



## Operating Systems

Process Synchronization  
(Ch 2.3, 2.4)

## Too Much Pizza

Person A

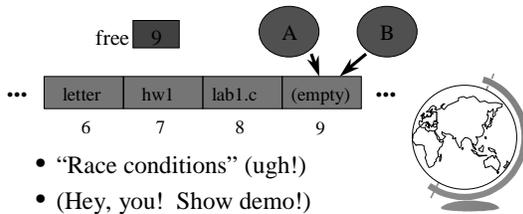
Person B

3:00	Look in fridge. Pizza!	
3:05	Leave for store.	Look in fridge. Pizza!
3:10	Arrive at store.	Leave for store.
3:15	Buy pizza.	Arrive at store.
3:20	Arrive home.	Buy pizza.
3:25	Put away pizza.	Arrive home.
3:30		Put pizza away. Oh no!



## Cooperating Processes

- Consider: print spooler
  - Enter file name in spooler queue
  - Printer daemon checks queue and prints



- “Race conditions” (ugh!)
- (Hey, you! Show demo!)

## Outline

- Need for synchronization
  - why?
- Solutions that require busy waiting
  - what?
- Semaphores
  - what are they?
- Classical problems
  - dining philosophers
  - reader/writers



## Producer Consumer

- Model for cooperating processes
- Producer “produces” and item that consumer “consumes”
- Bounded buffer (shared memory)
 

```
item buffer[MAX]; /* queue */
int counter; /* num items */
```



## Producer

```
item i; /* item produced */
int in; /* put next item */
while (1) {
    produce an item
    while (counter == MAX){/*no-op*/}
    buffer[in] = item;
    in = (in + 1) % MAX;
    counter = counter + 1;
}
```



## Consumer

```
item i; /* item consumed */
int out; /* take next item */
while (1) {
    while (counter == 0) { /*no-op*/}
    item = buffer[out];
    out = (out + 1) % MAX;
    counter = counter - 1;
    consume the item
}
```



## Trouble!

```
P: R1 = counter      {R1 = 5}
P: R1 = R1 + 1      {R1 = 6}
C: R2 = counter      {R2 = 5}
C: R2 = R2 - 1      {R2 = 4}
C: counter = R2      {counter = 4}
P: counter = R1      {counter = 6}
```



## Critical Section

- Mutual Exclusion
  - Only one process inside critical region
- Progress
  - No process outside critical region may block other processes wanting in
- Bounded Waiting
  - No process should have to wait forever (starvation)
- Note, no assumptions about speed!



## First Try: Strict Alternation

```
int turn; /* shared, id of turn */

while(1) {
    while (turn <> my_pid) { /* no-op */}
    /* critical section */
    turn = your_pid
    /* remainder section */
}
```



## Second Try

```
int flag[1]; /* boolean */

while(1) {
    flag[my_pid] = true;
    while (flag[your_pid]) { /* no-op */}
    /* critical section */
    flag[my_pid] = false;
    /* remainder section */
}
```



## Third Try: Peterson's Solution

```
int flag[1]; /* boolean */
int turn;

while(1) {
    flag[my_pid] = true;
    turn = your_pid;
    while (flag[your_pid] &&
           turn==your_pid) { /* noop */}
    /* critical section */
    flag[my_pid] = false;
    /* remainder section */
}
```



## Multiple-Processes

- “Bakery Algorithm”
- Common data structures

```
boolean choosing[n];
int num[n];
```
- Ordering of processes
  - If same number, can decide “winner”



## Multiple-Processes

```
choosing[my_pid] = true;
num[my_pid] = max(num[0],num[1] ...)+1
choosing[my_pid] = false;
for (j=0; j<n; j++) {
    while(choosing[j]) { }
    while(num[j]!=0 &&
        (num[j],j)<(num[my_pid],my_pid)){ }
}
/* critical section */
num[my_pid] = 0;
```



## Synchronization Hardware

- Test-and-Set: returns and modifies atomically

```
int Test_and_Set(int &target) {
    int temp;
    temp = target;
    target = true;
    return temp;
}
```



## Using Test\_and\_Set

```
while(1) {
    while (Test_and_Set(lock)) { }
    /* critical section */
    lock = false;
    /* remainder section */
}
```

- All the solutions so far have required “Busy Waiting” ... what is that?



## Outline

- Need for synchronization (done)
  - why?
- Solutions that require busy waiting (done)
  - what?
- Semaphores
  - what are they?
- Classical problems
  - dining philosophers
  - reader/writers



## Semaphores

- Do not require “busy waiting”
- Semaphore S (shared, often initially =1)
  - integer variable
  - accessed via two (invisibly) atomic operations

```
wait(S): S = S - 1
    if S<0 then block(S)
signal(S): S = S + 1
    if S<=0 then wakeup(S)
```



## Critical Section w/Semaphores

```
semaphore mutex; /* shared */

while(1) {
    wait(mutex);
    /* critical section */
    signal(mutex);
    /* remainder section */
}
```

(Hey, you! Show demo!)



## Semaphore Implementation

- Disable interrupts
  - Why is this not evil?
  - Multi-processors?
- Use correct software solution
- Use special hardware, i.e.- Test-and-Set



## Design Technique: Reducing a Problem to a Special Case

- Simple solution not adequate
  - ex: disabling interrupts
- Problem solution requires special case solution
  - ex: protecting *S* for semaphores
- Simple solution adequate for special case
- Other examples:
  - name servers, on-line help



## Trouble!

```
signal(S)
/* cr */
wait(S)
```

```
wait(S)
/* cr */
wait(S)
```

```
/* cr */
```

```
Process A
wait(S)
wait(Q)
...
```

```
Process B
wait(Q)
wait(S)
...
```



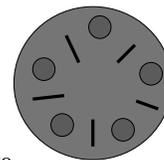
## Classical Synchronization Problems

- Bounded Buffer
- Readers Writers
- Dining Philosophers



## Dining Philosophers

- Philosophers
  - Think
  - Sit
  - Eat
  - Think
- Need 2 chopsticks to eat



## Dining Philosophers

### Philosopher i:

```
while (1) {
    /* think... */
    wait(chopstick[i]);
    wait(chopstick[i+1 % 5]);
    /* eat */
    signal(chopstick[i]);
    signal(chopstick[i+1 % 5]);
}
```

(Other solutions?)



## Other Solutions

- Allow at most N-1 to sit at a time
- Allow to pick up chopsticks only if both are available
- Asymmetric solution (odd L-R, even R-L)



## Readers-Writers

- *Readers* only read the content of object
- *Writers* read and write the object
- Critical region:
  - No processes
  - One or more readers (no writers)
  - One writer (nothing else)
- Solutions favor Reader *or* Writer



## Readers-Writers

### Shared:

```
semaphore mutex, wrt;
int readcount;
```

### Writer:

```
wait(wrt)
/* write stuff */
signal(wrt);
```



## Readers-Writers

### Reader:

```
wait(mutex);
readcount = readcount + 1;
if (readcount==1) wait(wrt);
signal(mutex);
/* read stuff */
wait(mutex);
readcount = readcount - 1;
if (readcount==0) signal(wrt);
signal(mutex);
```



## Monitors

- High-level construct
- Collection of:
  - variables
  - data structures
  - functions
  - Like C++ class
- One process active inside
- “Condition” variable
  - not counters like semaphores



## Monitor Producer-Consumer

```
monitor ProducerConsumer {
    condition full, empty;
    integer count;

    /* function prototypes */
    void enter(item i);
    item remove();
}
void producer();
void consumer();
```



## Monitor Producer-Consumer

```
void producer() {
    item i;
    while (1) {
        /* produce item i */
        ProducerConsumer.enter(i);
    }
}
void consumer() {
    item i;
    while (1) {
        i = ProducerConsumer.remove();
        /* consume item i */
    }
}
```



## Monitor Producer-Consumer

```
void enter (item i) {
    if (count == N) sleep(full);
    /* add item i */
    count = count + 1;
    if (count == 1) then wakeup(empty);
}
item remove () {
    if (count == 0) then wakeup(empty);
    /* remove item into i */
    count = count - 1;
    if (count == N-1) then sleep(full);
    return i;
}
```



## Other Process Synchronization Methods

- Sequencers
- Path Expressions
- Serializers
- ...
- All essentially equivalent in terms of semantics. Can build each other!



## Trouble?

- Monitors and Regions attractive, but ...
  - Not supported by C, C++, Pascal ...
    - + semaphores easy to add
- Monitors, Semaphores, Regions ...
  - require shared memory
  - break on multiple CPU (w/own mem)
  - break distributed systems
- In general, Inter-Process Communication (IPC)
  - Move towards *Message Passing*



## Inter Process Communication

- How does one process communicate with another process? Some of the ways:
  - *shared memory* – read/write to shared region
    - + `shmget()`, `shmctl()` in Unix
    - + Memory mapped files in WinNT/2000
  - *semaphores* - signal notifies waiting process
  - *software interrupts* - process notified asynchronously
  - *pipes* - unidirectional stream communication
  - *message passing* - processes send and receive messages.



## Software Interrupts

- Similar to hardware interrupt.
- Processes interrupt each other (often for system call)
- Asynchronous! Stops execution then restarts
  - ctrl-C
  - child process completes
  - alarm scheduled by the process expires
    - + Unix: SIGALRM from alarm() or setitimer()
  - resource limit exceeded (disk quota, CPU time)
  - programming errors: invalid data, divide by zero



## Software Interrupts

- SendInterrupt(pid, num)
  - type num to process pid,
  - kill() in Unix
  - (NT doesn't allow signals to processes)
- HandleInterrupt(num, handler)
  - type num, use function handler
  - signal() in Unix
  - Use exception handler in WinNT/2000
- Typical handlers:
  - ignore
  - terminate (maybe w/core dump)
  - user-defined
- (Hey, show demos!)



## Unreliable Signals

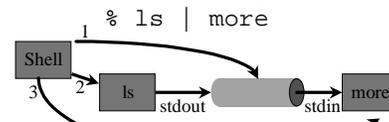
- Before POSIX.1 standard:
 

```
signal(SIGINT, sig_int);
...
sig_int() {
    /* re-establish handler */
    signal(SIGINT, sig_int);
}
```
- Another signal could come before handler re-established!



## Pipes

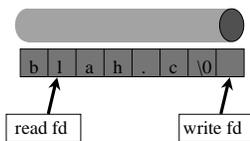
- One process writes, 2nd process reads



- Shell:
  - 1 create a pipe
  - 2 create a process for ls command, setting stdout to write side of pipe
  - 3 create a process for more command, setting stdin to read side of pipe



## The Pipe



- Bounded Buffer
  - shared buffer (Unix 4096K)
  - block writes to full pipe
  - block reads to empty pipe



## The Pipe

- Process inherits file descriptors from parent
  - file descriptor 0 stdin, 1 stdout, 2 stderr
- Process doesn't know (or care!) when reading from keyboard, file, or process or writing to terminal, file, or process
- System calls:
  - read(fd, buffer, nbytes) (scanf() built on top)
  - write(fd, buffer, nbytes) (printf() built on top)
  - pipe(rgfd) creates a pipe
    - + rgfd array of 2 fd. Read from rgfd[0], write to rgfd[1]
- (Hey, show sample code!)



## Message Passing

- Communicate information from one process to another via primitives:  
send(dest, &message)  
receive(source, &message)
- Receiver can specify ANY
- Receiver can block (or not)



## Producer-Consumer

```
void Producer() {
    while (TRUE) {
        /* produce item */
        build_message(&m, item);
        send(consumer, &m);
        receive(producer, &m); /* wait for ack */
    }
}

void Consumer {
    while(1) {
        receive(producer, &m);
        extract_item(&m, &item);
        send(producer, &m); /* ack */
        /* consume item */
    }
}
```



## Consumer Mailbox

```
void Consumer {
    for (i=0; i<N; i++)
        send(producer, &m); /* N empties */
    while(1) {
        receive(producer, &m);
        extract_item(&m, &item);
        send(producer, &m); /* ack */
        /* consume item */
    }
}
```



## New Troubles with Messages?



## New Troubles with Message Passing

- Scrambled messages (*checksum*)
- Lost messages (*acknowledgements*)
- Lost acknowledgements (*sequence no.*)
- Process unreachable (down, terminates)
- Naming
- Authentication
- Performance (from copying, message building)
- (Take cs4513!)

