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# IMGD 3000 - Technical Game Development I: Intro to AI in Games, Part 2

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# Motivation

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- Particle systems can add nice realism to an environment
  - Fairly simplistic "rules"
  - No collision detection
  
- NPCs can be implemented in a similar fashion
  - Complex behavior  $\Rightarrow$  more-complex rules
  - Combination of "standard" and special purpose algorithms

# Sample Uses of AI in Games (recap)

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- ❑ Bad guys guarding something
- ❑ Bad guys looking for you
- ❑ Bad guys trying to beat you to something
- ❑ Bad guys trying to beat you (literally)
- ❑ Good guys working with you
- ❑ Other people just minding their own business

# Flocks, Herds, and Schools

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- A **flock** consists of a group of discrete **boids** moving in a visually complex fashion.
- There appears to be some central control, but evidence indicates that the motion is just the aggregate result of individual object motions.
- Problem
  - How do we simulate the motions of a flock in games?

# Behavioral Systems

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- ❑ Special instance of particle systems
- ❑ **Flock** is a group of objects that exhibit the general class of polarized (aligned), non-colliding, aggregate motion.
- ❑ **Boid** is a simulated bird-like object, *i.e.*, it exhibits this type of behavior. It can be a fish, dinosaur, *etc.*
- ❑ Allow each object to determine its own behavior

# General Approach

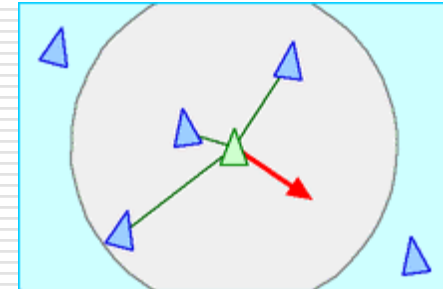
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- Each boid maintains
  - An internal state
  - A set of behaviors
  
- Fits very nicely into a C++ (Java, etc.) **class**
  - Each boid is an instance of this class
  
- Three main behavioral rules
  - Separation
  - Alignment
  - Cohesion

# Three Rules

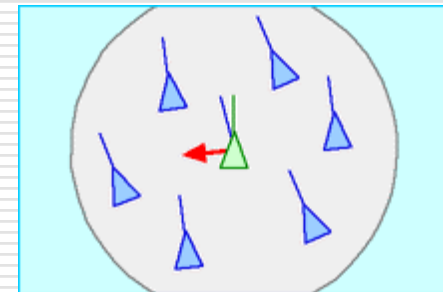
## □ Separation

- Steer to avoid crowding local flockmates



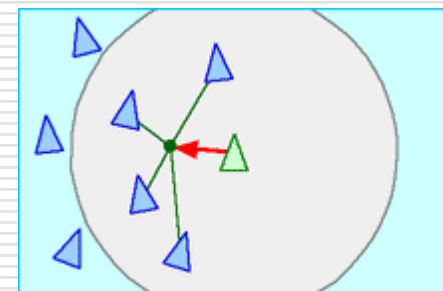
## □ Alignment

- Steer towards the average heading of local flockmates



## □ Cohesion

- Steer to move toward the average position of flockmates



# Three Rules, Restated

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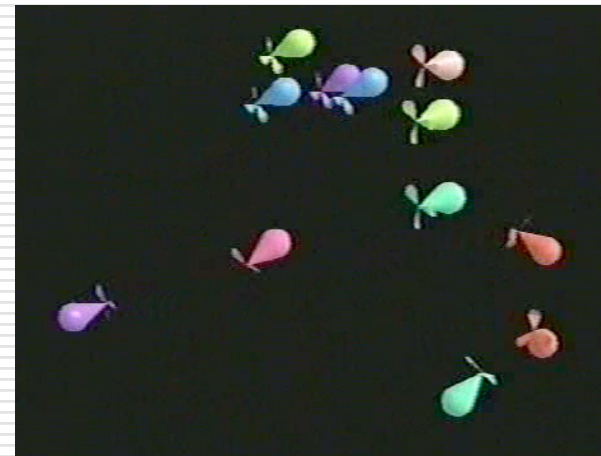
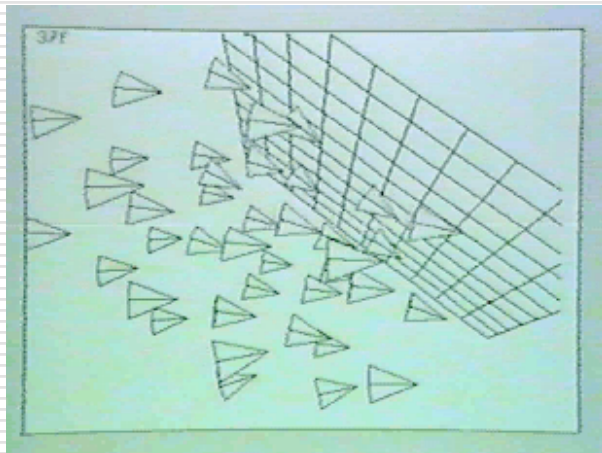
- ❑ Avoid collisions with neighbors and obstacles
- ❑ Attempt to match velocity (speed and direction) of neighbors
- ❑ Attempt to stay close to neighbors
- ❑ These are not orthogonal
  - Collision avoidance helps establish a minimum distance to neighbors
  - Velocity matching maintains it



# Boid Brain

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- Each boid has access to whole scene
- Each one only considers flockmates in neighborhood
  - Typically defined using a radius
  - Think of fish in murky water, birds in fog



# More Rules?

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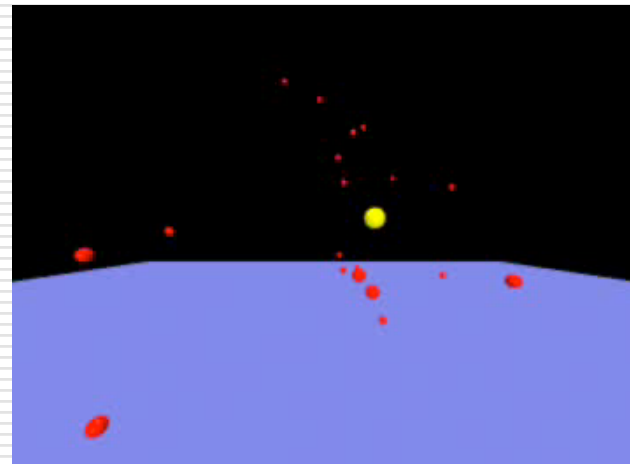
- What else could you do with this?



# More Rules?

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- Seek and flee
  - Food vs. Food?
- Pursue and Evade
- Wander
- Arrival
- Containment
- Wall following
- Path following
- Leader following



# Problems with Behavioral Techniques

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- Trade control for automation
  - Difficult to get **exact** desired effect
- Solution: Follow the leader
  - How to define leader
- Solution: Use only for background
  - Use something else for foreground characters
- Need to consider **every** boid
  - $O(n^2)$  complexity!
  - How can we fix this?

# Behavioral Systems: Examples

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- ❑ Bats and penguins in *Batman Returns*
- ❑ All battle scenes in *Lord of the Rings*
- ❑ Most battle scenes in *Star Wars*
  
- ❑ Add some stochastic behaviors in order to deter uniformity

# References

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- ❑ C. W. Reynolds, "Flocks, Herds, and Schools: A Distributed Behavioral Model", *Computer Graphics*, vol. 21, no. 4, pp 25-34, 1987.
- ❑ <http://www.red3d.com/cwr/boids/>
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