PARALLEL & DISTRIBUTED DATABASES

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INTRODUCTION

In centralized database:

- Data is located in one place (one server)
- All DBMS functionalities are done by that server
 - Enforcing ACID properties of transactions
 - Concurrency control, recovery mechanisms
 - Answering queries

In Distributed databases:

- Data is stored in multiple places (each is running a DBMS)
- New notion of distributed transactions
- DBMS functionalities are now distributed over many machines
 - Revisit how these functionalities work in distributed environment

WHY DISTRIBUTED DATABASES

- Data is too large
- Applications are by nature distributed
 - Bank with many branches
 - Chain of retail stores with many locations
 - Library with many branches
- Get benefit of distributed and parallel processing
 - Faster response time for queries

PARALLEL VS. DISTRIBUTED DATABASES

- Distributed processing usually imply parallel processing (not vise versa)
 - Can have parallel processing on a single machine

Assumptions about architecture

Parallel Databases

- Machines are physically close to each other, e.g., same server room
- Machines connects with dedicated high-speed LANs and switches
- Communication cost is assumed to be small
- Can shared-memory, shared-disk, or shared-nothing architecture

Distributed Databases

- Machines can far from each other, e.g., in different continent
- Can be connected using public-purpose network, e.g., Internet
- Communication cost and problems cannot be ignored
- Usually shared-nothing architecture

PARALLEL DATABASE & & PARALLEL PROCESSING

WHY PARALLEL PROCESSING



- Divide a big problem into many smaller ones to be solved in parallel
- Increase bandwidth (in our case decrease queries' response time)

DIFFERENT ARCHITECTURE

• Three possible architectures for passing information



Shared-disk



Shared-nothing



1- SHARED-MEMORY ARCHITECTURE

- Every processor has its own disk
- Single memory address-space for all processors
 - Reading or writing to far memory can be slightly more expensive
- Every processor can have its own local memory and cache as well



2- SHARED-DISK ARCHITECTURE

- Every processor has its own memory (not accessible by others)
- All machines can access all disks in the system
- Number of disks does not necessarily match the number of processors



3- SHARED-NOTHING ARCHITECTURE

- Most common architecture nowadays
- Every machine has its own memory and disk
 - Many cheap machines (commodity hardware)
- Communication is done through highspeed network and switches
- Usually machines can have a hierarchy
 - Machines on same rack
 - Then racks are connected through highspeed switches



- Scales better
- Easier to build
- Cheaper cost

TYPES OF PARALLELISM

Pipeline Parallelism (Inter-operator parallelism)

• Ordered (or partially ordered) tasks and different machines are performing different tasks



- Partitioned Parallelism (Intra-operator parallelism)
 - A task divided over all machines to run in parallel



IDEAL SCALABILITY SCENARIO

• Speed-Up

 More resources means proportionally less time for given amount of data.

• Scale-Up

• If resources increased in proportion to increase in data size, time is constant.



PARTITIONING OF DATA

To partition a relation R over m machines



Hash-based partitioning

A...E F...J K...N O...S T...Z

Round-robin partitioning



- Shared-nothing architecture is sensitive to partitioning
- Good partitioning depends on what operations are common

PARALLEL ALGORITHMS FOR DBMS OPERATIONS

PARALLEL SCAN $\sigma_c(R)$

- Relation R is partitioned over *m* machines
 - Each partition of R is around |R|/m tuples
- Each machine scans its own partition and applies the selection condition c
- If data are partitioned using round robin or a hash function (over the entire tuple)
 - The resulted relation is expected to be well distributed over all nodes
 - All partitioned will be scanned
- If data are range partitioned or hash-based partitioned (on the selection column)
 - The resulted relation can be clustered on few nodes
 - Few partitions need to be touched
 - Parallel Projection is also straightforward
 - All partitions will be touched
 - Not sensitive to how data is partitioned

PARALLEL DUPLICATE ELIMINATION

• If relation is range or hash-based partitioned

- Identical tuples are in the same partition
- So, eliminate duplicates in each partition independently

If relation is round-robin partitioned

- Re-partition the relation using a hash function
- So every machine creates m partitions and send the ith partition to machine i
- machine i can now perform the duplicate elimination
 - Same idea applies to Set Operations (Union, Intersect, Except)
 - But apply the same partitioning to both relations R & S

PARALLEL JOIN $R(X,Y) \bowtie S(Y,Z)$

- Re-partition R and S on the join attribute Y (natural join) or (equi join)
 - Hash-based or range-based partitioning
- Each machine i receives all ith partitions from all machines (from R and S)
 - Each machine can locally join the partitions it has
- Depending on the partitions sizes of R and S, local joins can be hash-based or merge-join



PARALLEL SORTING

Range-based

- Re-partition R based on ranges into m partitions
- Machine i receives all ith partitions from all machines and sort that partition
- The entire R is now sorted
- Skewed data is an issue
 - Apply sampling phase first
 - Ranges can be of different width



Merge-based

- Each node sorts its own data
- All nodes start sending their sorted data (one block at a time) to a single machine
- This machine applies merge-sort technique as data come

COMPLEX PARALLEL QUERY PLANS

- All previous examples are intra-operator parallelism
- Complex queries can have inter-operator parallelism
 - Different machines perform different tasks



PERFORMANCE OF PARALLEL ALGORITHMS

- In many cases, parallel algorithms reach their expected lower bound (or close to)
 - If parallelism degree is m, then the parallel cost is 1/m of the sequential cost
 - Cost mostly refers to query's response time

Example

Parallel selection or projection is 1/m of the sequential cost



PERFORMANCE OF PARALLEL ALGORITHMS (CONT'D)

- Total disk I/Os (sum over all machines) of parallel algorithms can be larger than that of sequential counterpart
 - But we get the benefit of being done in parallel

Example

- Merge-sort join (serial case) has I/O cost = 3(B(R) + B(S))
- Merge-sort join (parallel case) has total (sum) I/O cost = 5(B(R) + B(S))
 - Considering the parallelism = 5(B(R) + B(S)) / m

Number of pages of relations R and S

OPTIMIZING PARALLEL ALGORITHMS

- Best serial plan != the best parallel one
- Trivial counter-example:
 - Table partitioned with local secondary index at two nodes
 - Range query: all data of node 1 and 1% of node 2.
 - Node 1 should do a scan of its partition.
 - Node 2 should use secondary index.



- Different optimization algorithms for parallel plans (more candidate plans)
- Different machines may perform the same operation but using different plans

SUMMARY OF PARALLEL DATABASES

Three possible architectures

- Shared-memory
- Shared-disk
- Shared-nothing (the most common one)

Parallel algorithms

- Intra-operator
 - Scans, projections, joins, sorting, set operators, etc.
- Inter-operator
 - Distributing different operators in a complex query to different nodes

Partitioning and data layout is important and affect the performance

Optimization of parallel algorithms is a challenge