

Notes on Project 5

December 8, 2012

About “recursively memoize oper,” and its type. In the problem about maximum nonadjacent subsequences, you will first construct a “knowledge extension operator” called `mnas_oper`.

This operator depends on the sequence s that it is supposed to work on, and it builds an operator f (meaning, a *function* f) that will extend knowledge about the sums of maximum nonadjacent subsequences of s . The result f is a function that takes an index i and a “current knowledge” operator g . Then $f(i, g)$ will return the maximum sum for a nonadjacent subsequence of s that uses at most the first i positions of s . It should give the right answers up to some maximum j *assuming* that g gives the right answers up to maximum $j - 1$.

So $f(i, g)$ *extends* the knowledge contained in g .

Notice that the “type” of g is $\text{Int} \rightarrow \text{Int}$. That means, given an integer argument i , $g(i)$ is an integer, namely the sum of the maximum nonadjacent subsequence of s that uses at most the first i entries from s . (Assume that s is a sequence of integers, so that the sum is an integer too.) We can write this:

$$g: \text{Int} \rightarrow \text{Int}$$

That means that the type of f will be:

$$f: \text{Int} \times (\text{Int} \rightarrow \text{Int}) \rightarrow \text{Int}.$$

This says that if f is given an integer i and an argument g with type $g: \text{Int} \rightarrow \text{Int}$, then $f(i, g)$ should be an integer.

So what is the type of `mnas_oper`? Well, it is a function that takes as argument an integer array, and it returns f . Let us write the type of an integer array as `Int array`. Since we already know the type of f , we can write the type of `mnas_oper` as:

$$\text{mnas_oper}: \text{Int array} \rightarrow (\text{Int} \times (\text{Int} \rightarrow \text{Int}) \rightarrow \text{Int}).$$

We are now ready to figure out the type of `recursively_memoize_oper`. It can take as argument a function like f , which is called `o` in the `max_nonadj.lua` file. We know that f has type $f: \text{Int} \times (\text{Int} \rightarrow \text{Int}) \rightarrow \text{Int}$. It returns a function `fn` which takes an argument that it gives as first argument to f , and `fn` returns the same answer that f returned. That means that the argument and return value of `fn` are the same as the first argument and the return value of f . So $\text{fn}: \text{Int} \rightarrow \text{Int}$.

Since `recursively_memoize_oper` takes an argument of type $f: \text{Int} \times (\text{Int} \rightarrow \text{Int}) \rightarrow \text{Int}$ and returns a function of type $\text{Int} \rightarrow \text{Int}$, we have:

```
recursively_memoize_oper: (Int × (Int → Int) → Int) → (Int → Int).
```

We can use this to explain how `mnas_max` works. Its definition says:

```
function mnas_max(s)
  return recursively_memoize_oper(mnas_oper(s))(#s)
end
```

It takes an argument s which is an integer array, i.e., $s: \text{Int array}$. Thus,

$$\text{mnas_oper}(s): \text{Int} \times (\text{Int} \rightarrow \text{Int}) \rightarrow \text{Int}$$

since this is the type of value that `mnas_oper` returns. Thus:

$$\text{recursively_memoize_oper}(\text{mnas_oper}(s)): \text{Int} \rightarrow \text{Int}.$$

Now $\#s$ is an integer, namely the length of s . So:

$$\text{recursively_memoize_oper}(\text{mnas_oper}(s))(\#s): \text{Int}.$$

This is exactly what we want: It means that `mnas_max` returns an integer, given any sequence (array) of integers.

Curiously, `recursively_memoize_oper` can also be applied to arguments of other types. This is the relevant story for our problem, however.

Knowledge extension operators and recurrences. The project write-up and the starter code file both use the word “recurrence.” In both of these, they mean what we have been calling a knowledge extension operator. “Recurrence” is not a crazy thing to call a knowledge extension operator, since it does some work but does “recur” to its function argument g as needed.

However, I should emphasize that this has nothing to do with recurrences like the ones that the Master Theorem talks about, such as $T(n) = aT(n/b) + f(n)$.

Bellman-Ford and Finding the Shortest Paths. Suppose that you write your Bellman-Ford implementation, and call it on a graph g and starting node s . The code is supposed to give you back two tables. One is the table d whose entry for node t is the length of the shortest path $s \rightarrow^* t$. If the entry in d is nil, that means that there was no path from s to t ¹.

The other is the table π , i.e. pi. $\pi[n]$ is the parent, i.e. predecessor, of n along some shortest path from s . So some shortest path is of the form $s \rightarrow^* \pi[t] \rightarrow t$; its last arc takes us from $\pi[t]$ to t . We can use π again to find out the earlier part of this path, as in:

$$s \rightarrow^* \pi[\pi[t]] \rightarrow \pi[t] \rightarrow t.$$

You can keep using this idea backward to get the whole path between s and t worked out.

¹I'm using $s \rightarrow^* t$ to mean that we're allowed to use \rightarrow zero or more times repeatedly to get to t .