

The OS 502 Project



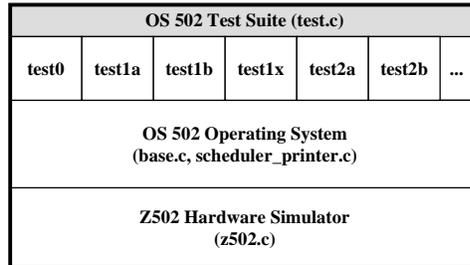
CS 502
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OS 502 Project Outline



- Architecture of the Simulator Environment
- Z502 Hardware Organization and Architecture
- Generic Operating System Structure
- The Test Suite
 - Phase 1 Tests
 - Phase 2 Tests

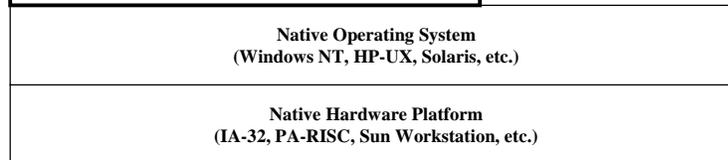
Simulator Environment



All elements inside the heavy box are in a single process, running a *single* thread of execution.

All I/O devices of the Z502 are simulated entities. This includes the timer device and the disk devices.

Try to treat the Z502 Hardware Simulator as a "black box" and use the Z502 architecture specification instead.



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Z502 Architecture

- Dual-Mode architecture
 - User mode (see A.4)
 - High level language, augmented with
 - Z502 General Purpose Registers
 - Macros for simplifying reentrant programs
 - Systems Calls, provided as macros (do *not* rewrite!)
 - Z502 "Programs" are written as C functions taking a void parameter and having a void return.

• Example Program:

```

void test0( void )
{
    SELECT_STEP
    {
        STEP( 0 )
        printf("This is test 0");
        GET_TIME_OF_DAY( &Z502_REG_1 );
        STEP( 1 )
        printf("Time of day is %d\n", Z502_REG_1);
        TERMINATE_PROCESS( -1, &Z502_REG_9 );
        STEP( 2 )
        printf("Error: Test should be terminated, but isn't\n");
        break;
    }
}
    
```

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Z502 Architecture (cont.)

- User Mode (cont.)
 - Address space for user programs is divided into
 - C code “program” memory for instructions and for local variables. This, for all intents and purposes, is not constrained in size.
 - User “data” memory, referenced through a virtual address space, and called MEMORY, and accessed from user space through the MEM_XXXX macros. No programs in phase 1 access this user memory.
- Kernel Mode
 - Instruction set includes C language instructions, plus
 - access to all the Z502 registers
 - access to Z502 physical memory (MEMORY)
 - access to the privileged instructions of the Z502 instruction set
 - I/O primitives
 - memory primitives
 - context switching primitives
 - These are all available through provided macros

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Z502 Registers and Vectors

Name	Bits	Usage
Z502_REG_ARG1 ... Z502_REG_ARG6	32	For passing system call parameter values
Z502_REG_1 ... Z502_REG_9	32	General purpose
Z502_REG_PROGRAM_COUNTER	32	Points to next location in user program
Z502_REG_PAGE_TABLE_ADDR	32	Points to page table
Z502_REG_PAGE_TABLE_LENGTH	32	Length of page table in 32 bit entries
Z502_REG_CURRENT_CONTEXT	32	Handle for current context
Z502_REG_INTERRUPT_MASK	32	Interrupt enable/disable
TO_VECTOR	3 x 32	Addresses of interruption handlers
STAT_VECTOR	2 x N x 32	Exception statuses

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Interruption Handling by the Z502



- **Interruption Sources**
 - Interrupts
 - TIMER_INTERRUPT from the delay timer
 - DISK_INTERRUPT from disk 1, 2, ...
 - Faults
 - INVALID_MEMORY fault
 - CPU_ERROR fault
 - PRIVILEGED_INSTRUCTION fault
 - Traps
 - SOFTWARE_TRAP for each system call
 - TO_VECTOR contains an address for each category of interruption source.

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Interruption Handling



- In `os_init` (the OS boot code), the OS sets values for each of the entries in `TO_VECTOR`.
- On the Z502, there is a total enumeration of all interruptions (exceptions)
 - SOFTWARE_TRAP
 - CPU_ERROR
 - INVALID_MEMORY
 - PRIVILEGED_INSTRUCTION
 - TIMER_INTERRUPT
 - DISK_INTERRUPT
 - DISK_INTERRUPT + 1
 - ...
 - LARGEST_STAT_VECTOR_INDEX

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Z502 Hardware Actions on Interruption

- Let the *interruption number* (called *exception* in Appendix A) be x .
- User registers are saved in *Z502 Hardware Context*
- Hardware sets
 - $\text{STAT_VECTOR}[\text{SV_ACTIVE}][x] = \text{TRUE}$
 - $\text{STAT_VECTOR}[\text{SV_VALUE}][x] = \text{interruption specific info}$
- Execution mode is set to *kernel*
- Hardware begins execution at Interrupt, Fault, or Trap entry point as defined by TO_VECTOR
- Note that INTERRUPT_MASK is not set to TRUE . The operating system must do this if that is the desired mode of operation.

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OS Responsibilities on an Interruption

- On Entry
 - Mask interrupts (if desired)
 - Clear the Interruption Source
 - set $\text{STAT_VECTOR}[\text{SV_ACTIVE}][x]$ to FALSE
 - Determine the cause of the interruption and process accordingly
- On Exit
 - Unmask interrupts (if not already done).
 - For Interrupts, simply *return*
 - For traps and faults, ultimately exit the OS by performing a context switch (even if that switches back to the original process). This operation restores the user registers from the *Z502 Hardware Context* and sets the execution mode back to *user*.

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Interruption Causes

- Use `STAT_VECTOR[SV_VALUE][x]` to determine an interruption cause and influence processing:
 - For `SOFTWARE_TRAP`, value is the system call number. Use this to enter a switch statement to process system calls.
 - For `CPU_ERROR`, value is given by error codes (see table in Appendix A)
 - For `INVALID_MEMORY`, value is virtual memory page causing the fault
 - For `PRIVILEGED_INSTRUCTION`, value is 0
 - For all interrupts (timer and disk), value is given by error codes (where one of the possibilities is `ERR_SUCCESS`)

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Z502 Hardware Context

- The *context* is the state of the executing CPU, essentially its registers.
- The Hardware context is essentially a register set, plus an entry address.
- The OS only deals with the handle to a context. Typically this is stored in the process control block.
- Z502 Operations for manipulating contexts
 - `Z502_MAKE_CONTEXT(handle, start address, kernel flag)`
 - `Z502_DESTROY_CONTEXT(handle)`
 - `Z502_SWITCH_CONTEXT(save/destroy flag, handle)`

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Operating System Structure

- Organize into functional areas
 - What are the functional areas of the Operating System?
 - What are the abstract data types required?
 - Class participation, putting together an OS structure...
- Next steps (Milestone 3)
 - Strawman functional spec for each module defined in the block diagram.
 - For each module
 - set of interrelations with other OS modules
 - portions of the Z502 interface being invoked by the module
 - Set of system calls realized within the module
 - For system calls
 - Categorization by module
 - Attributes: blocking vs. non-blocking, save/destroy context

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Milestone 4: test0

- Code given previously. Nearly the simplest user program possible.
- Requirements
 - Core OS
 - os_init
 - TO_VECTOR
 - trap_handler
 - System call switch
 - Process Management module
 - os_create
 - os_terminate
 - Timer module
 - os_get_time

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The Test Suite: Phase 1



- Test1a: Add SLEEP, requires timer multiplexing and interrupt handling, infrastructure for multiple processes.
- Test1b: Interface tests to CREATE_PROCESS
- Test1c: Multiple instances of test1a; demonstration of FCFS scheduling (by using same priorities)
- Test1d: Likewise for different priorities
- Test1e: Suspend/Resume interface test
- Test1f: Suspend/Resume on real scheduling
- Test1g: Change Priority interface test
- Test1h: Change Priority on real scheduling
- Test1k: Misc. error tests