

WPI

CS 4732:
Computer Animation

Key Frames & Shape Changes

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Key Framing

- Key frames define important poses during an animation
 - Specified by animator
 - Computer fills in `tweens

- How should the computer interpolate as desired by the animator?
 - For curves?
 - For shapes?

Key Framing (cont.)

- Two main problems
 - Correspondence
 - Interpolation method

- For curves
 - One could require the curves to have same number of control points
 - Interpolate control points, regenerate curve

Key Framing (cont.)

- For shapes
 - One could require the shapes to have the same topology
 - Apply physics-based simulation
 - Or use key framing for more control
- Shape animation used a lot for facial animations

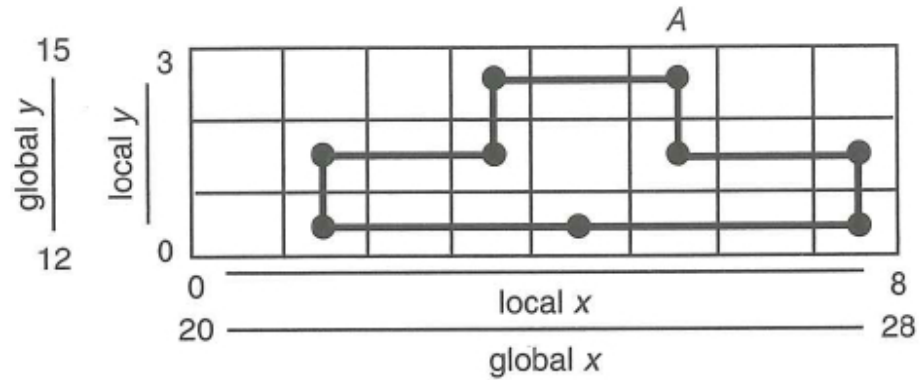
Shape Animation

- What does it mean for shapes to be different?
 - Uniform scaling?
 - Is a square the same as a rectangle?
- Pulling/pushing vertices
 - Can be tedious/time consuming
 - Can displace neighbors by some influence function

2D Shape Deformation

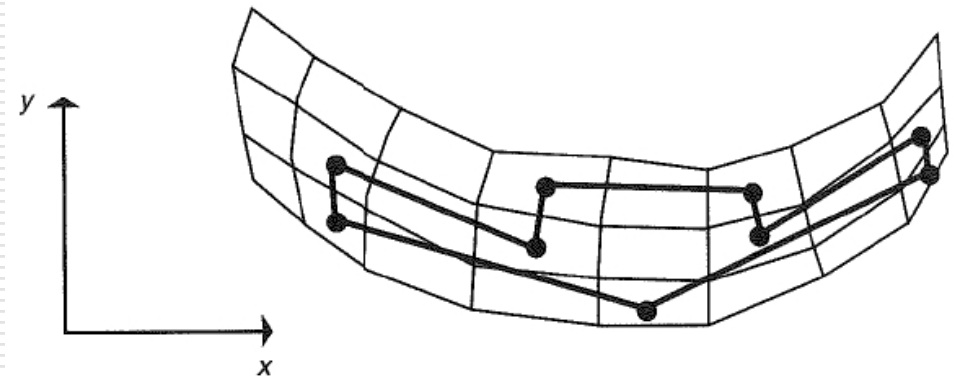
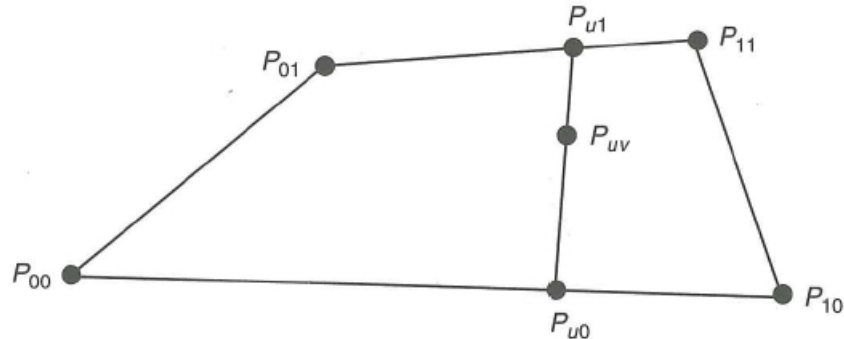
- One approach to deformation is to
 - Embed the vertices of the shape within a regular grid
 - Note the relative locations of the vertices to the grid intersections
 - Apply deformations to the grid
 - Recalculate the deformed vertex positions using bilinear interpolation
- Allows for more-efficient recalculation
- Makes it easier for the animator to specify deformation

2D Shape Deformation (cont.)



(1-u)

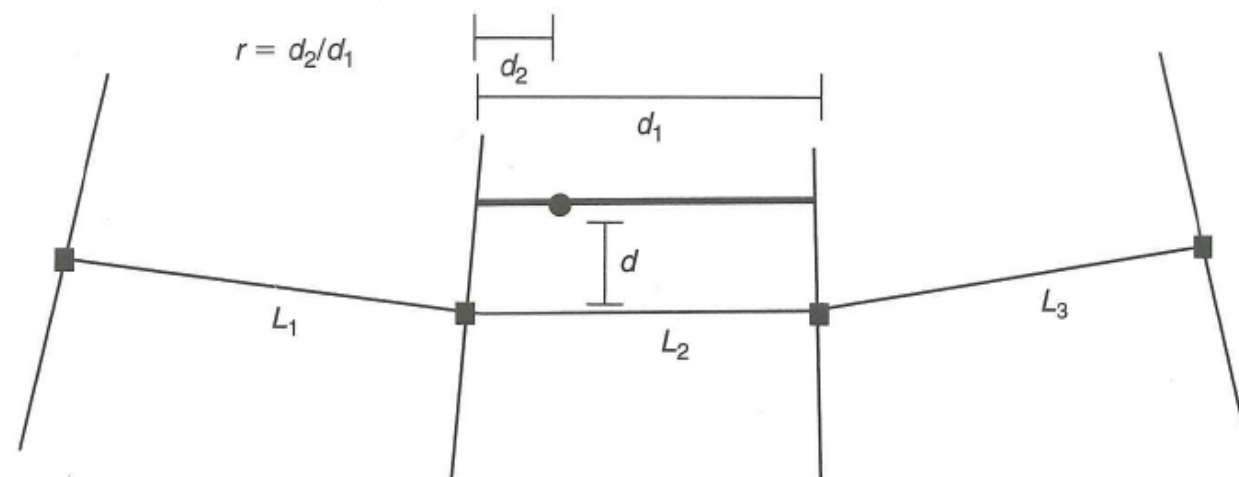
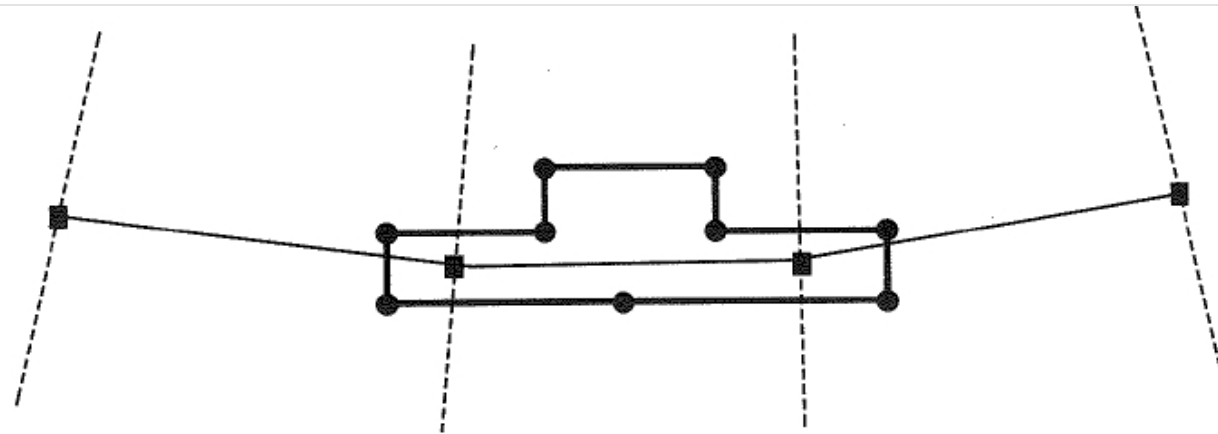
$$\begin{aligned}
 P_{u0} &= (1-u)P_{00} + uP_{10} \\
 P_{u1} &= (1-u)P_{01} + uP_{11} \\
 P_{uv} &= (1-v)P_{u0} + vP_{u1} \\
 &= (1-u)(1-v)P_{00} + (1-u)vP_{01} + u(1-v)P_{10} + uvP_{11}
 \end{aligned}$$



Polyline Deformation

- Similar to grid deformation
- Calculate the relative position of the vertices to a polyline
- Good for snakes, tentacles, etc.

Polyline Deformation (cont.)



Free Form Deformation (FFD)

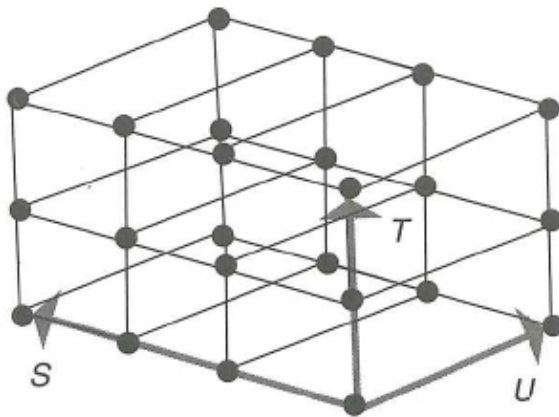
- Extend 2D technique to 3D
 - Use cubic (or other) interpolation instead of bilinear
 - Embed the shape within a grid defined by three axes
 - Record the locations of the vertices within the grid
 - Deform the grid
 - Calculate the new positions

FFD (cont.)

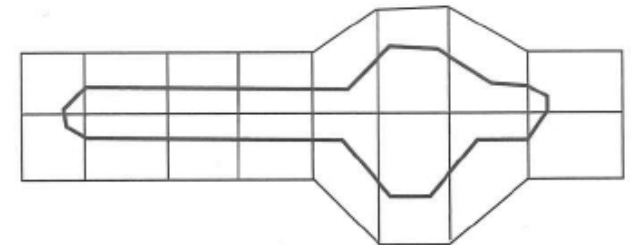
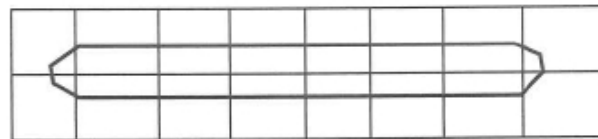
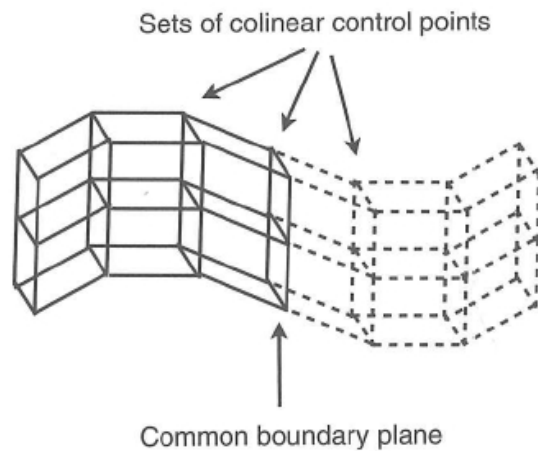
- Continuity can be insured in the same way as in 2D
- FFDs can be applied in sequence or hierarchically as well.
- Animation can be carried out by
 - Moving the control points over time
 - Moving the shape through the distorted space
 - Can define a “tool” and deform shapes with it

FFD Animation

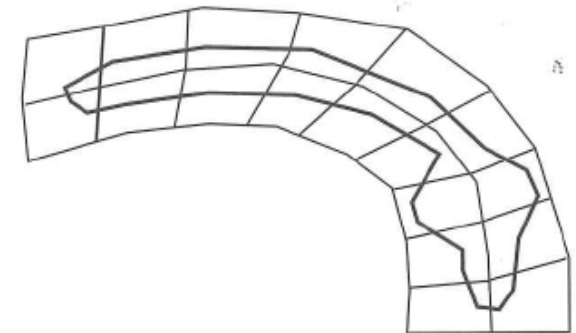
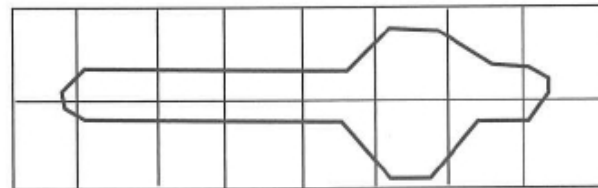
- Control points can be deformed based on
 - Physical simulation, e.g., a ball hitting a sponge
 - Key framing
 - Facial simulation (e.g., bones, muscles, etc.)
 - Any function you can think of!



FFD Animation (cont.)



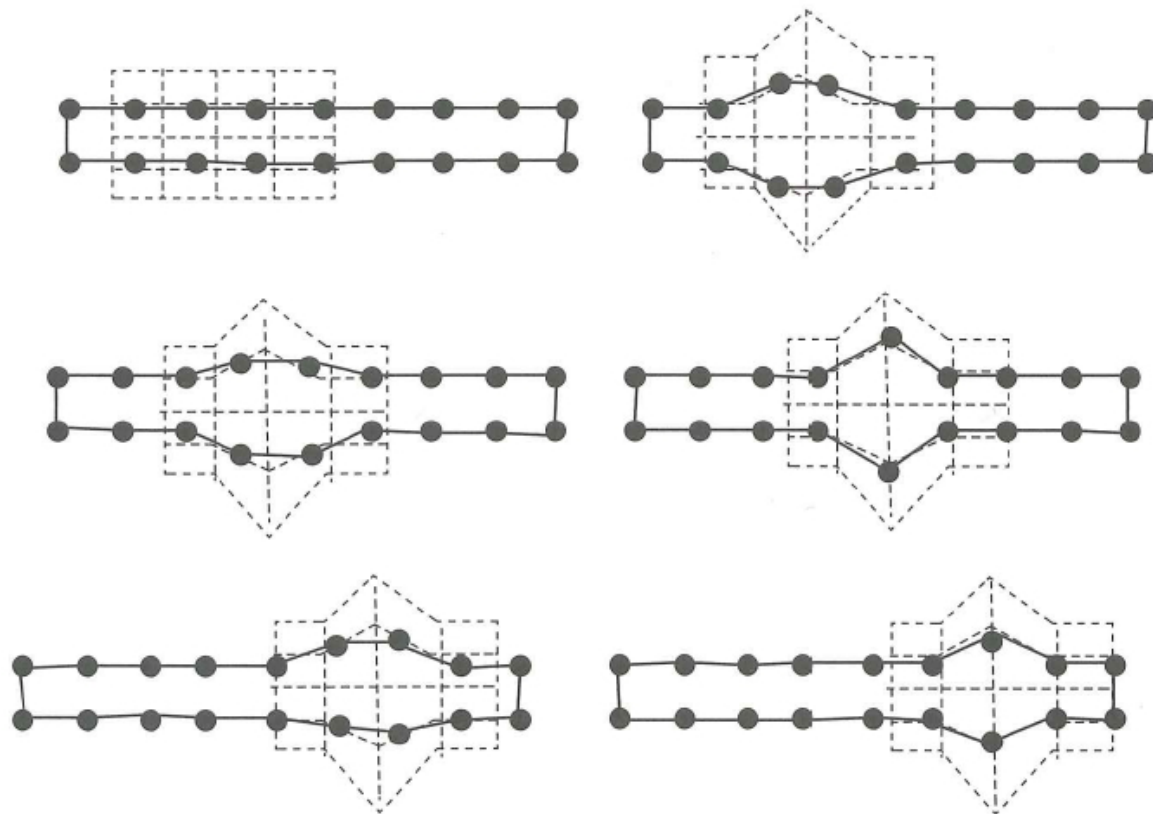
Bulging



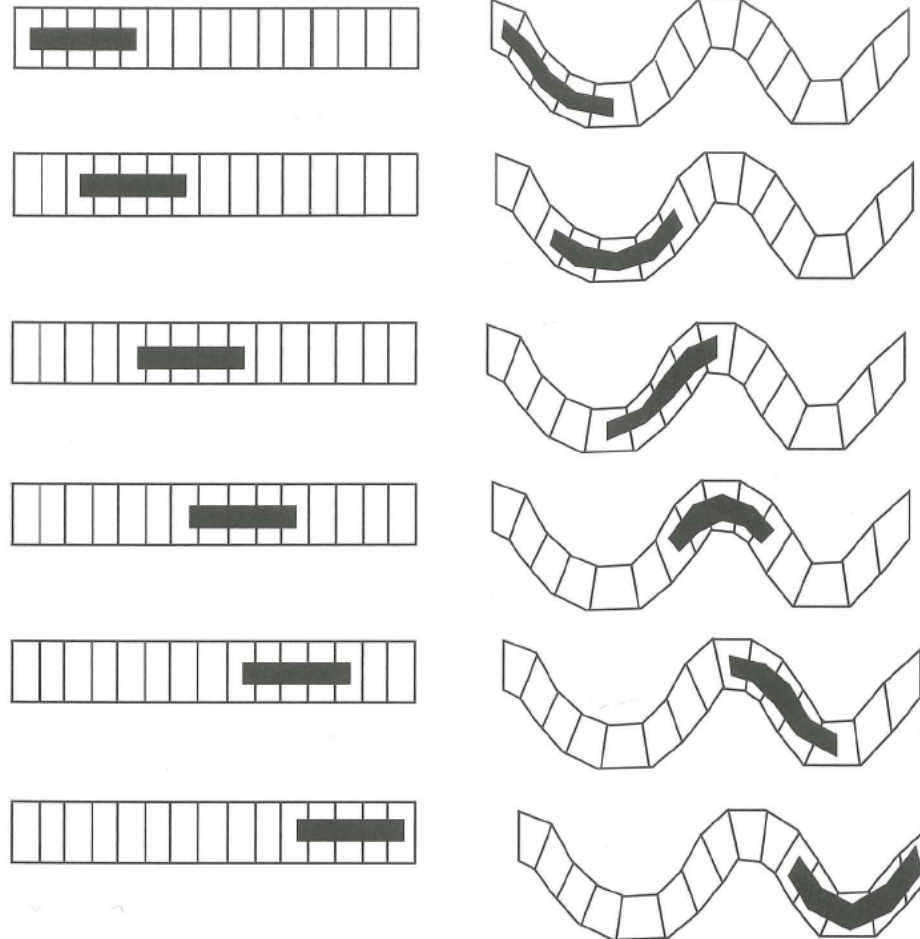
Bending

FFD Animation (cont.)

□ “Tools” for distortion



FFD Animation (cont.)



Object traversing the logical FFD coordinate space

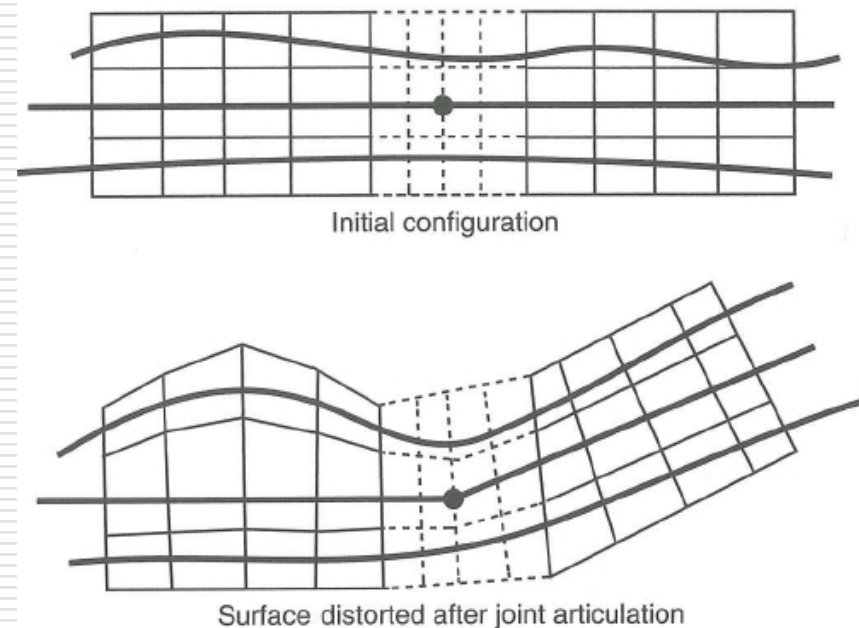
Object traversing the distorted space

Bones, Joints & Muscles

- How does all this relate to modern tools for animating figures?
- Bones as reference objects
 - Link length, joints, etc.
 - Bone movement constrained by muscles, etc.
- Skin defined in space as a spring-mass model
- Deformation is a combination of FFD & springs

Bones, Joints & Muscles (cont.)

- Bones move
- FFD lattice “anchored” to bone
- Spring-mass model moves FFD control points



3D Morphing

- Smoothly change one 3D shape into another
- Two main approaches
 - Volume based
 - Surface based
- Which one to use depends on properties of the shapes, and the desired effect

Volume-Based 3D Morphing

- ❑ Represent each shape as a volume
- ❑ Morph one volume to another
- ❑ Can be expensive
- ❑ Does not take into account properties that might be important for animation
- ❑ Not used as much as surface-based morphing

Terms Used in Surface-Based

- Object
 - Entity that has 3D surface geometry
- Shape
 - Set of points in object space that make up an object's surface
- Model
 - Any complete description of the shape of an object
- One 3D **object** may have several **models** that describe its **shape**

More Terms

□ Topology

- The number of holes an object has, and the number of bodies in the object
- The vertex/edge/face connectivity of a polyhedron

□ Genus

- How many holes an object has
- Sphere is *genus 0*
- Doughnut is *genus 1*

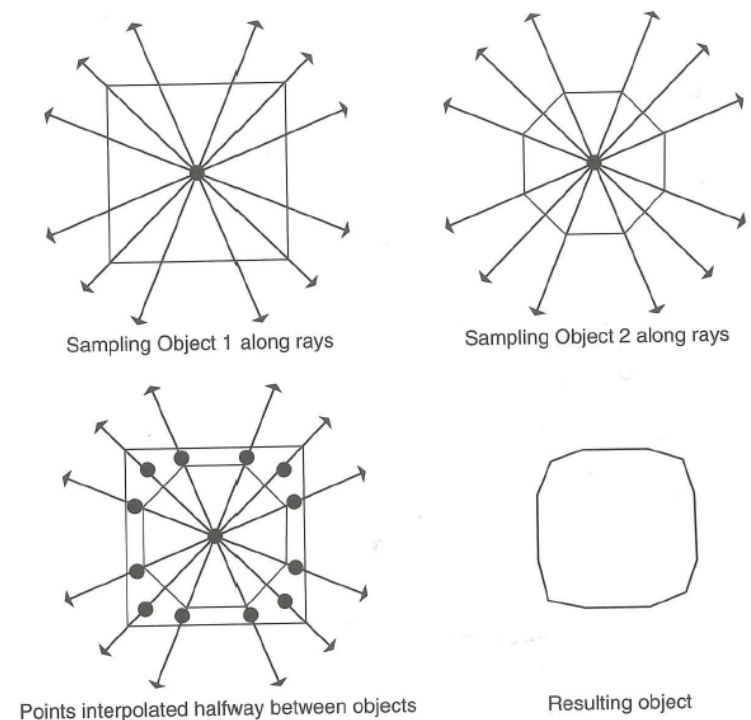
Surface-Based 3D Morphing

- Two main problems to solve
 - Vertex correspondence problem
 - Finding a mapping for each vertex on one shape to a vertex on the other
 - Interpolation problem
 - Creating a set of intermediate objects that move from one to the other

- Shapes typically have different surface topologies
 - Connectivity of vertices
 - Some objects may have “holes” in them

Surface-Based 3D Morphing (cont.)

- If the topologies match
 - Just interpolate 3D vertex positions over time
- If star-shaped object
 - Find distance to point in *kernel*, and interpolate



Mapping Onto a Sphere

- Several approaches
 - Project all vertices, edges, etc. onto the surface of a sphere
 - Then take the union of the vertices/edges for both objects
 - Then project back
 - Then perform vertex-by-vertex interpolation
- Can lead to an explosion of new edges
- Does not attempt to match edges
- Other approaches (in book) try this

2D Morphing

- Usually an image-based post-process
- Transform a *source image* into a *destination image*
- Main task
 - Identify corresponding features of the two images.
- Two main approaches
 - User-defined coordinate grid
 - Feature lines

User-defined Coordinate Grid

- Image-based approach
- User defines a curvilinear grid, where main features lie within corresponding grid squares
- Intermediate images are generated by
 - Interpolating the grid points
 - Linear, or higher-order using adjacent key frames
 - Stretching/compressing pixels from the source to the intermediate, and from the destination to the intermediate
- The two images are cross dissolved

User-defined Coordinate Grid (cont.)

□ Grids

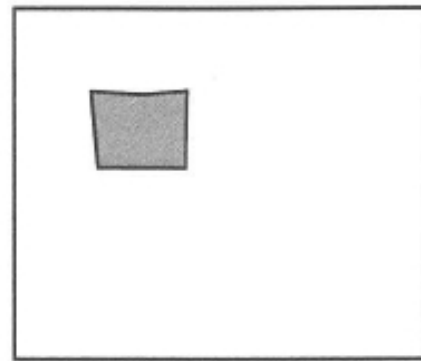


Image A

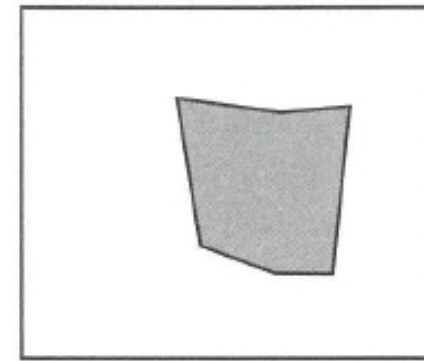


Image B

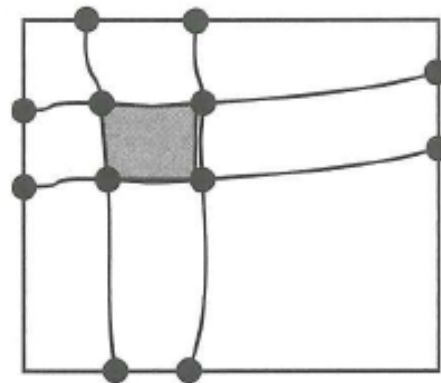


Image A with grid points and curves defined

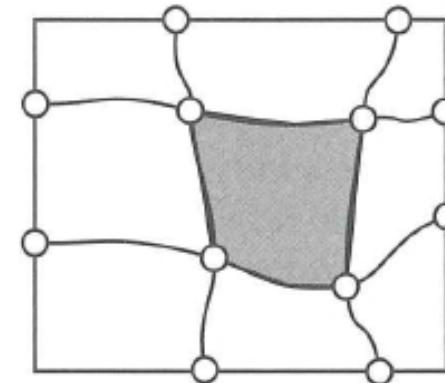


Image B with grid points and curves defined

Feature-based Morphing

- User specifies pairs of lines on source and destination images
 - Lines should cover some features
- A mapping for each pixel to each feature line in each image is established
- Intermediate line locations are then determined using interpolation
 - Either endpoints, or center+orientation
- A weighted average is used to generate the intermediate images
- Cross-dissolve is again used

Some Examples

- <http://davis.wpi.edu/~matt/courses/morph/>
- <http://morph.cs.st-andrews.ac.uk/fof/index.html>
- <http://www.fantamorph.com/index.html>