maps pseudo-depth z from range [-1,1] to [0,1]
  Pseudo-depth stored in depth buffer, used for Depth testing (Will



## References

■ Hill, sections 7.4.4, 4.8.2